Introduction to Computer Vision

Michael J. Black Sept 2009

Lecture 7: Linear filtering, smoothing and pyramids

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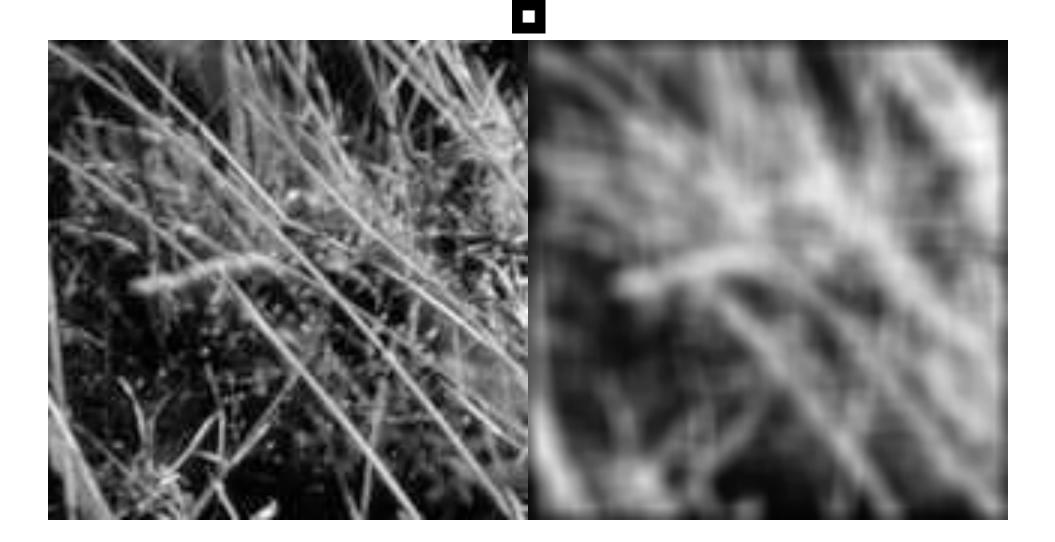
Goals

- Linear filtering (cont.)
 - Foundations for asng1.
 - Problem 1, image pyramids
 - Problem 2, image derivatives
- Friday: correlation, features – Problems 3&4

Homework

- Assignment 1
 - Problems 1&2 due Monday Sept 28
 - Problems 3&4 due Oct 5.
 - Grad credit do extra credit questions

Example: Smoothing by Averaging

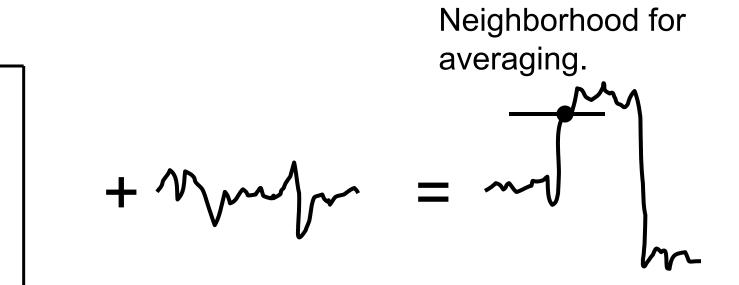


Linear systems

Basic properties. If T[.] is a linear operator, and a and b are scalars, then:

- homogeneity T[a X] = a T[X]
- Additivity $T[X_1+X_2] = T[X_1]+T[X_2]$
- superposition $T[aX_1+bX_2] = aT[X_1]+bT[X_2]$
- − Linear system ⇔ superposition
- Examples:
 - matrix operations (additions, multiplication)
 - convolutions

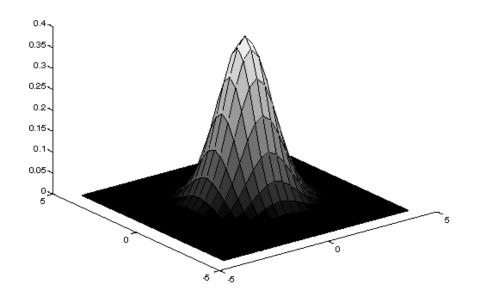
Smoothing as Inference About the Signal



Nearby points tell more about the signal than distant ones.

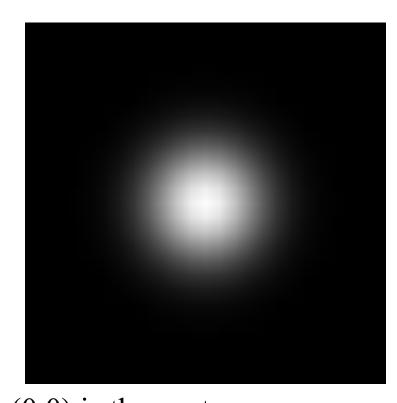
Gaussian Averaging

- Rotationally symmetric.
- Weights nearby pixels more than distant ones.
 - This makes sense as probabilistic inference.



• A Gaussian gives a good model of a fuzzy blob

An Isotropic Gaussian



• The picture shows a smoothing kernel proportional to

$$g(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(x^2 + y^2)}{2\sigma^2}\right)$$

(which is a reasonable model of a circularly symmetric fuzzy blob)

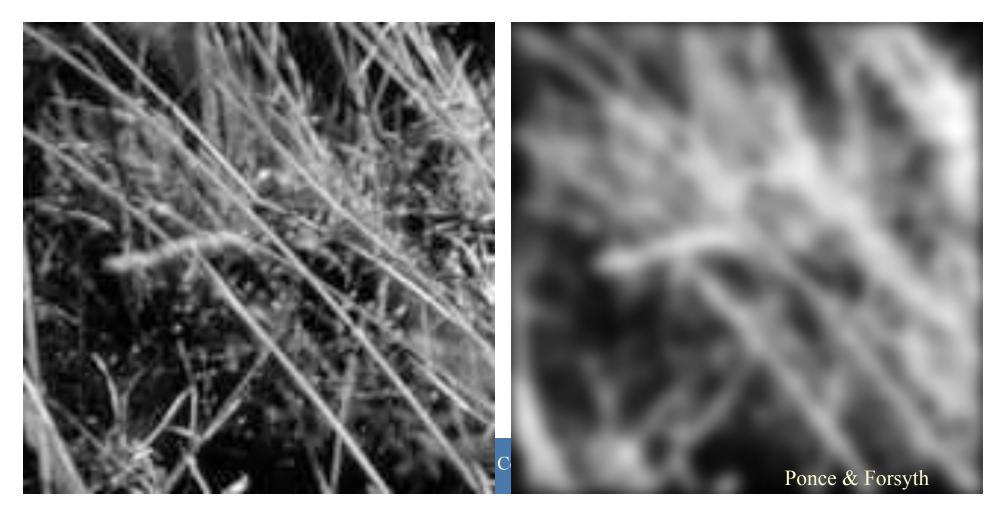
Ponce & Forsyth

(0,0) is the center

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Smoothing with a Gaussian





Homework

g=fspecial('gaussian',3,1)

B = imfilter(A,g,'symmetric','conv')
B = imfilter(A,g,'symmetric','corr')
% in the case of a symmetric filter, these are the same

Separable Gaussian

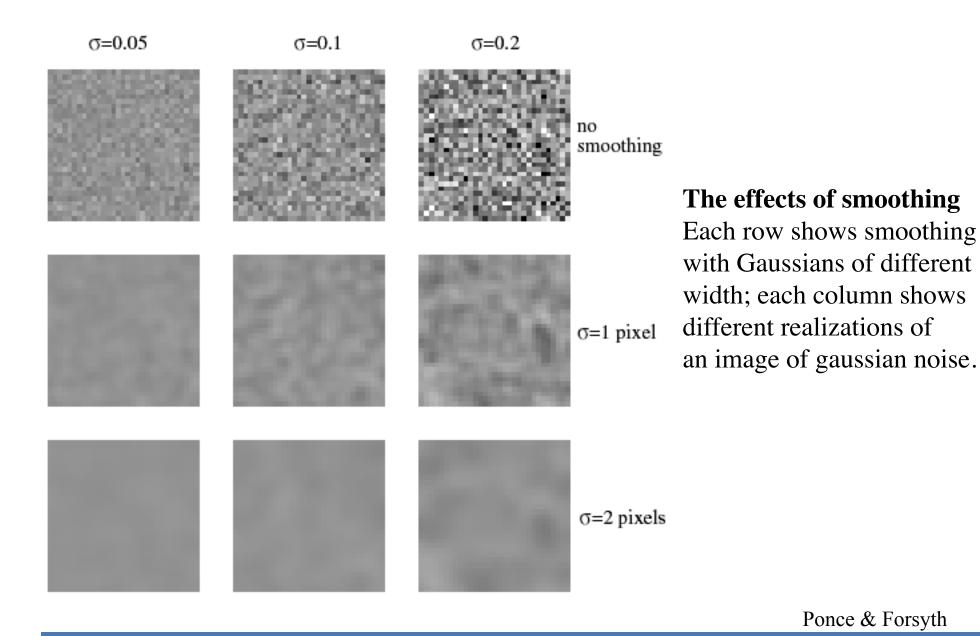
$$g(x) = \frac{1}{\sqrt{2\pi\sigma}} \exp(-x^2/(2\sigma^2)) = G_x$$

$$g(y) = \frac{1}{\sqrt{2\pi\sigma}} \exp(-y^2/(2\sigma^2)) = G_y$$

Product?

$$g(x, y) = \frac{1}{2\pi\sigma^2} \exp(-(x^2 + y^2)/(2\sigma^2))$$

$$G_x \otimes (G_y \otimes I) = (G_x \otimes G_y) \otimes I = G_{xy} \otimes I$$



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Multi-Resolution Image Representation

- Gaussian pyramids
- Laplacian Pyramids



Source: Irani

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Motivation for studying scale.



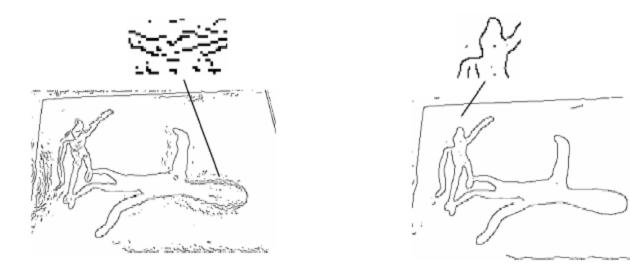
ELDER AND ZUCKER: LOCAL SCALE CONTROL FOR EDGE DETECTION AND BLUR ESTIMATION

IEEE TRANSACTIONS ON PATTERN ANALYSIS AND MACHINE INTELLIGENCE, VOL. 20, NO. 7, JULY 1998

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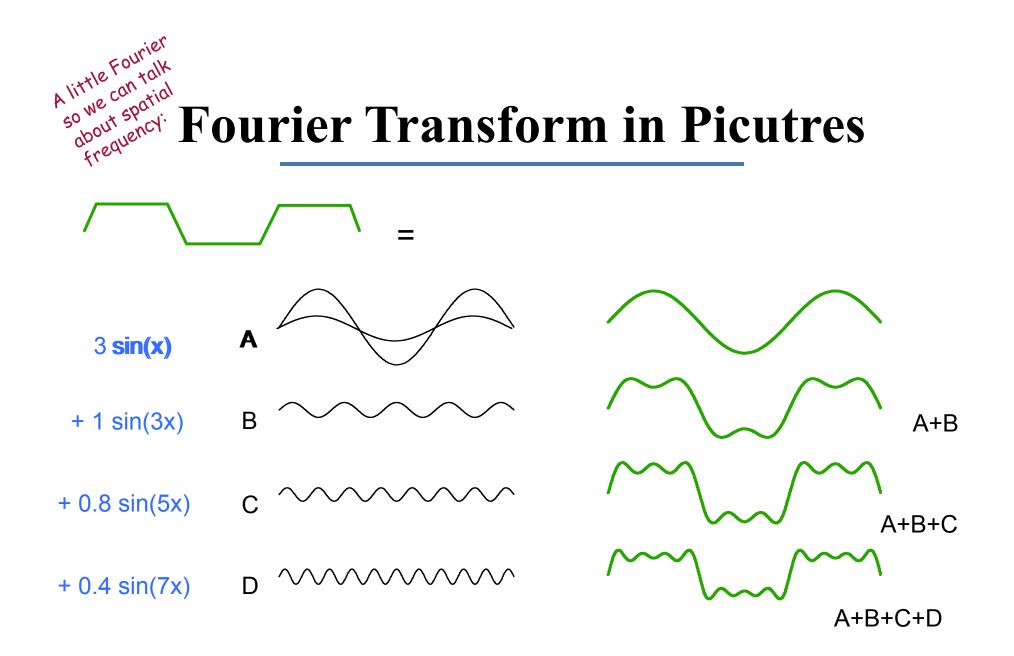
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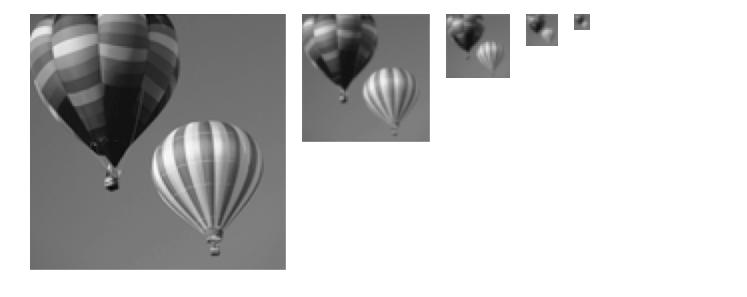
Hwk 1 Prob 1, hint

- Use structures and cell arrays
- Write a nice display function
- Don't represent pyramid as an image and then filter this image – it will produce artifacts at the boundaries between the levels.



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Gaussian Pyramid



High resolution — Low resolution

Source: Irani

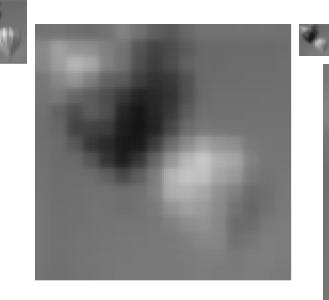
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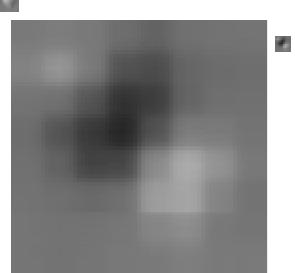








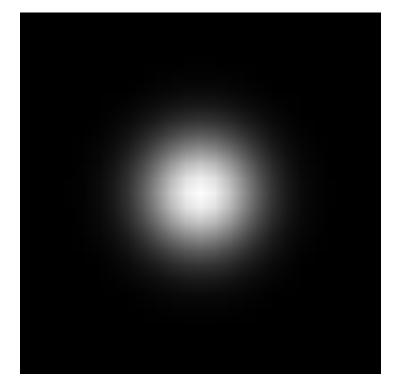




Source: Irani

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An Isotropic Gaussian



• The picture shows a smoothing kernel proportional to

$$g(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(x^2 + y^2)}{2\sigma^2}\right)$$

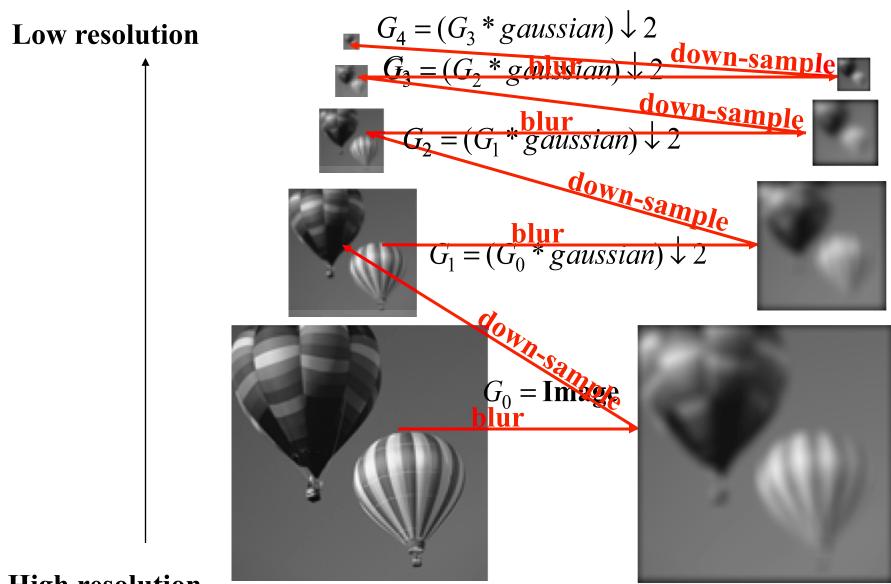
(0,0) in center

To smooth image, convolve with this filter.

Ponce & Forsyth

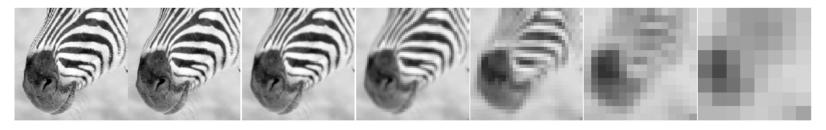
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The Gaussian Pyramid



High resolution

Source: Irani



512 256 128 64 32 16

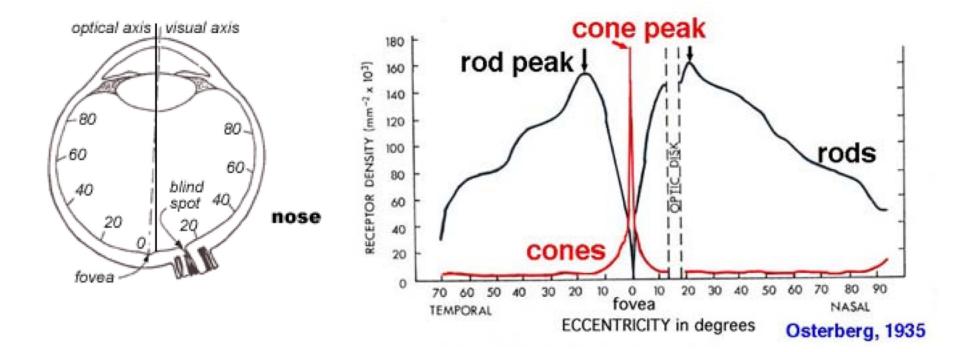


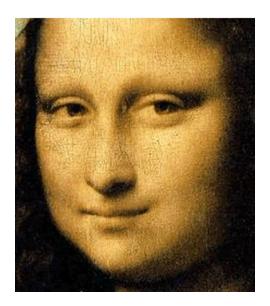
A bar in the big images is a hair on the zebra's nose; in smaller images, a stripe; in the smallest, the animal's nose

8

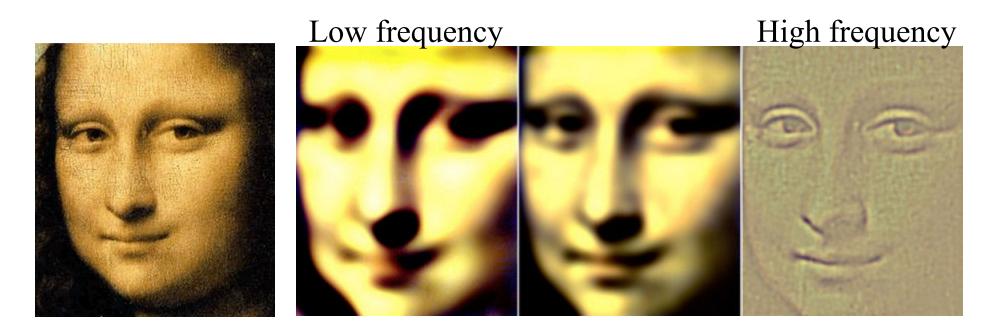
Source: Ponce&Forsyth

Foveal/peripheral vision



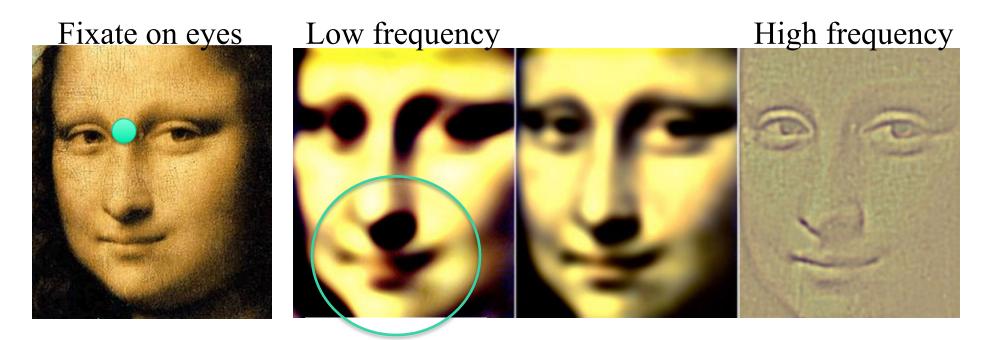


Why is her smile so mysterious? Why is this picture so fascinating? What could spatial frequency have to do with it?



Margaret Livingstone

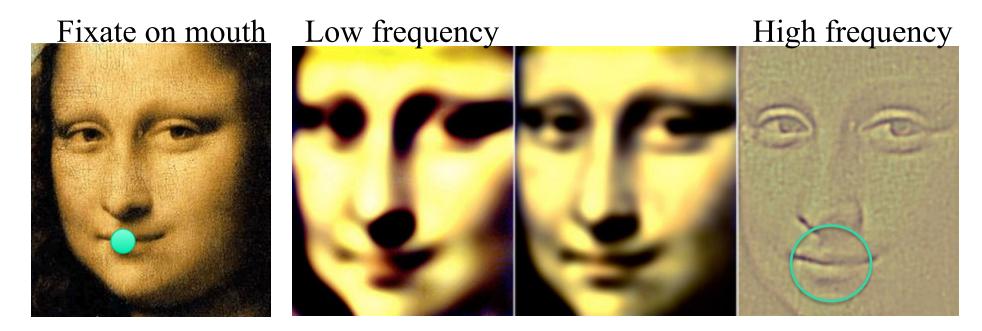
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Mouth seen in low resolution periphery

Margaret Livingstone

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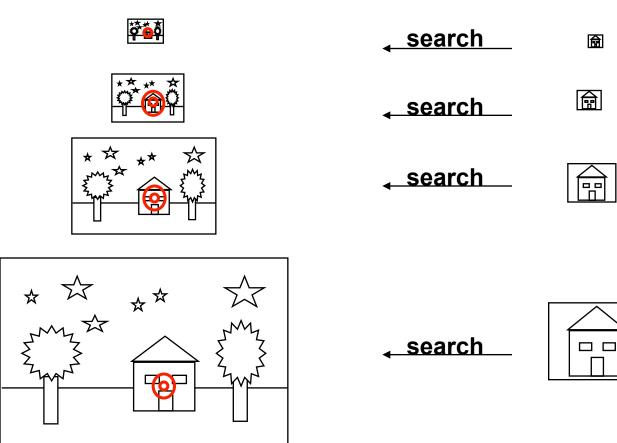


Mouth seen in high resolution fovea

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Motivation: Search



Irani & Basri

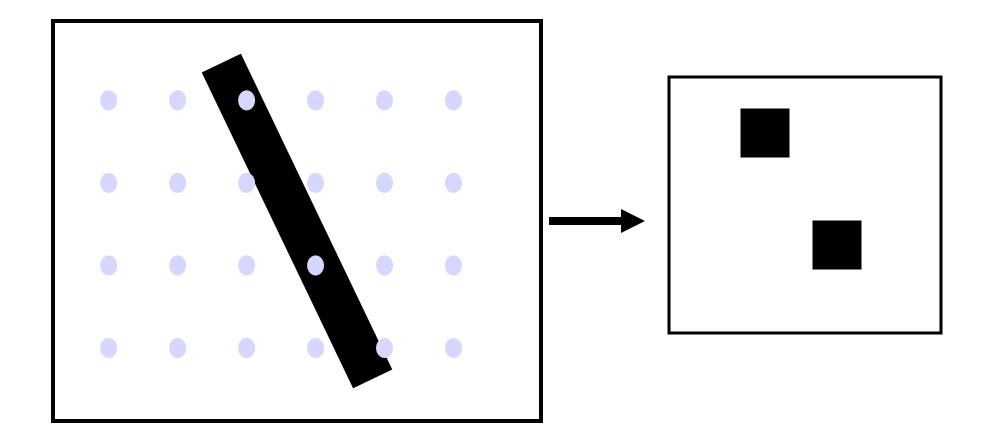
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Sub-sampling

Why smooth before sub-sampling?

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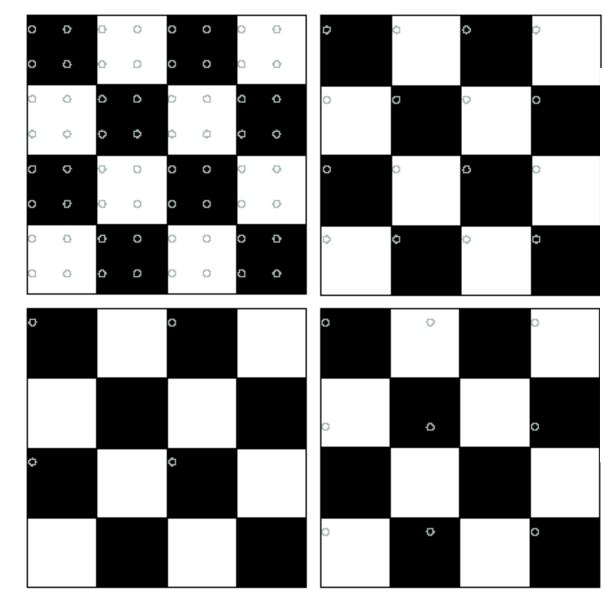
Subsampling



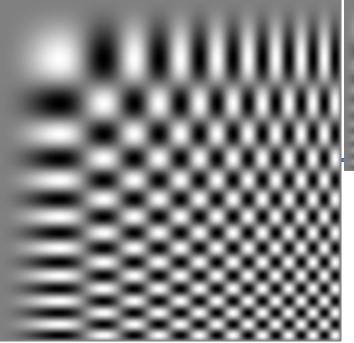
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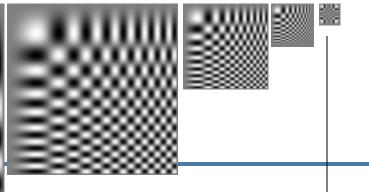
Aliasing

- Can't shrink an image by taking every second pixel
- If we do, characteristic errors appear
 - Common phenomenon
 - Wagon wheels rolling the wrong way in movies
 - Checkerboards misrepresented in ray tracing

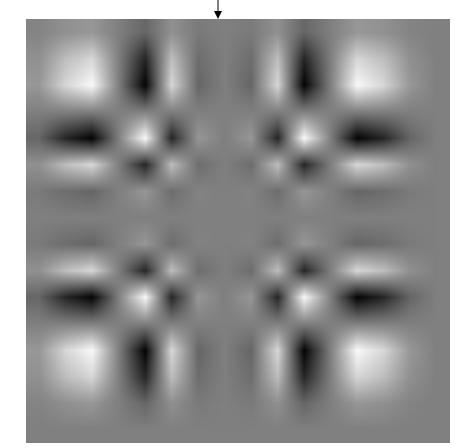


Resample the checkerboard by taking one sample at each circle. In the case of the top left board, new representation is reasonable. Top right also yields a reasonable representation. Bottom left is all black (dubious) and bottom right has checks that are too big.





Constructing a pyramid by taking every second pixel leads to layers that badly misrepresent the top layer



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