Walk-Sums and Belief Propagation in Gaussian Graphical Models

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Multivariate Gaussians

- Standard form: $p(x) \propto \exp\{-\frac{1}{2}(x-\mu)^T P^{-1}(x-\mu)\}$ where P is symmetric and $P \succ 0$.
- Information form: $p(x) \propto \exp\{-\frac{1}{2}x^T J x + h^T x\}$ where J is symmetric and $J \succ 0$.

$$\mu = J^{-1}h \quad \text{and} \quad P = J^{-1}$$

- J : Information matrix
- h: Potential vector

Multivariate Gaussians

- Rescale the variables so that $J_{ii} = 1$
- Partial correlation coefficients

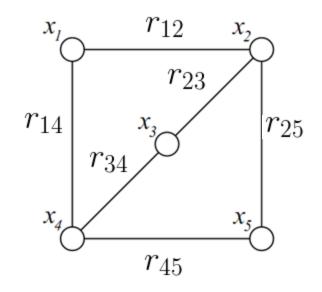
$$r_{ij} \triangleq \frac{\operatorname{cov}(x_i; x_j | x_{V \setminus ij})}{\sqrt{\operatorname{var}(x_i | x_{V \setminus ij}) \operatorname{var}(x_j | x_{V \setminus ij})}} = -\frac{J_{ij}}{\sqrt{J_{ii} J_{jj}}} = -J_{ij}$$

• Define R such that $R_{ii} = 0$ and $R_{ij} = r_{ij}$

$$J = I - R$$

Gaussian MRFs

p(x₁, x₂, x₃, x₄, x₅) can be written as G = (V,E) where each component x_i is a node and r_{ij} are edge weights.

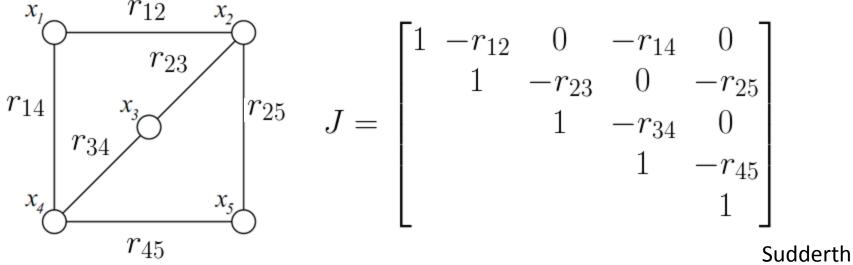


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Gaussian MRFs

• J encodes pairwise Markov independencies:

$$J_{ij} = 0 \quad \text{iff} \ \{i, j\} \notin E$$



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Gaussian MRFs

• Hammersley-Clifford theorem:

 $p(x) \propto \exp\{-\frac{1}{2}x^T J x + h^T x\}$ can be written as

$$p(x) \propto \prod_{i \in V} \Psi_i(x_i) \prod_{\{i,j\} \in E} \Psi_{ij}(x_i, x_j)$$

$$\psi_i(x_i) = \exp\{-\frac{1}{2}J_{ii}x_i^2 + h_ix_i\}$$

$$\psi_{ij}(x_i, x_j) = \exp\{-x_iJ_{ij}x_j\}$$

Problem

• Given the model (J_V, h_V) , we want to perform variable elimination/marginalization

$$\boldsymbol{U} = V \backslash \boldsymbol{i} \qquad p_U(x_U) = \int_{x_i} p(\mathbf{x}) dx_i = N(\mu_U, P_U)$$

$$p(x_i) = \int_{x_{V \setminus i}} p(\mathbf{x}) dx_{V \setminus i} = N(\mu_i, \sigma_i)$$

Variable elimination in trees

For the acyclic Gaussian case, $p_U(x_U)$ is obtained by

$$\hat{J}_U = J_{U,U} - J_{U,i} J_{ii}^{-1} J_{i,U}$$
 and $\hat{h}_U = h_U - J_{U,i} J_{ii}^{-1} h_i$
 $p_U(x_U) = N(\hat{J}_U, \hat{h}_U)$

How to compute all marginals efficiently?

Belief Propagation

Perform Sum-Product/BP to obtain marginals at each node.

$$m_{i \to j}(x_j) = \int \psi_{ij}(x_i, x_j) \psi_i(x_i) \prod_{k \in \mathcal{N}(i) \setminus j} m_{k \to i}(x_i) dx_i$$
$$p_i(x_i) \propto \psi_i(x_i) \prod_{k \in \mathcal{N}(i)} m_{k \to i}(x_i)$$

Cyclic case

• Try Loopy BP

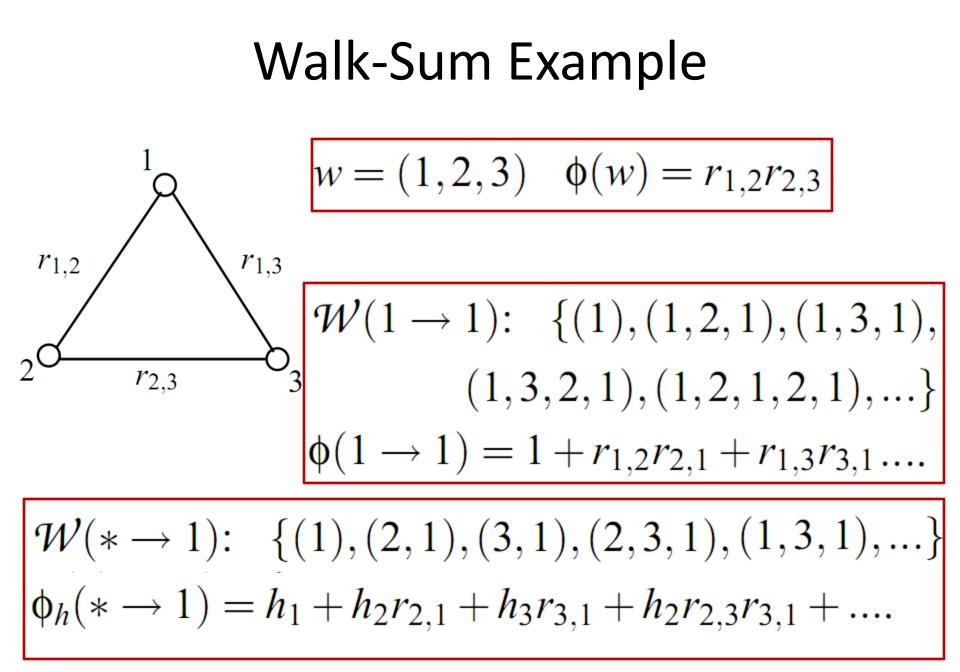
$$m_{i\to j}^{(n)}(x_j) = \int \Psi_{ij}(x_i, x_j) \Psi_i(x_i) \prod_{k \in \mathcal{N}(i) \setminus j} m_{k\to i}^{(n-1)}(x_i) dx_i$$

- Not guaranteed to converge, energy function has multiple fixed points.
- Can we exploit Gaussian structure to guarantee convergence and correctness?

Walk-Sums 101

- Walk $w = (w_0, w_1, \dots, w_l) \ w_k \in V$ $\{w_k, w_{k+1}\} \in E$
- Weight of a walk w $\phi(w) = \prod_{k=1}^{l(w)} r_{w_{k-1},w_k}$
- A set of walks W

$$\phi(\mathcal{W}) = \sum_{w \in \mathcal{W}} \phi(w) \qquad \phi_h(\mathcal{W}) = \sum_{w \in \mathcal{W}} h_{w_0} \phi(w)$$



Neumann Series

$$J = I - R$$

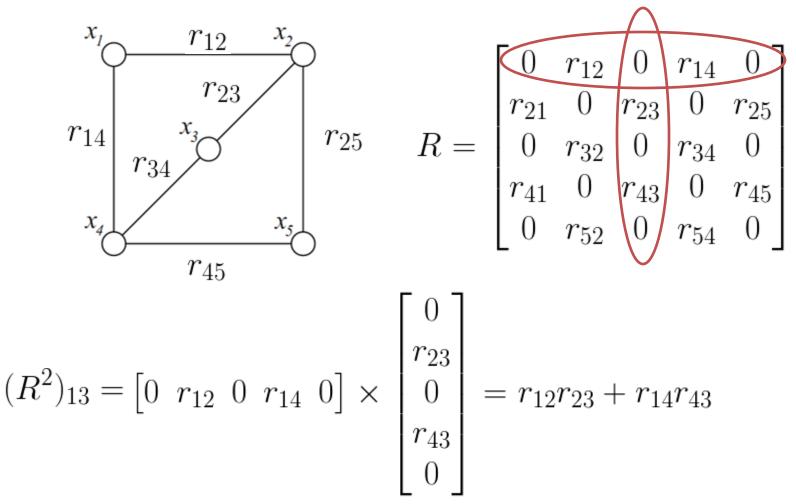
Maximum absolute value of the eigenvalues.
$$P = J^{-1} = (I - R)^{-1} = \sum_{k=0}^{\infty} R^k, \text{ for } \rho(R) < 1$$

• $(R^l)_{ij}$ can be interpreted as sum of walks from i to j of length l

$$(R^{l})_{ij} = \sum_{w_1, \dots, w_{l-1}} r_{i, w_1} r_{w_1, w_2} \dots r_{w_{l-1}, j} = \sum_{w: i \stackrel{l}{\to} j} \phi(w)$$

Neumann Series

Compute $(R^2)_{13}$



Walk-Sums for Inference

$$P = J^{-1} = (I - R)^{-1} = \sum_{k=0}^{\infty} R^k$$
, for $\rho(R) < 1$

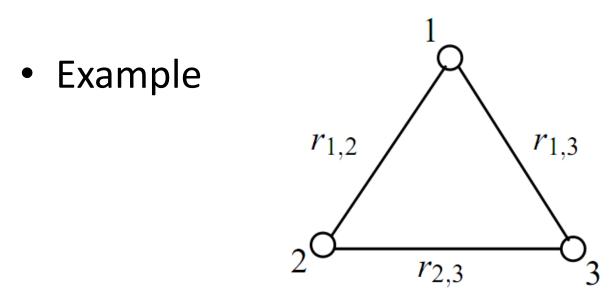
• Computing the marginals

$$P_{ii} = \phi(i \to i) = \frac{1}{1 - \alpha_i}$$

$$\alpha_i = \phi(i \xrightarrow{i} i)$$

$$\mu_i = \phi_h(* \to i) = \frac{h_i + \beta_i}{1 - \alpha_i} \qquad \beta_i = \phi_h(* \to i)$$

Walk-Sums for Inference



 $P_{1,1} = \phi(1 \to 1) = 1 + r_{1,2}r_{2,1} + r_{1,3}r_{3,1} + r_{1,2}r_{2,3}r_{3,1} + \dots$ $\mu_1 = \phi_h(* \to 1) = h_1 + h_2r_{2,1} + h_3r_{3,1} + h_2r_{2,3}r_{3,1} + \dots$ Sums are guaranteed to converge!

Walk-Summability

- If the sum is well-defined (converges absolutely) then the model is walk summable.
- Equivalent conditions for walk-summability

(i) $\sum_{w:i \to j} |\phi(w)|$ converges for all $i, j \in V$.

(ii)
$$\sum_{l} \overline{R^{l}}$$
 converges.

(iii) $\rho(\overline{R}) < 1$. (iv) $I - \overline{R} \succ 0$.

Define \overline{R} where $\overline{R}_{ij} = |R_{ij}|$ $P = J^{-1} = (I - R)^{-1}$ $= \sum_{k=0}^{\infty} R^k$ for $\rho(R) < 1$

Walk-Summable models

- Attractive models: If for all i, $R \ge 0$
 - Attractive models are walk-summable. Proof follows directly from condition (iv).
- Non-frustrated models: If the graph doesn't contain cycles with an odd number of negative edge weights.
 - Non-frustrated models are walk-summable.
 - Trees don't contain any cycles so they are also walk-summable.

Walk-Summable models

• Pairwise-Normalizable: If for every edge $e \in E$,

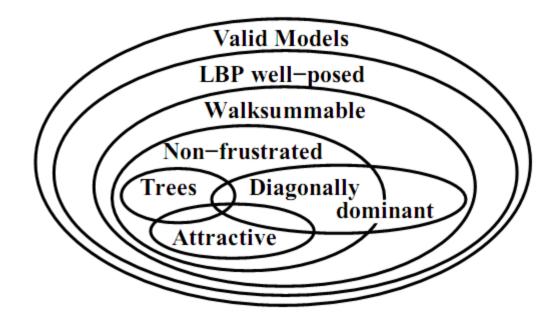
 $J_e \succ 0$

• Walk-Summability is **equivalent** to pairwise normalizability.

• Diagonally dominant: $\sum_{j \neq i} |J_{ij}| < J_{ii}$ These models are pairwise-normalizable and hence walk-summable.

Walk-Summable models

 Walk-summable/pairwise normalizable models include trees, attractive, non-frustrated and diagonally dominant models.



Walk-Sum interpretation of BP

- Walk-Sum computation on trees is equivalent to running BP.
- This framework can be used to analyze loopy BP behavior in cyclic graphs:
 - Loopy BP is equivalent to exact inference on the computation tree.
 - Then, Loopy BP is equivalent to walk sums in the computation tree.
 - Analyze the difference between walk sums in the computation tree and walk sums in the original graph.

Walk-Sums and BP on trees

• Calculating variances with Walk-Sums:

$$P_{jj} = \frac{1}{1 - \alpha_j}$$

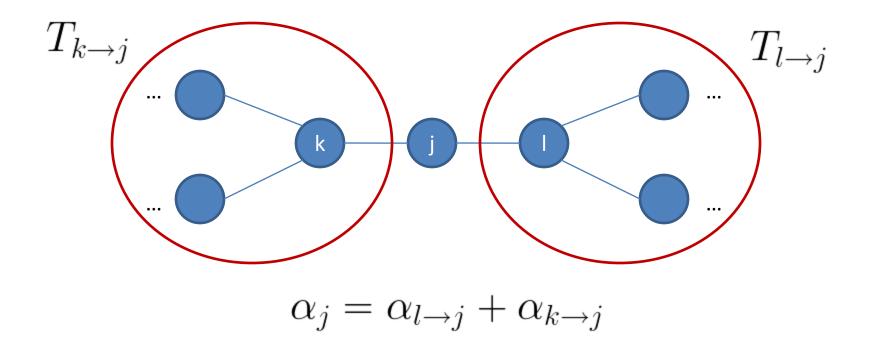
$$\alpha_j = \phi(j \xrightarrow{\backslash j} j) = \sum_{i \in \mathcal{N}(j)} \phi(j \xrightarrow{\backslash j} j \mid T_{i \to j}) \triangleq \sum_{i \in \mathcal{N}(j)} \alpha_{i \to j}$$

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• Belief equation at node j

$$b(x_j) \propto \psi_j(x_j) \prod_{k \in N(j)} m_{k \to j}(x_j)$$

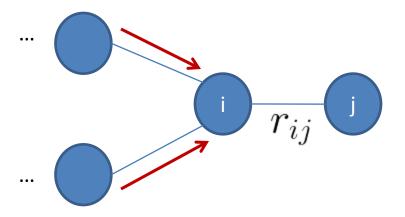
Walk-Sums and BP on trees $\alpha_j = \phi(j \xrightarrow{\backslash j} j) = \sum_{i \in \mathcal{N}(j)} \phi(j \xrightarrow{\backslash j} j \mid T_{i \to j}) \triangleq \sum_{i \in \mathcal{N}(j)} \alpha_{i \to j}$



Walk-Sums and BP on trees

 How about α_{i→j}? How do they correspond to messages in BP?

$$\alpha_{i \to j} = r_{ij}^2 \frac{1}{1 - \sum_{k \in \mathcal{N}(i) \setminus j} \alpha_{k \to i}}$$

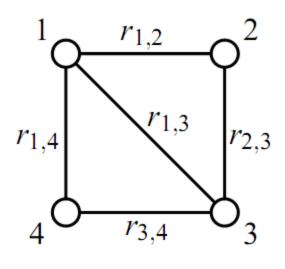


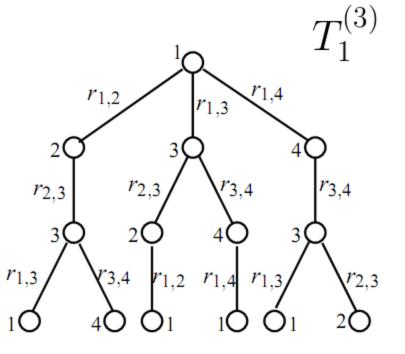
How about loopy BP?

- Can we use the walk-sum framework to understand the convergence and correctness of loopy BP in Gaussian models?
 - We will do this by comparing the walk-sums in the original graph to the loopy BP, which is equivalent to walk-sums in the computation tree.
 - Are they the same?

Computation tree

• Running Loopy BP on the original graph is equivalent to running exact inference on the computation tree $T_i^{(n)}$, hence doing walk-sums.





Loopy BP in Walk-Summable Models

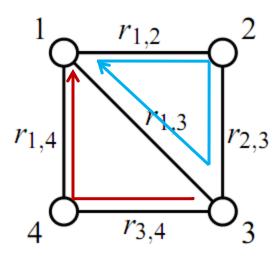
 After n iterations, the estimates for node 0 (root of the tree) are

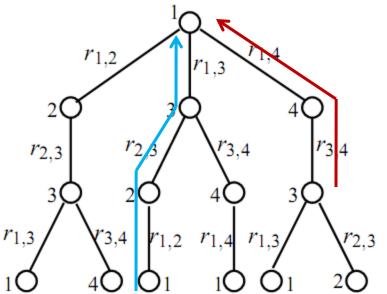
$$P_0(T_i^{(n)}) = \phi(0 \to 0 \mid T_i^{(n)})$$
$$\mu_0(T_i^{(n)}) = \phi_h(* \to 0 \mid T_i^{(n)})$$

 Assuming loopy BP has converged, are the variance and mean estimates correct?

Estimated means

• Lemma: There is a 1-1 relationship between walks in the original graph and walks in the computation tree.

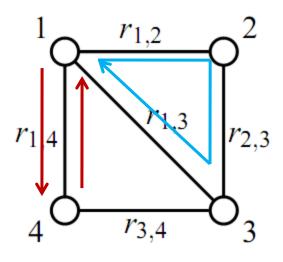


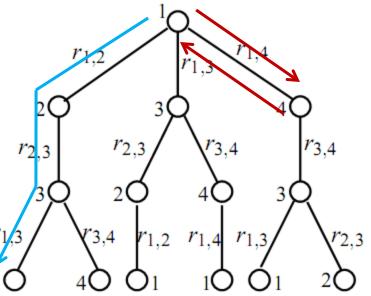


Upon convergence, the estimated means are correct!

Estimated variances

 Lemma: Loopy BP variance estimate is a sum of *backtracking* self-return walks, a subset of all self-return walks.





 Upon convergence, the estimated variances are incorrect!

Convergence

- All walks in $T_i^{(n)}$ are subsets of walks in the original graph.
- We have already shown that latter converges so the former must also converge!

 Loopy BP in walk-summable models will always converge!

Summary

- Introduced Walk-Sum framework.
- Shown that many non-trivial classes of models are walk-summable.
- Presented a Walk-Sum interpretation of BP.
- Shown that Loopy BP will converge in walksummable models and upon convergence, the means will be correct but variances in general will not.