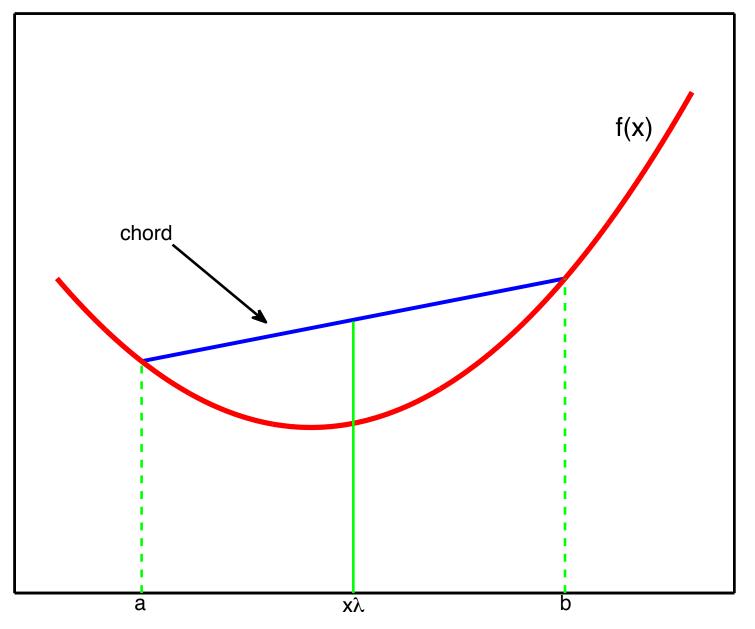
Applied Bayesian Nonparametrics

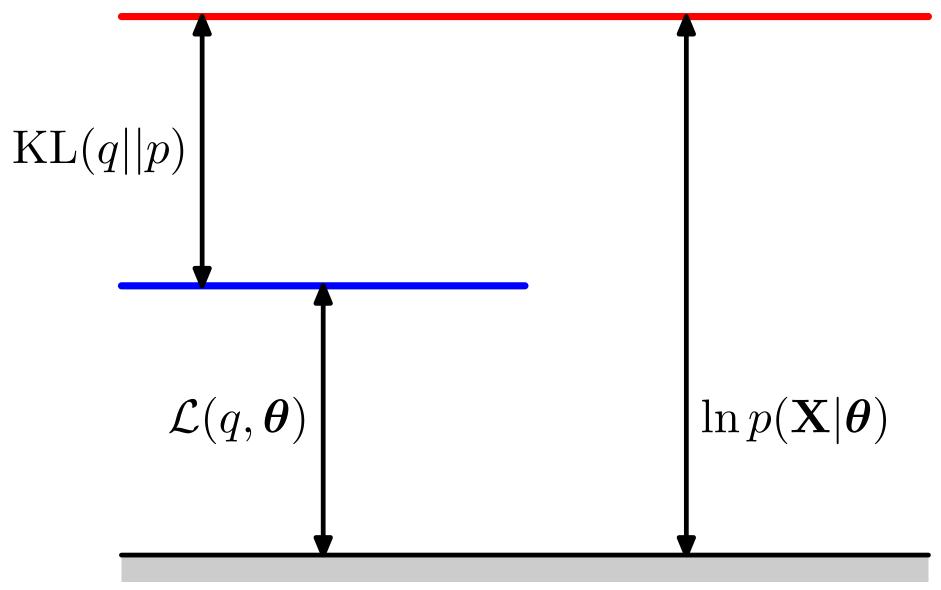
Special Topics in Machine Learning Brown University CSCI 2950-P, Fall 2011

October 11: Variational Methods

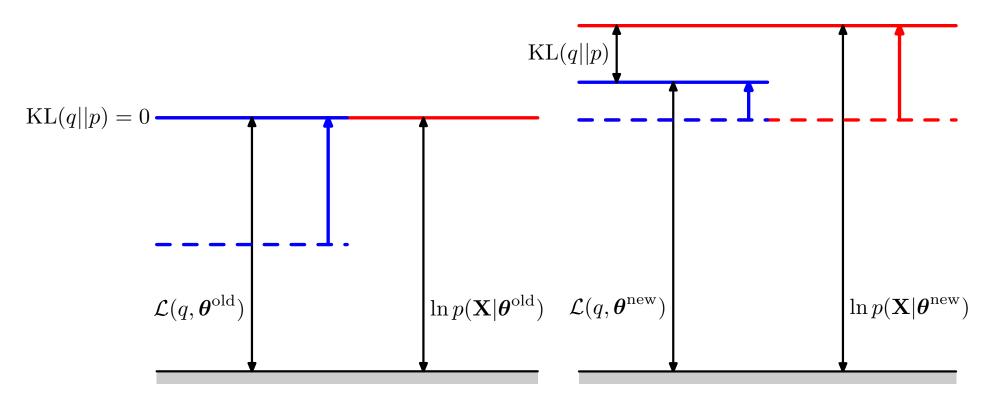
Convexity & Jensen's Inequality



Lower Bounds on Marginal Likelihood

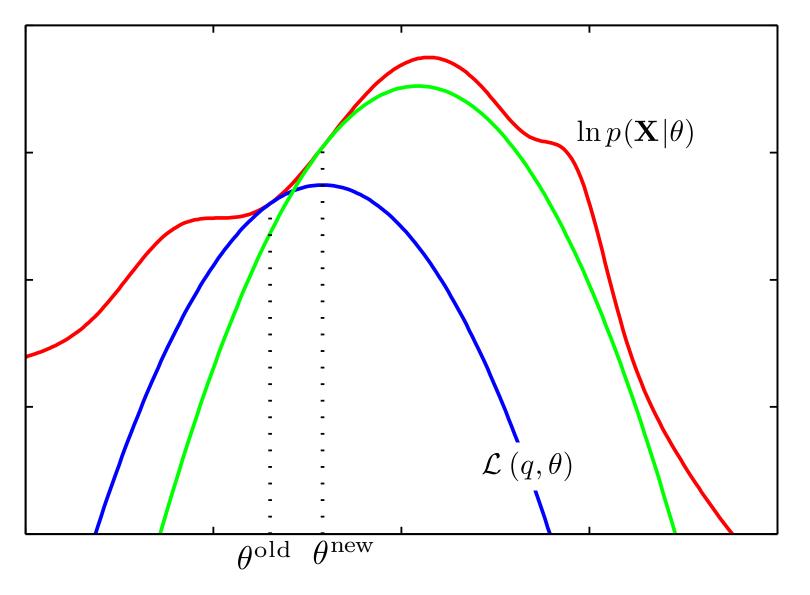


Expectation Maximization Algorithm



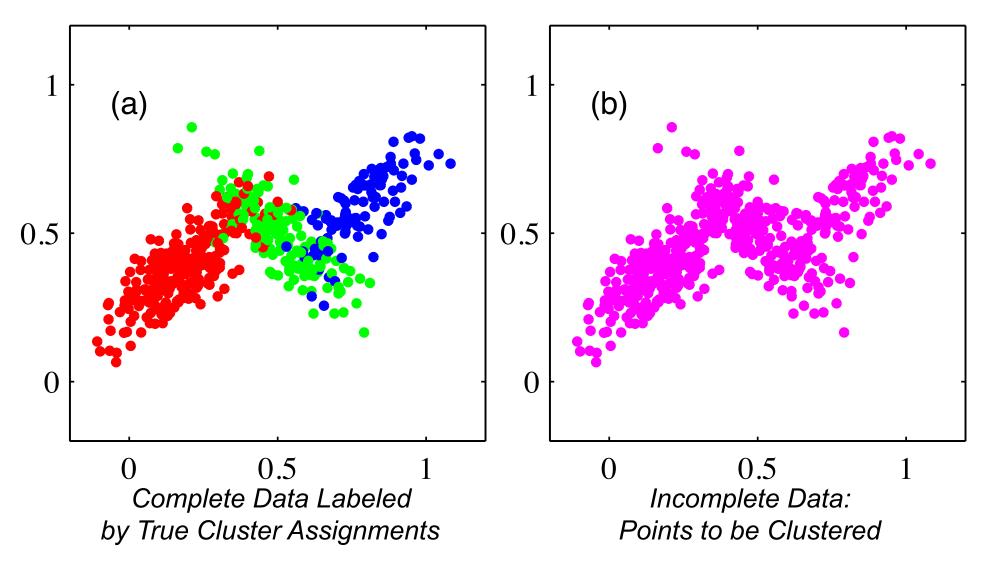
E Step: Optimize distribution on hidden variables given parameters *M Step:* Optimize parameters given distribution on hidden variables

EM: A Sequence of Lower Bounds

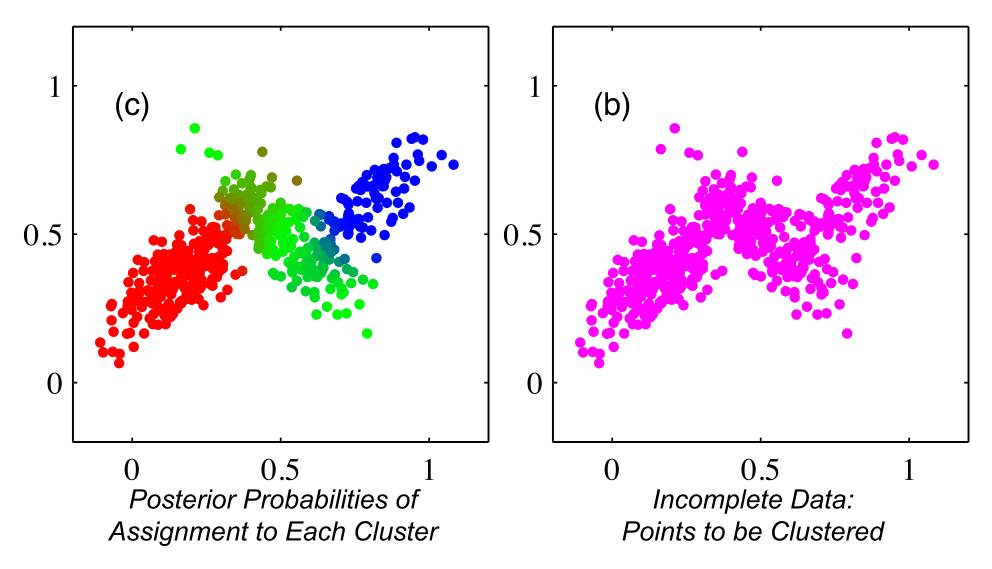


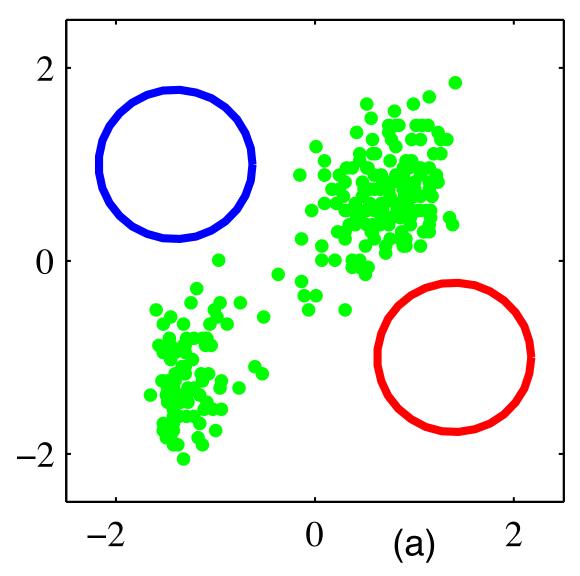
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Fitting Gaussian Mixtures

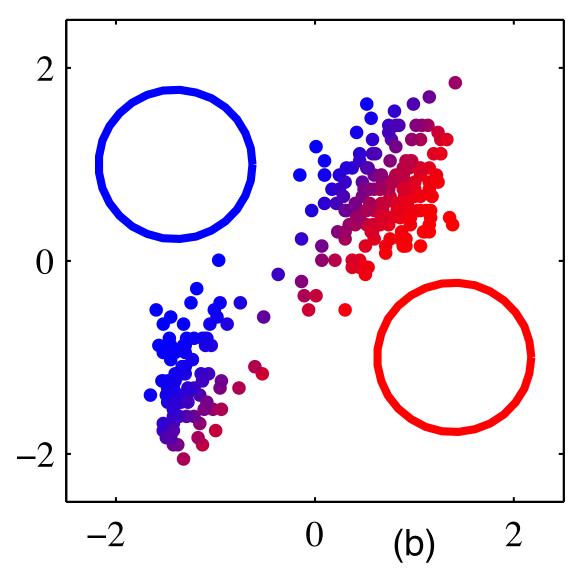


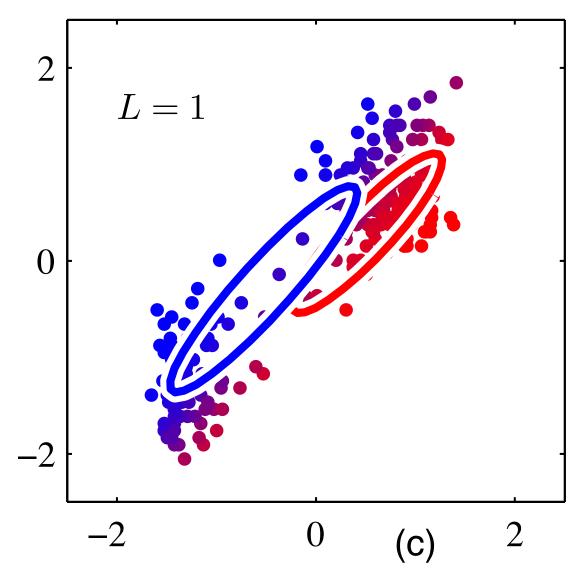
Posterior Assignment Probabilities

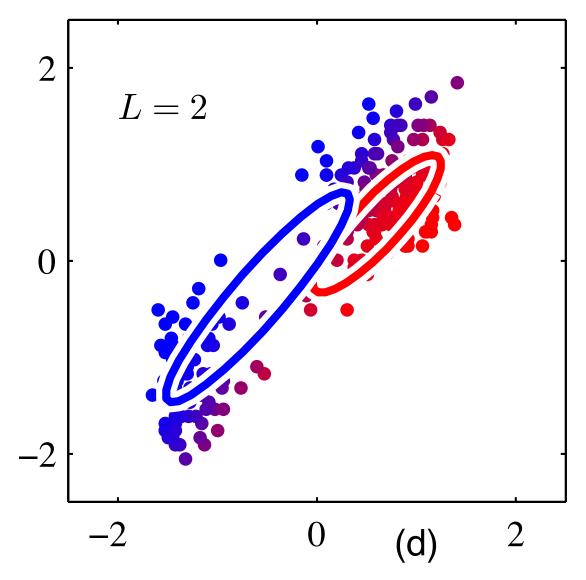


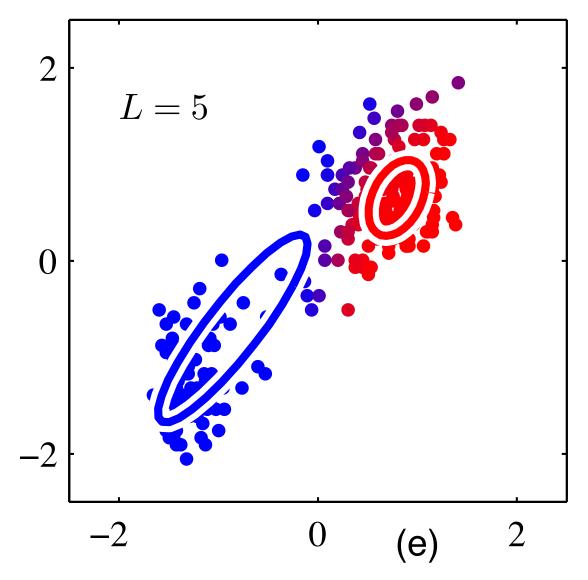


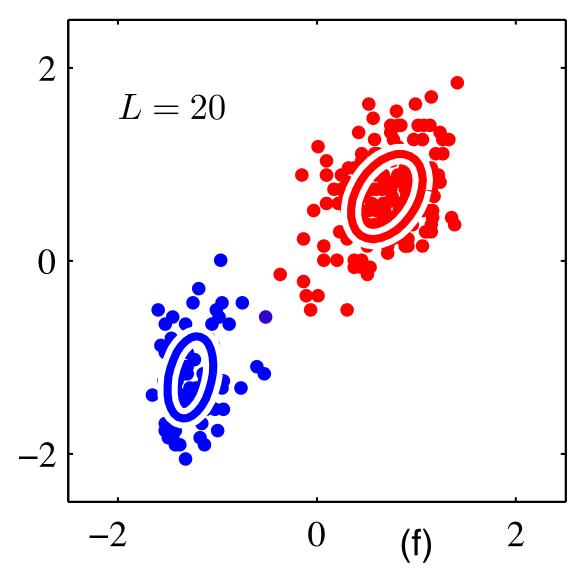
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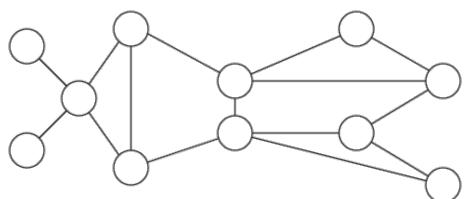






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Pairwise Markov Random Fields



$$p(x \mid y) = \frac{1}{Z} \prod_{(s,t) \in \mathcal{E}} \psi_{st}(x_s, x_t) \prod_{s \in \mathcal{V}} \psi_s(x_s, y)$$

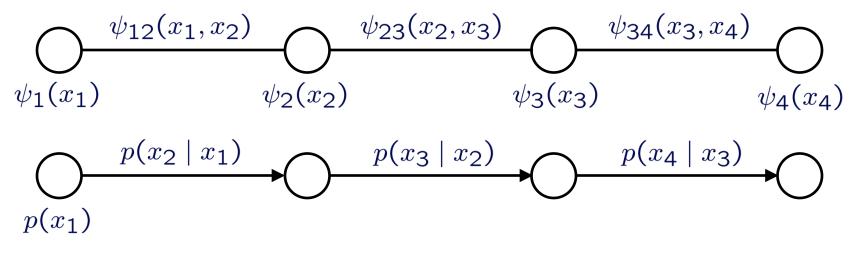
 $\mathcal{V} \longrightarrow$ set of N nodes $\{1, 2, \dots, N\}$

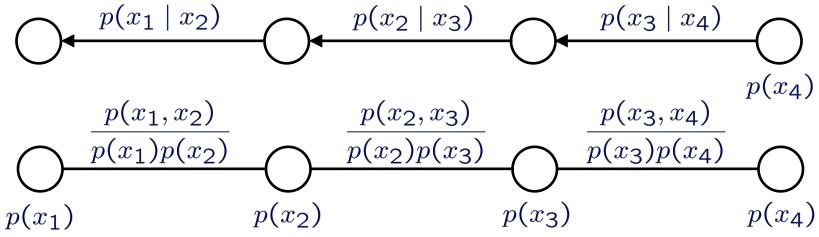
 \mathcal{E} \longrightarrow set of edges (s,t) connecting nodes $s,t\in\mathcal{V}$

normalization constant (partition function)

- Product of arbitrary positive *clique potential* functions
- Guaranteed Markov with respect to corresponding graph

Markov Chain Factorizations $p(x \mid y) = \frac{1}{Z} \prod_{(s,t) \in \mathcal{E}} \psi_{st}(x_s, x_t) \prod_{s \in \mathcal{V}} \psi_s(x_s, y)$





Energy Functions

$$p(x \mid y) = \frac{1}{Z} \prod_{(s,t)\in\mathcal{E}} \psi_{st}(x_s, x_t) \prod_{s\in\mathcal{V}} \psi_s(x_s, y)$$

$$= \frac{1}{Z} \exp\left\{-\sum_{(s,t)\in\mathcal{E}} \phi_{st}(x_s, x_t) - \sum_{s\in\mathcal{V}} \phi_s(x_s, y)\right\}$$

$$= \frac{1}{Z} \exp\left\{-E(x)\right\}$$

 $\phi_{st}(x_s, x_t) = -\log \psi_{st}(x_s, x_t) \qquad \phi_s(x_s) = -\log \psi_s(x_s)$

Interpretation and terminology from statistical physics

Approximate Inference Framework $p(x \mid y) = \frac{1}{Z} \prod_{(s,t) \in \mathcal{E}} \psi_{st}(x_s, x_t) \prod_{s \in \mathcal{V}} \psi_s(x_s, y)$

• Choose a family of approximating distributions which is tractable. The simplest example:

$$q(x) = \prod_{s \in \mathcal{V}} q_s(x_s)$$

• Define a distance to measure the quality of different approximations. Two possibilities:

$$D(p || q) = \sum_{x} p(x | y) \log \frac{p(x | y)}{q(x)}$$
$$D(q || p) = \sum_{x} q(x) \log \frac{q(x)}{p(x | y)}$$

• Find the approximation minimizing this distance

Fully Factored Approximations

$$p(x \mid y) = \frac{1}{Z} \prod_{(s,t) \in \mathcal{E}} \psi_{st}(x_s, x_t) \prod_{s \in \mathcal{V}} \psi_s(x_s, y)$$
$$q(x) = \prod_{s \in \mathcal{V}} q_s(x_s)$$

- Trivially minimized by setting $q_s(x_s) = p_s(x_s \mid y)$
- Doesn't provide a computational method...

Variational Approximations

$$D(q(x) || p(x | y)) = \sum_{x} q(x) \log \frac{q(x)}{p(x | y)}$$

$$\log p(y) = \log \sum_{x} p(x, y)$$

$$= \log \sum_{x} q(x) \frac{p(x, y)}{q(x)} \qquad \text{(Multiply by one)}$$

$$\geq \sum_{x} q(x) \log \frac{p(x, y)}{q(x)} \qquad \text{(Jensen's inequality)}$$

$$= -D(q(x) || p(x | y)) + \log p(y)$$

 Minimizing KL divergence maximizes a lower bound on the data likelihood

Free Energies

$$p(x \mid y) = \frac{1}{Z} \exp \{-E(x)\}$$

$$D(q \mid\mid p) = \sum_{x} q(x) \log q(x) - \sum_{x} q(x) \log p(x \mid y)$$

$$= -H(q) + \sum_{x} q(x)E(x) + \log Z$$
Negative Average Energy Normalizat ion
Gibbs Free Energy

 Free energies equivalent to KL divergence, up to a normalization constant

$$p(x \mid y) = \frac{1}{Z} \exp\left\{-\sum_{(s,t)\in\mathcal{E}} \phi_{st}(x_s, x_t) - \sum_{s\in\mathcal{V}} \phi_s(x_s, y)\right\}$$
$$q(x) = \prod_{s\in\mathcal{V}} q_s(x_s)$$

$$D(q || p) = -H(q) + \sum_{x} q(x)E(x) + \log Z$$

= $-\sum_{s \in \mathcal{V}} H_s(q_s) + \sum_{(s,t) \in \mathcal{E}} q_s(x_s)q_t(x_t)\phi_{st}(x_s, x_t)$
 $\cdots + \sum_{s \in \mathcal{V}} q_s(x_s)\phi_s(x_s) + \log Z$

Mean Field Equations

$$D(q || p) = -\sum_{s \in \mathcal{V}} H_s(q_s) + \sum_{(s,t) \in \mathcal{E}} q_s(x_s) q_t(x_t) \phi_{st}(x_s, x_t)$$
$$\dots + \sum_{s \in \mathcal{V}} q_s(x_s) \phi_s(x_s) + \log Z$$

- Add Lagrange multipliers to enforce
- $\sum_{x_s} q_s(x_s) = 1$

 $q_v(x_v)$

 $q_t(x_t)$

 x_s

• Taking derivatives and simplifying, we find a set of fixed point equations:

$$q_s(x_s) = \alpha \psi_s(x_s) \prod_{t \in \Gamma(s)} \prod_{x_t} \psi_{st}(x_s, x_t)^{q_t(x_t)}$$

• Updating one marginal at a time gives convergent coordinate descent

Mean Field Message Passing $m_{ij}(x_j) \propto \exp\left\{-\int_{\mathcal{X}} \phi_{ji}(x_j, x_i) q_i(x_i) dx_i\right\}$ $q_i(x_i) \propto \psi_i(x_i, y)$ $m_{ji}(x_i)$ $j \in \Gamma(i)$

Want products of messages to be simple

Want expectations of log potential functions to be simple

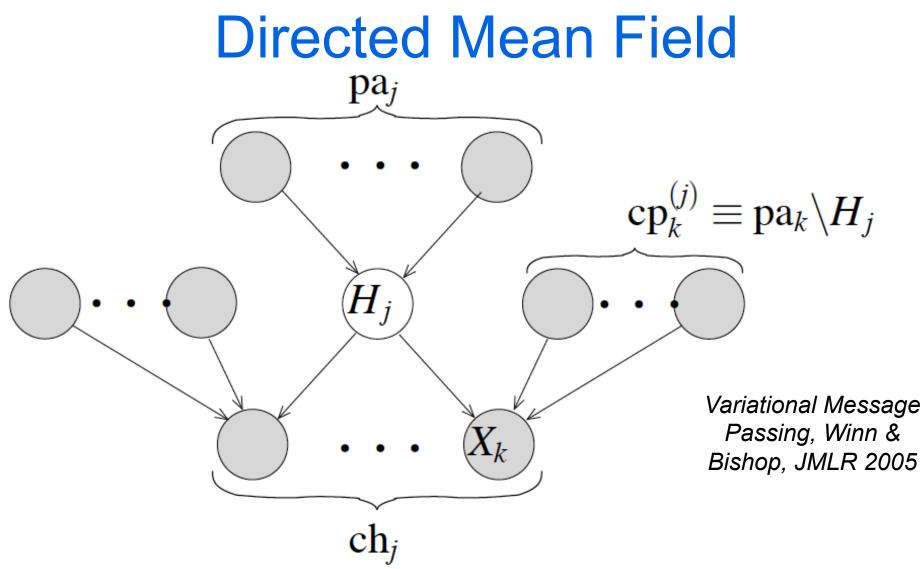
Exponential Families

• Natural or canonical parameters determine log-linear combination of sufficient statistics:

$$p(x \mid \theta) = \nu(x) \exp\left\{\sum_{a \in \mathcal{A}} \theta_a \phi_a(x) - \Phi(\theta)\right\}$$

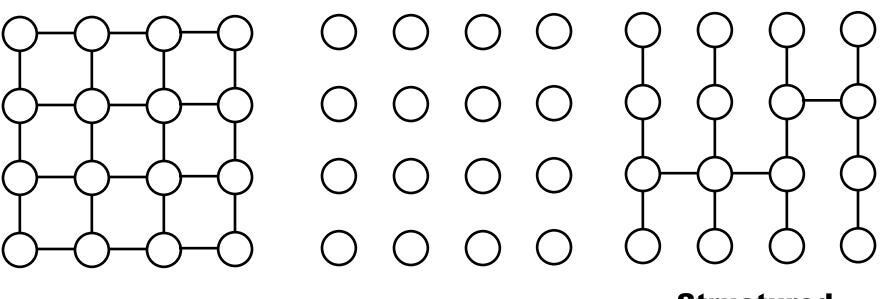
 Log partition function normalizes to produce valid probability distribution:

$$\Phi(\theta) = \log \int_{\mathcal{X}} \nu(x) \exp \left\{ \sum_{a \in \mathcal{A}} \theta_a \phi_a(x) \right\} dx$$
$$\Theta \triangleq \left\{ \theta \in \mathbb{R}^{|\mathcal{A}|} \mid \Phi(\theta) < \infty \right\}$$



- Can derive updates using exponential family form of the conditional distribution of each variable, given its parents
- Can also just take derivatives, collect terms, simplify...

Structured Mean Field



Original Graph

Naïve Mean Field

Structured Mean Field

 Any subgraph for which inference is tractable leads to a mean field style approximation for which the update equations are tractable