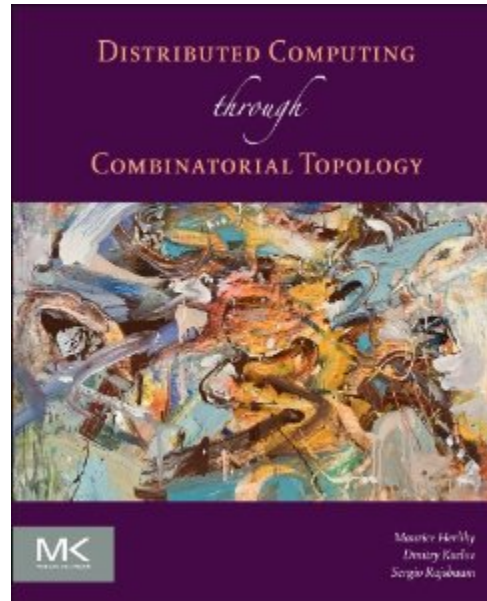


Wait-Free Computability for General Tasks



Companion slides for
Distributed Computing
Through Combinatorial Topology
Maurice Herlihy & Dmitry Kozlov & Sergio Rajsbaum

Road Map

Inherently colored tasks

Solvability for colored tasks

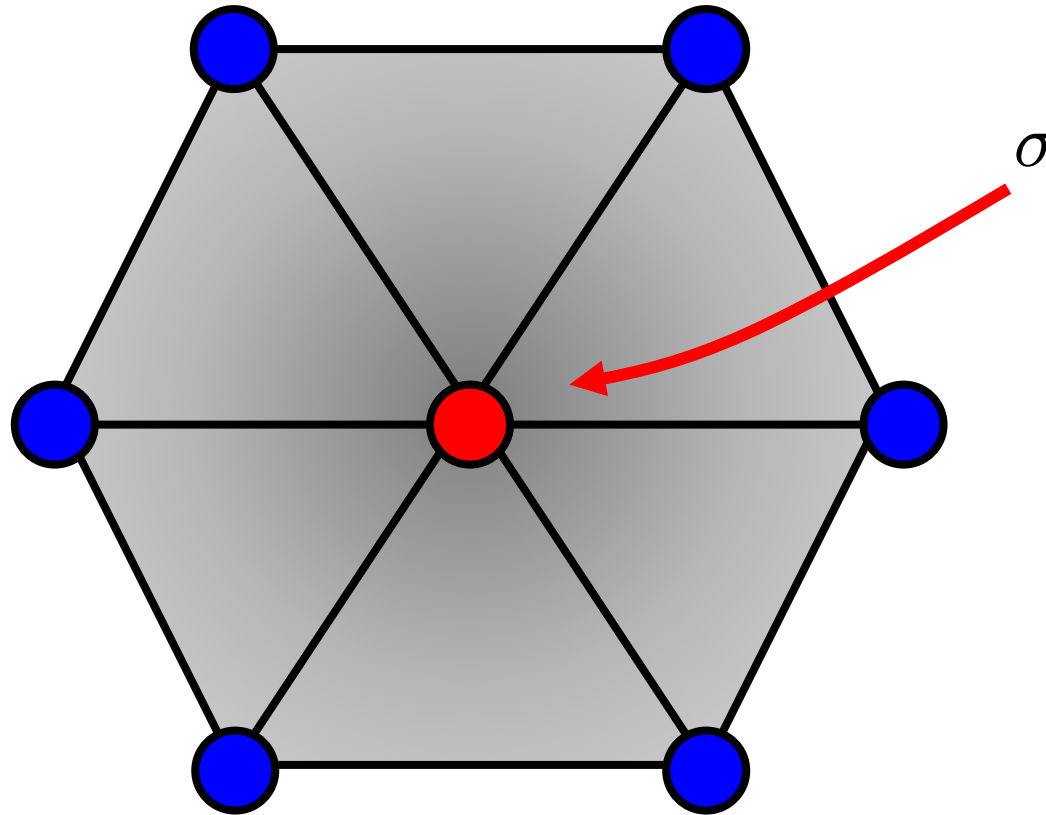
Protocol \Rightarrow map

Map \Rightarrow protocol

A Sufficient Topological Conditions

Review

Star

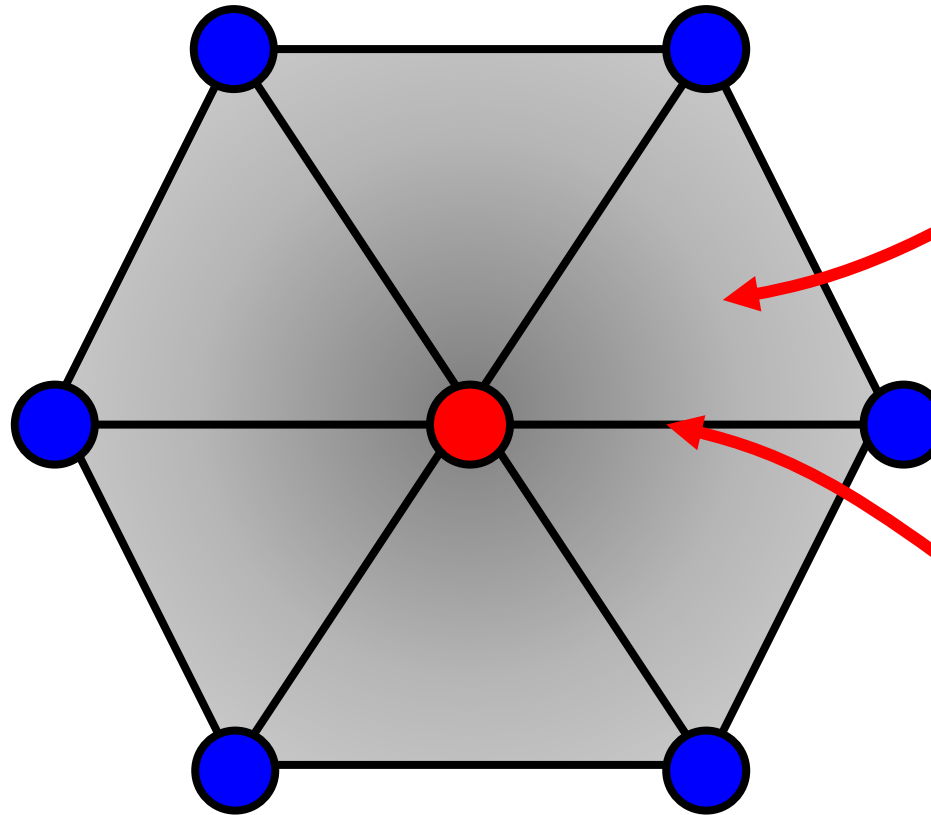


$\text{Star}(\sigma, \mathcal{K})$ is the complex of facets of \mathcal{K} containing σ

Complex

Review

Facet



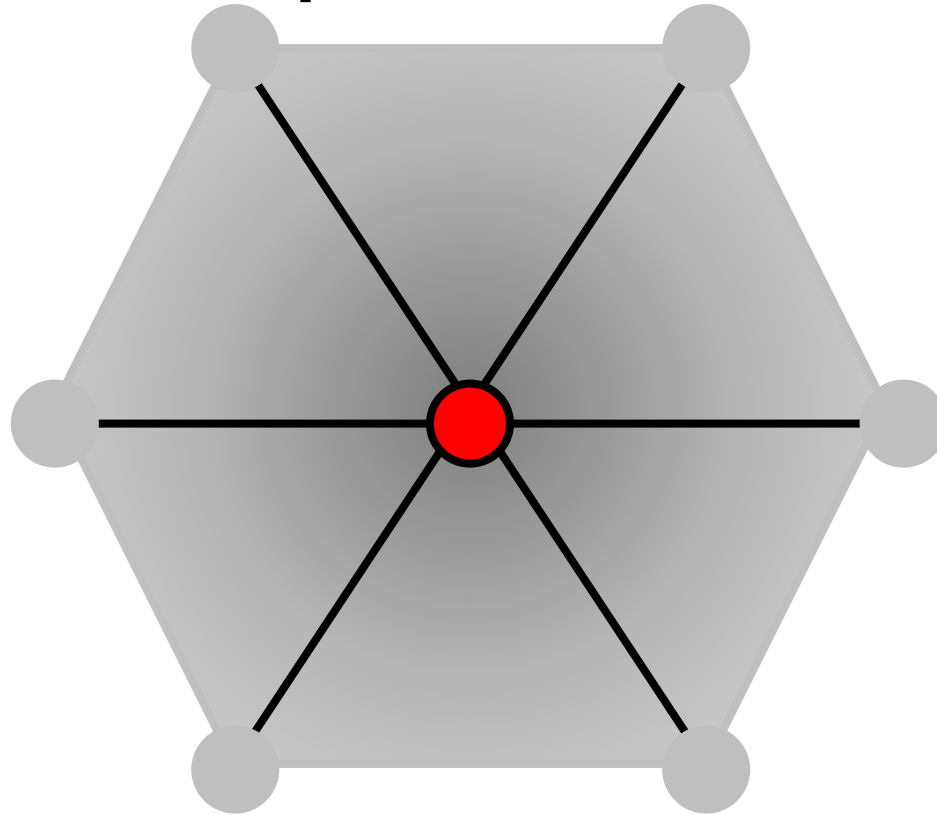
Facet

not a
facet

A facet is a simplex of maximal dimension

Review

Open Star

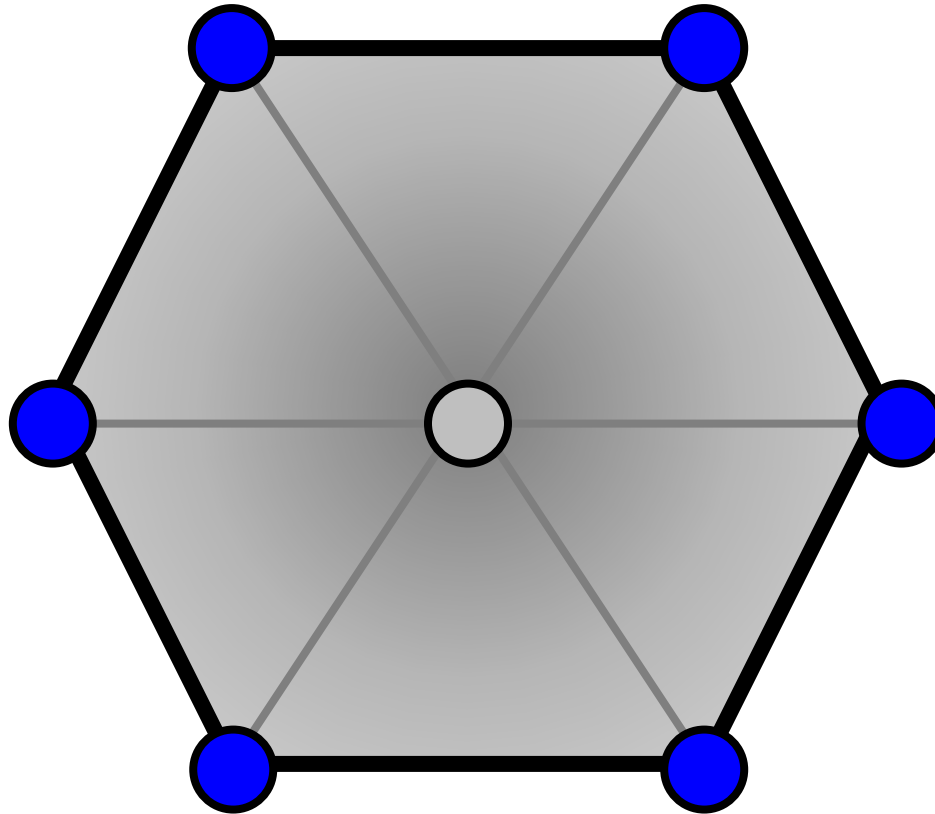


$\text{Star}^\circ(\sigma, \mathcal{K})$ union of interiors of simplexes containing σ

Point Set

Review

Link



$\text{Link}(\sigma, \mathcal{K})$ is the complex of simplices of $\text{Star}(\sigma, \mathcal{K})$ not containing σ

Complex

Review

A simplicial map ϕ is *rigid* if
 $\dim \phi(\sigma) = \dim \sigma$.

Road Map

Inherently colored tasks

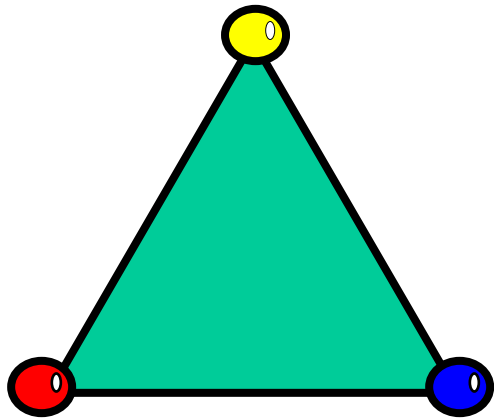
Solvability for colored tasks

Protocol \Rightarrow map

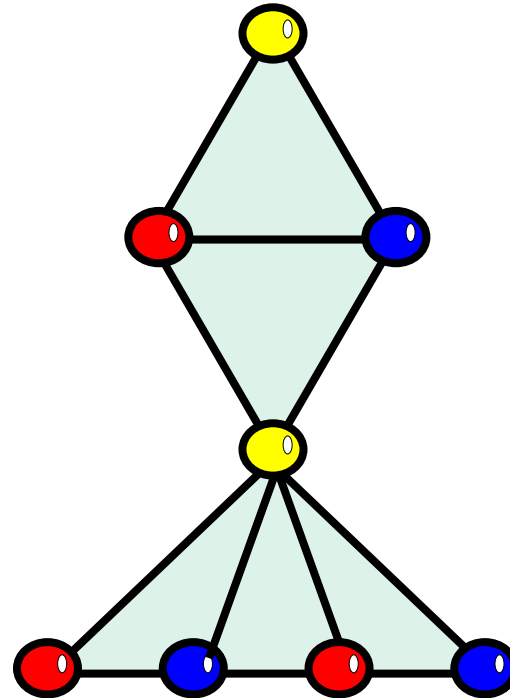
Map \Rightarrow protocol

A Sufficient Topological Conditions

The Hourglass task

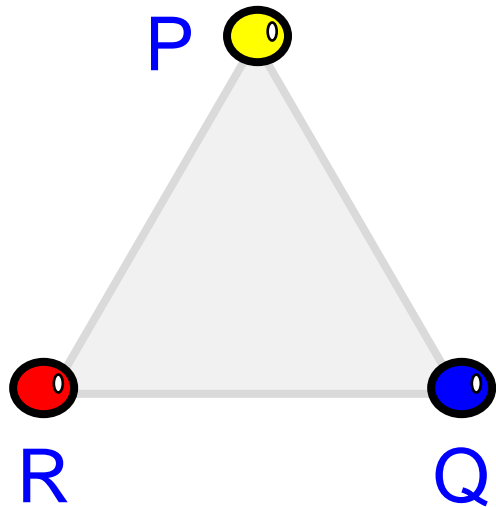


\mathcal{I}

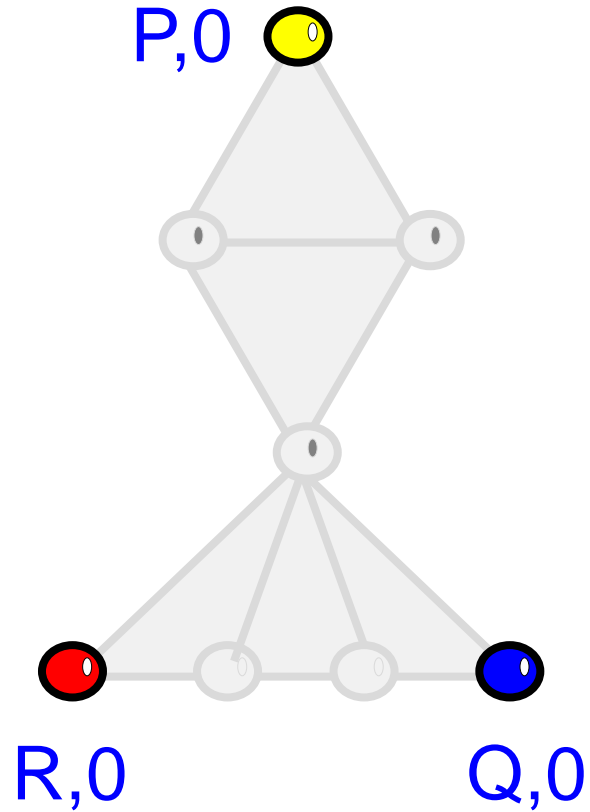
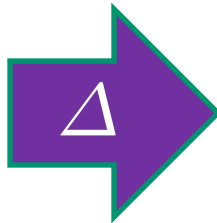


\mathcal{O}

Single-Process Executions



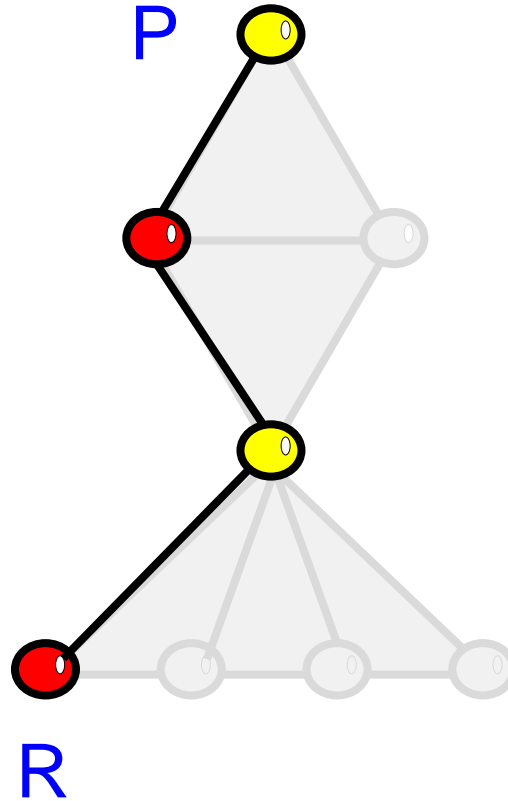
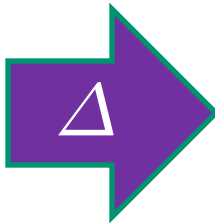
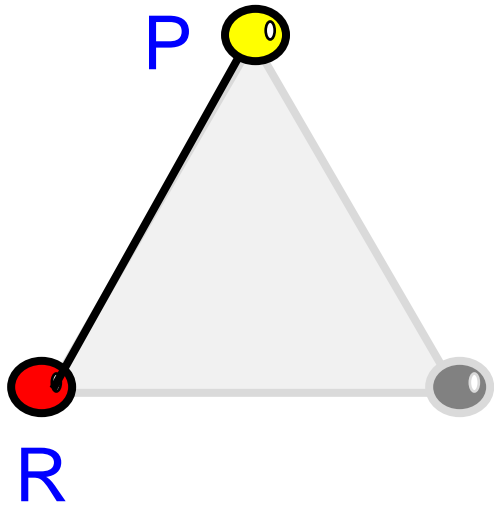
\mathcal{I}



\mathcal{O}

P and R only

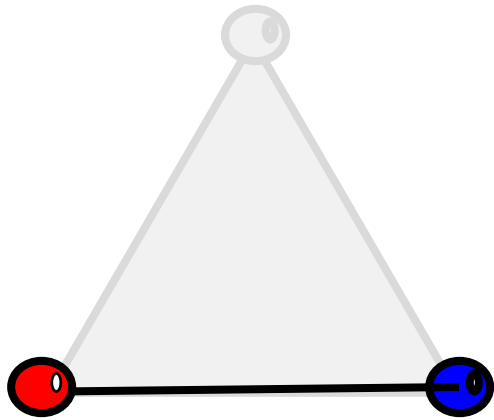
(P and Q Symmetric)



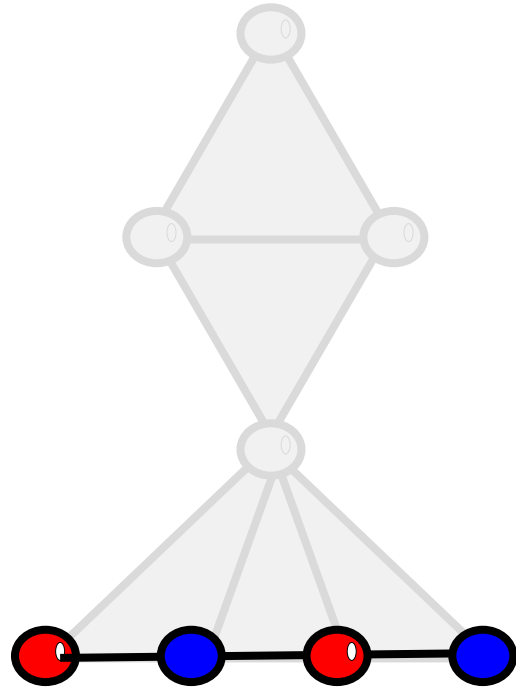
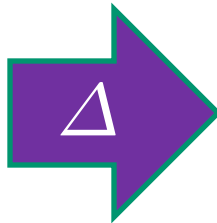
\mathcal{I}

\mathcal{O}

Q and R only



\mathcal{I}



\mathcal{O}

Claim:

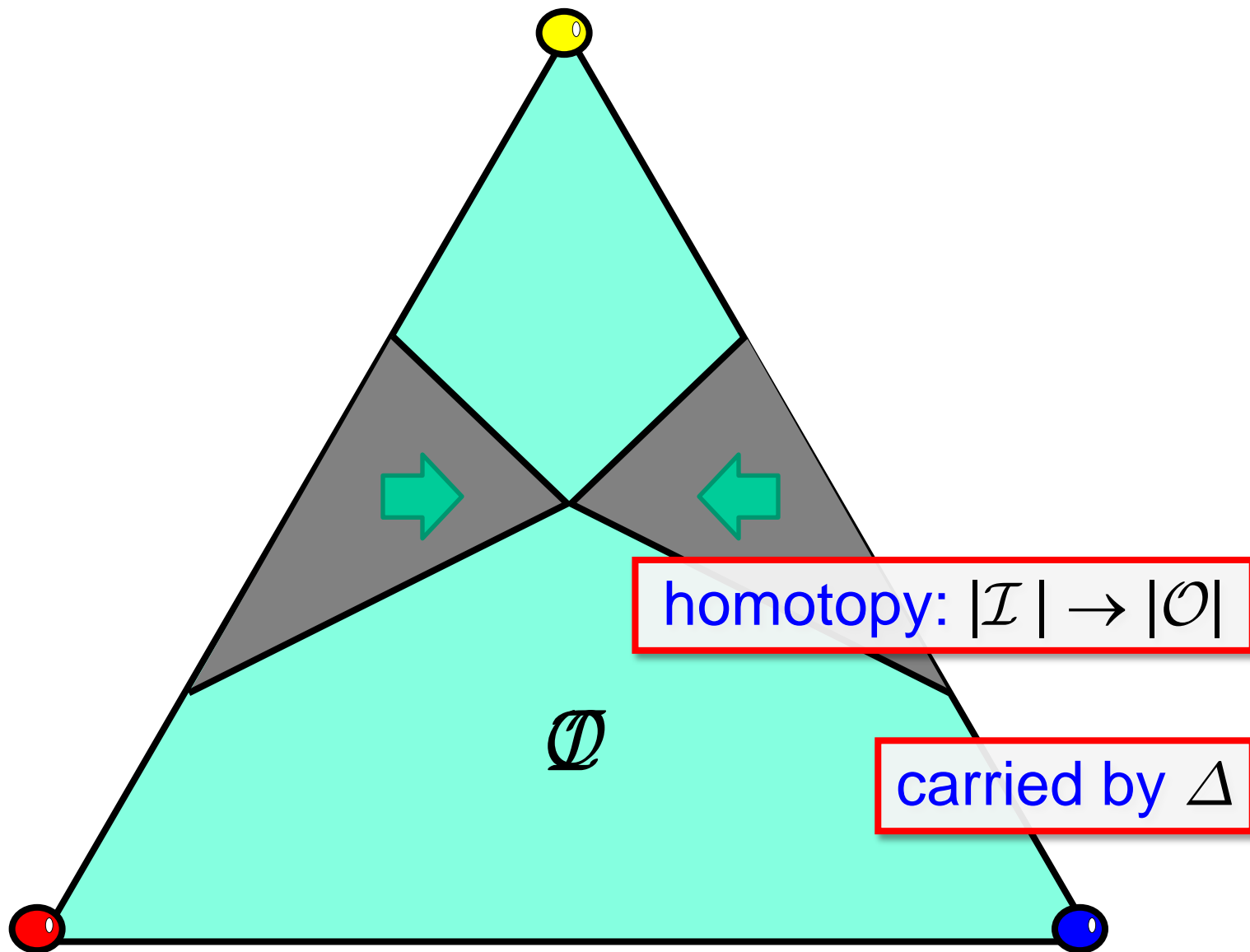
Hourglass satisfies conditions
of fundamental theorem ...

But has no wait-free immediate
snapshot protocol!

Claim:

Hourglass satisfies conditions
of fundamental theorem ...

But has no wait-free immediate
snapshot protocol!



Claim:

Hourglass satisfies conditions
of fundamental theorem ...

**But has no wait-free immediate
snapshot protocol!**

Claim:

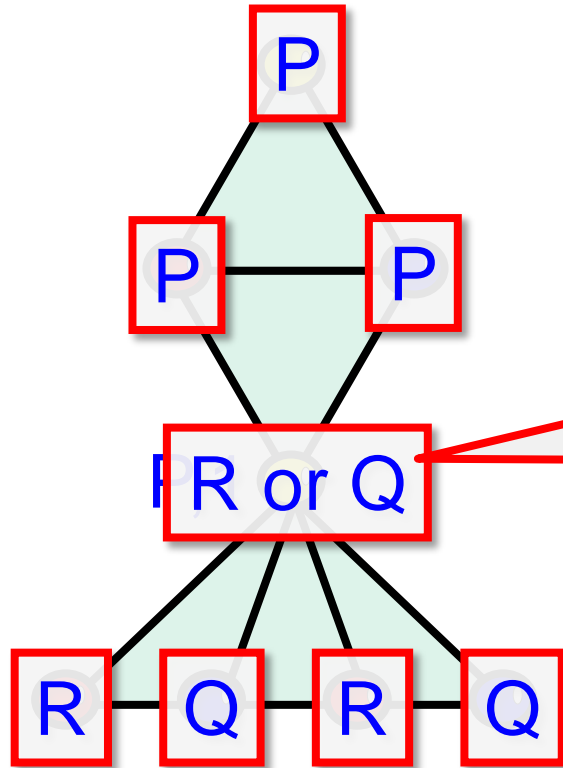
The Hourglass task solves
2-set agreement ...

Which has no wait-free
read-write protocol.

Protocol:

Write input value to
announce array ...

Run Hourglass task ...



Find non-null
announce[]
value

Look in announce[] array ...

What Went Wrong?

Theorem

A colorless $(\mathcal{I}, \mathcal{O}, \Delta)$ has a wait-free immediate snapshot protocol iff there is a continuous map ...

$$f: |\mathcal{I}| \rightarrow |\mathcal{O}| \dots$$

carried by Δ

One Direction is OK

Theorem

If $(\mathcal{I}, \mathcal{O}, \Delta)$ has a wait-free
read-write protocol ...

then there is a continuous map ...

$$f: |\mathcal{I}| \rightarrow |\mathcal{O}| \dots$$

carried by Δ

The Other Direction Fails

Theorem?

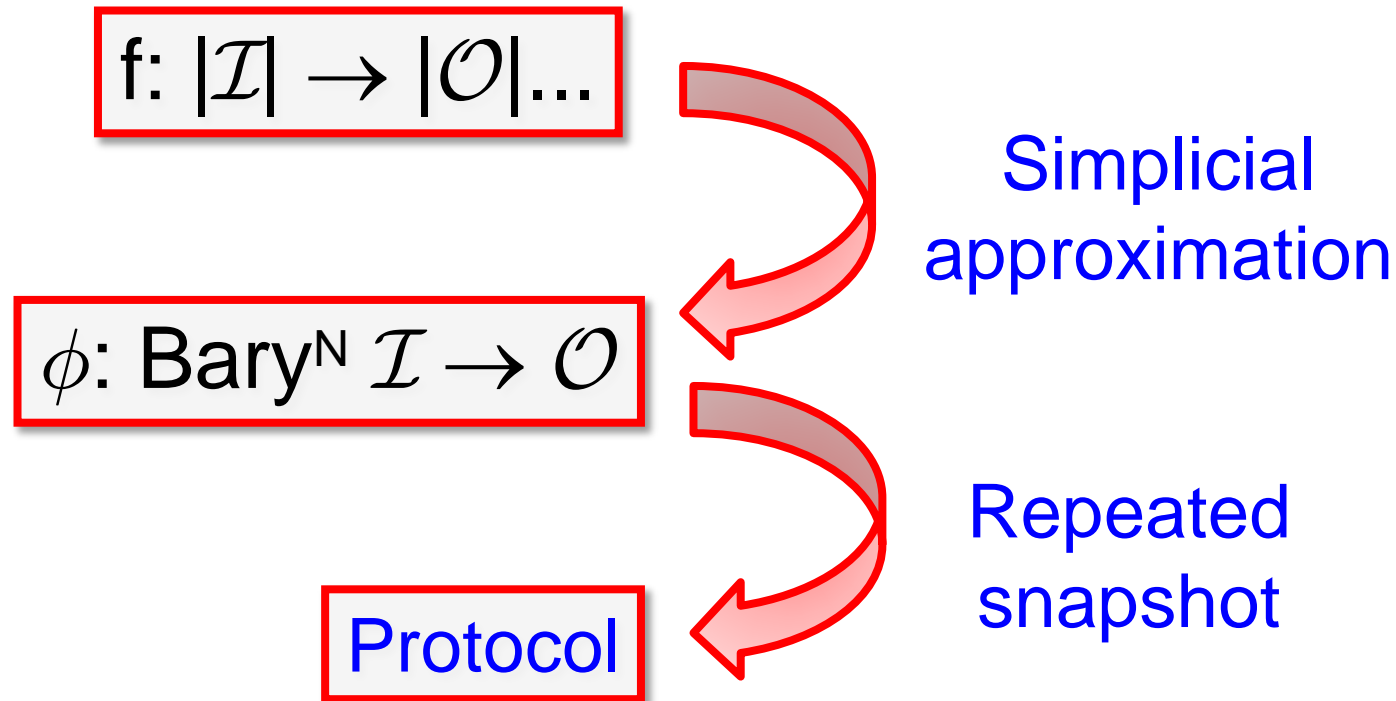
If there is a continuous map ...

$$f: |\mathcal{I}| \rightarrow |\mathcal{O}| \dots$$

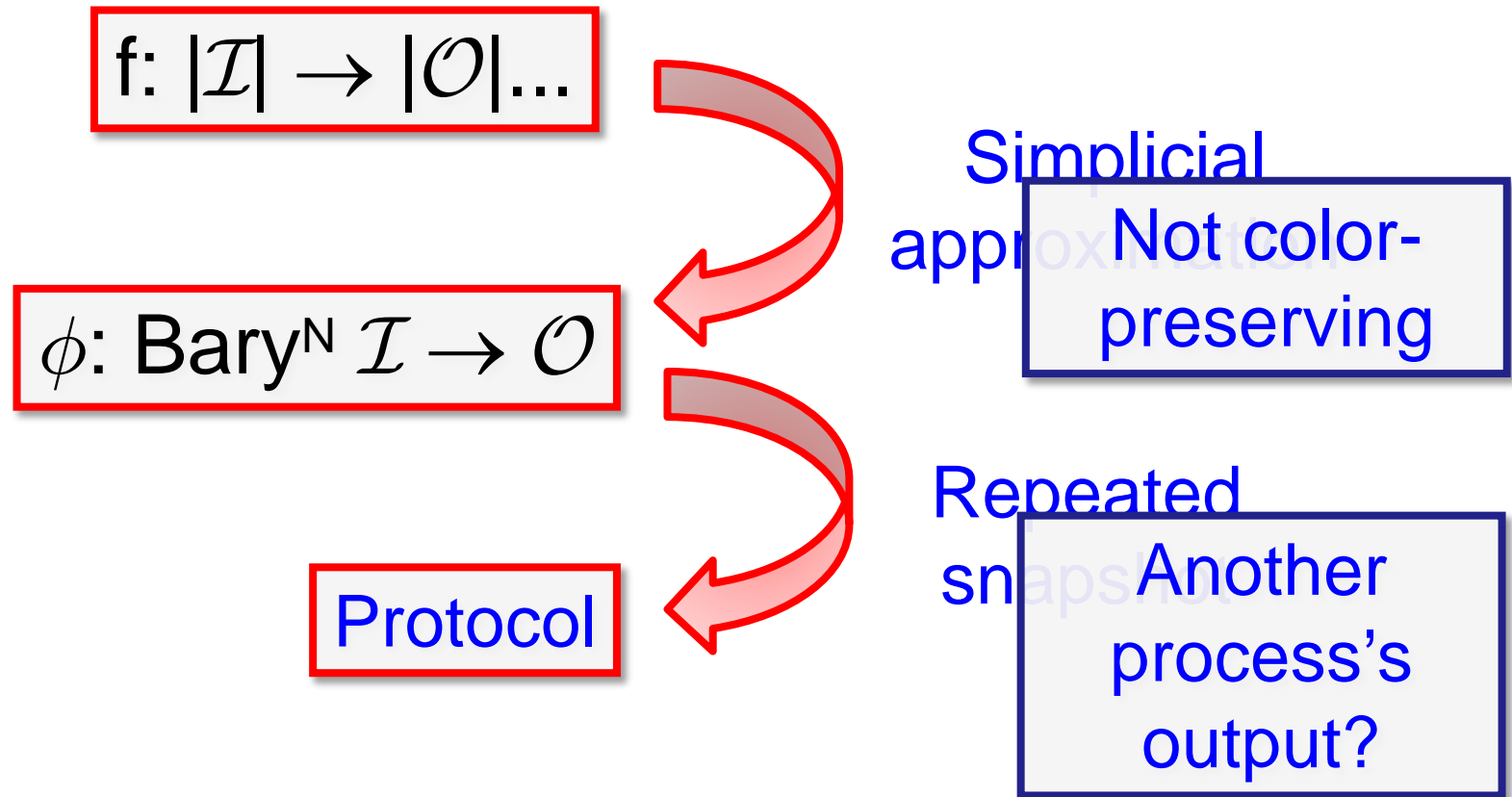
carried by Δ ...

then does $(\mathcal{I}, \mathcal{O}, \Delta)$ have a
wait-free IS protocol?

Review



Review



Road Map

Inherently colored tasks

Solvability for colored tasks

Protocol \Rightarrow map

Map \Rightarrow protocol

A Sufficient Topological Conditions

Theorem

A colorless $(\mathcal{I}, \mathcal{O}, \Delta)$ has a wait-free immediate snapshot protocol iff there is a continuous map ...

$$f: |\mathcal{I}| \rightarrow |\mathcal{O}| \dots$$

carried by Δ

How can we adapt this theorem to colored tasks?

Fundamental Theorem for Colored Tasks

Theorem

$(\mathcal{I}, \mathcal{O}, \Delta)$ has a wait-free read-write protocol iff ...

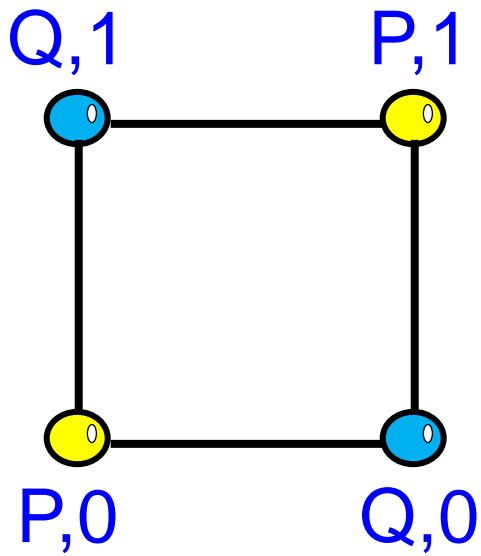
\mathcal{I} has a *chromatic* subdivision $\text{Div } \mathcal{I}$...

& *color-preserving* simplicial map

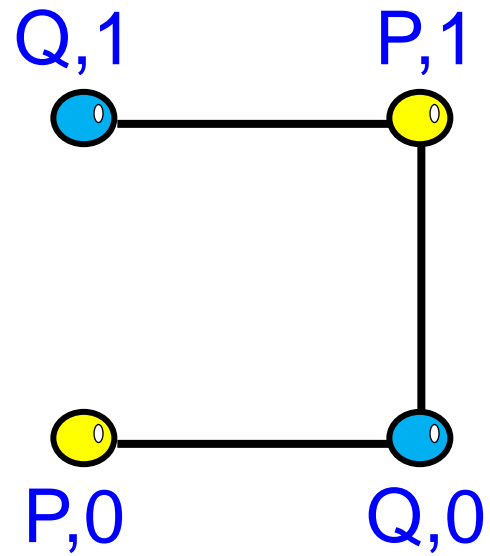
$$\phi: \text{Div } \mathcal{I} \rightarrow \mathcal{O} \dots$$

carried by Δ

Quasi-Consensus

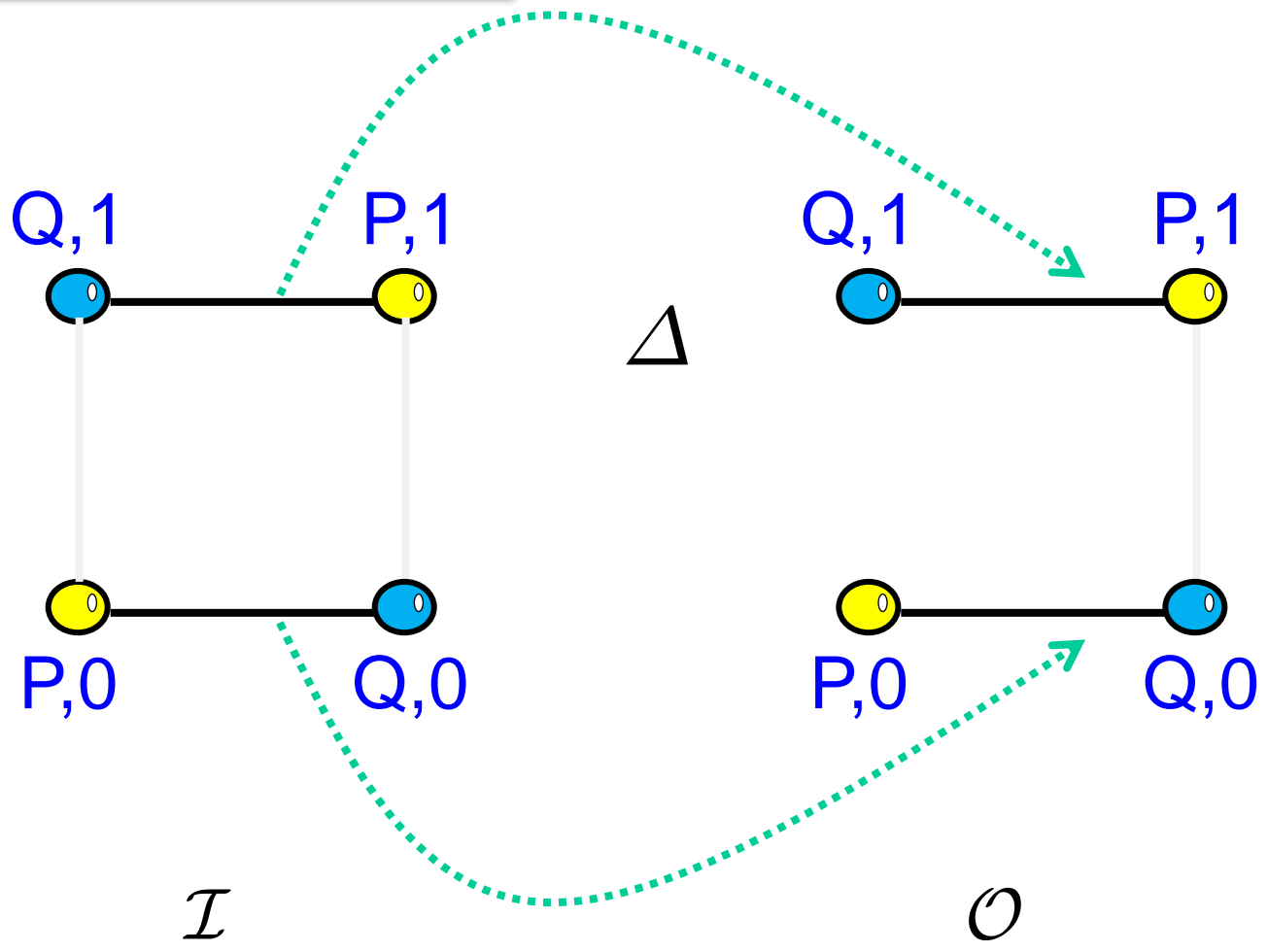


\mathcal{I}

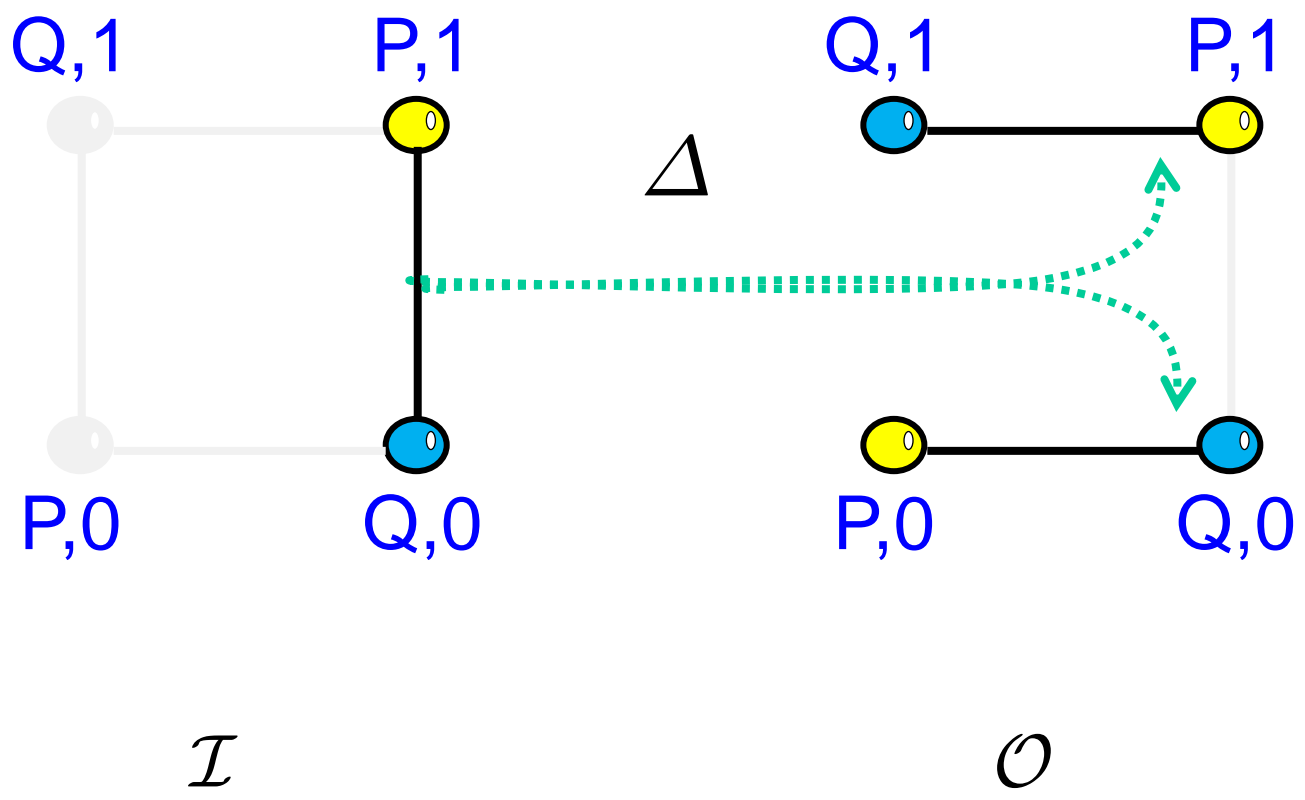


\mathcal{O}

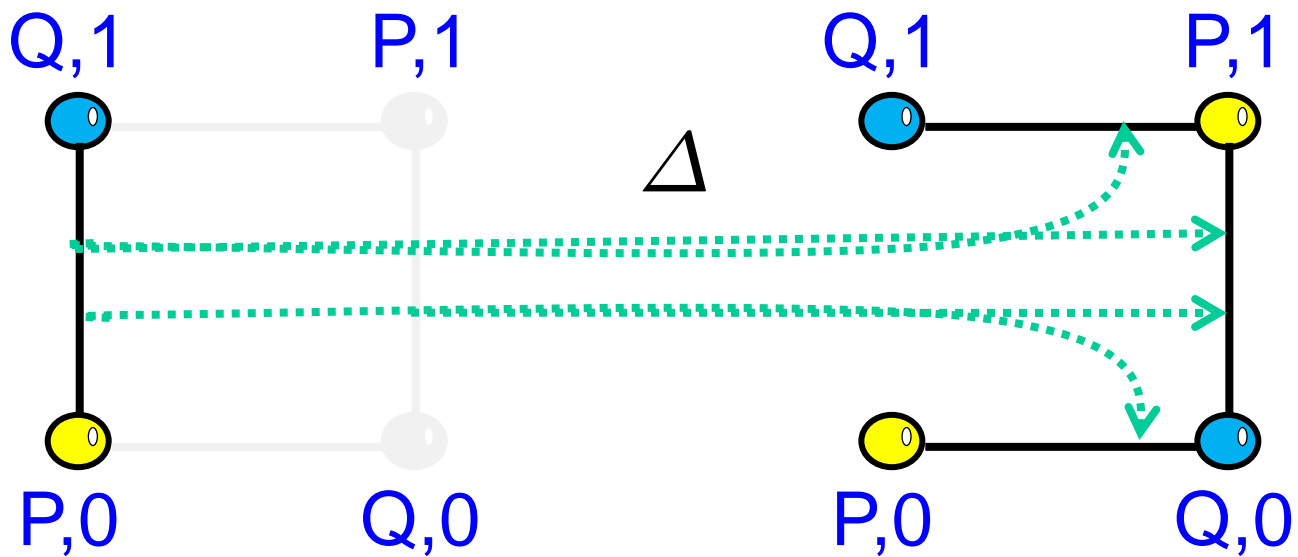
Quasi-Consensus



Quasi-Consensus



Quasi-Consensus

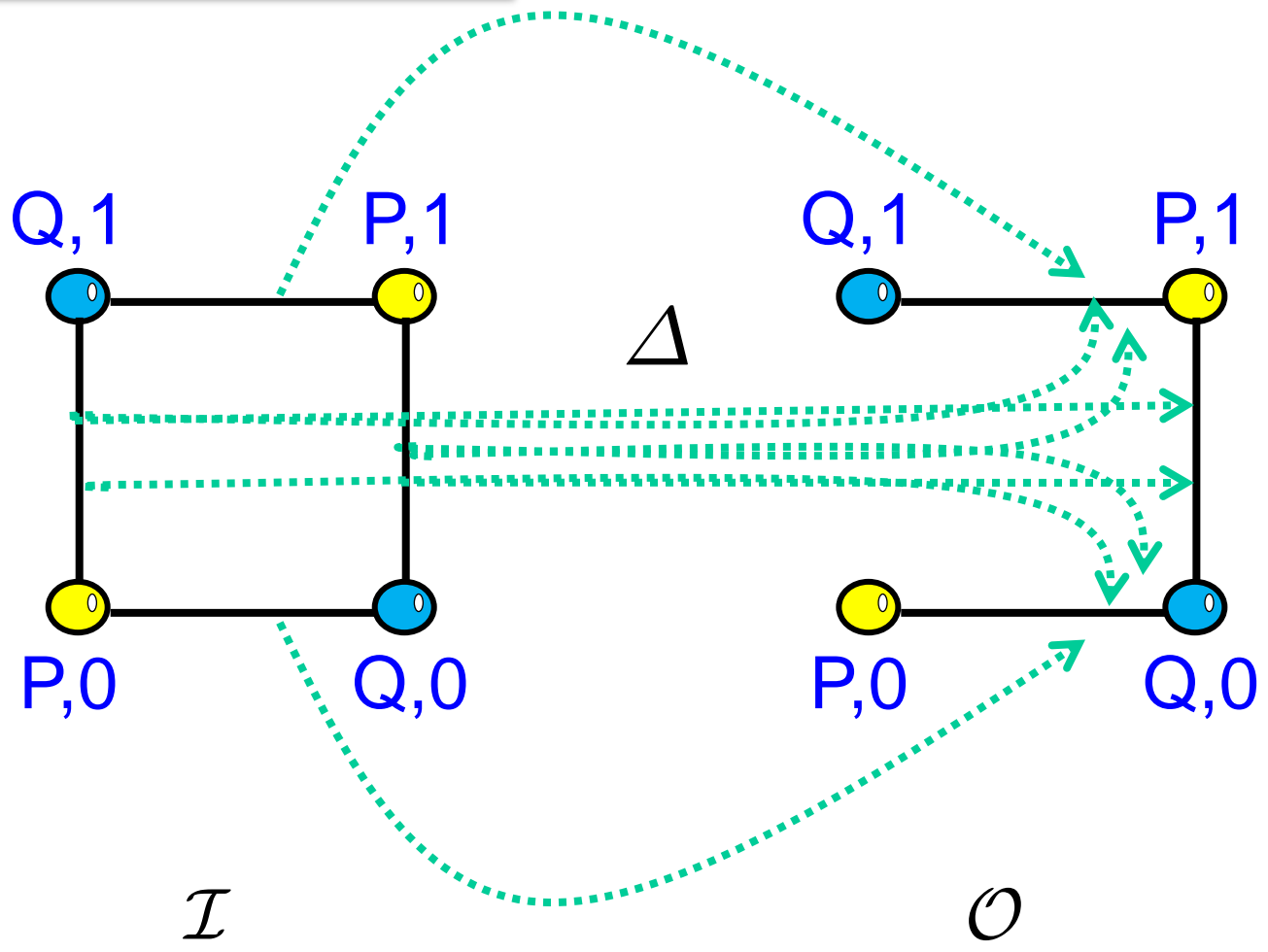


\mathcal{I}

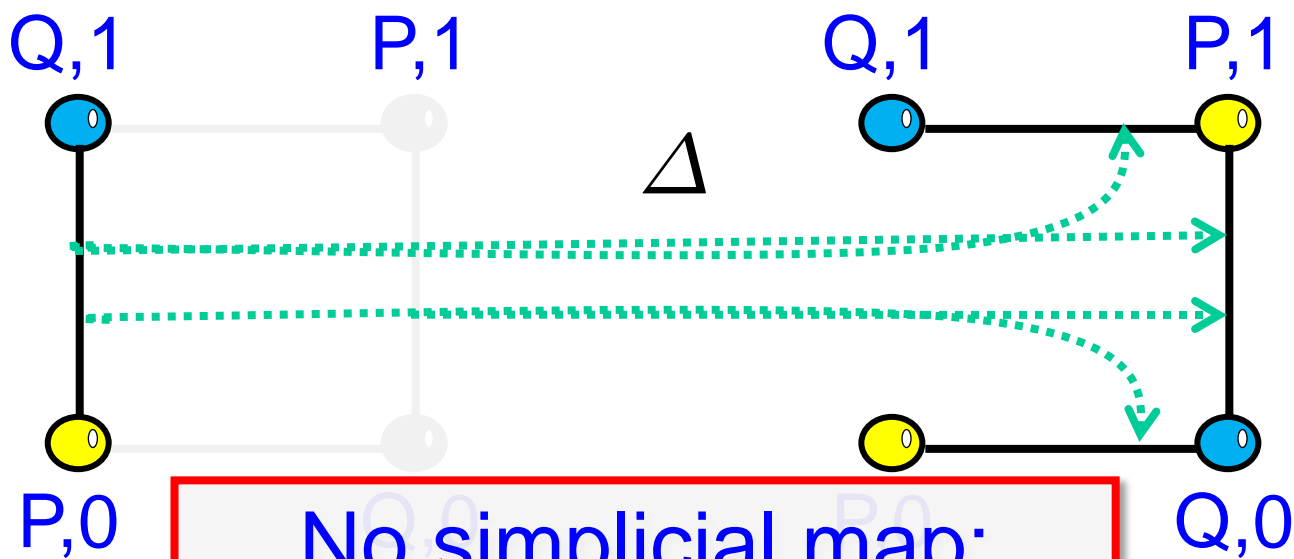
\mathcal{O}

Not a colorless task!

Quasi-Consensus



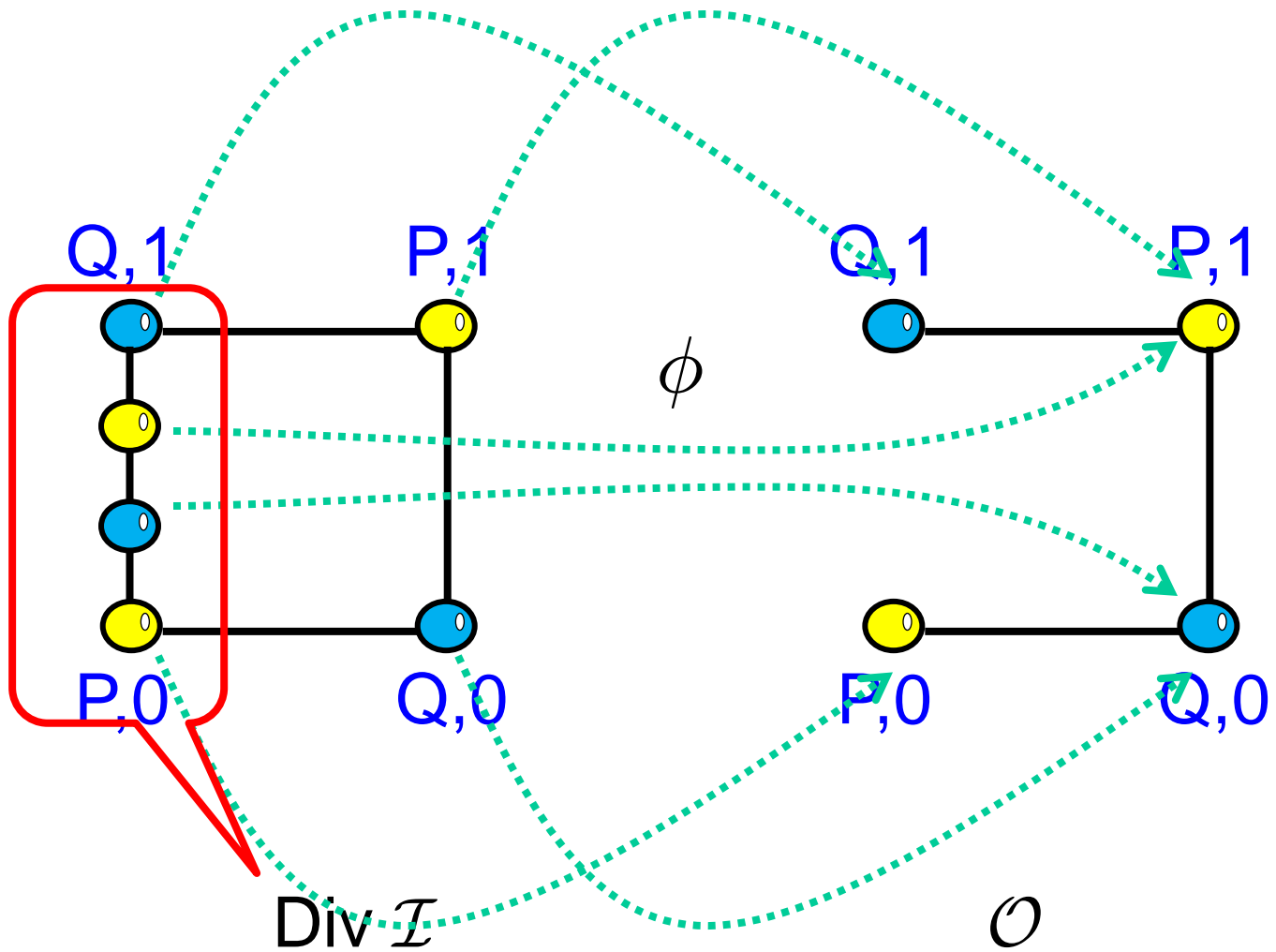
Quasi-Consensus



No simplicial map:

$$\mathcal{I} \rightarrow \mathcal{O}$$

carried by Δ



Code is asymmetric!

```
// code for P
T decide(T input) {
  announce[P] = input;
  if (input == 1)
    return 1;
  else if (announce[Q] != 1)
    return 0
  else
    return 1
}
```

```
// code for Q
T decide(T input) {
  announce[P] = input;
  if (input == 0)
    return 0;
  else if (announce[P] != 0)
    return 1
  else
    return 0
}
```

Road Map

Inherently colored tasks

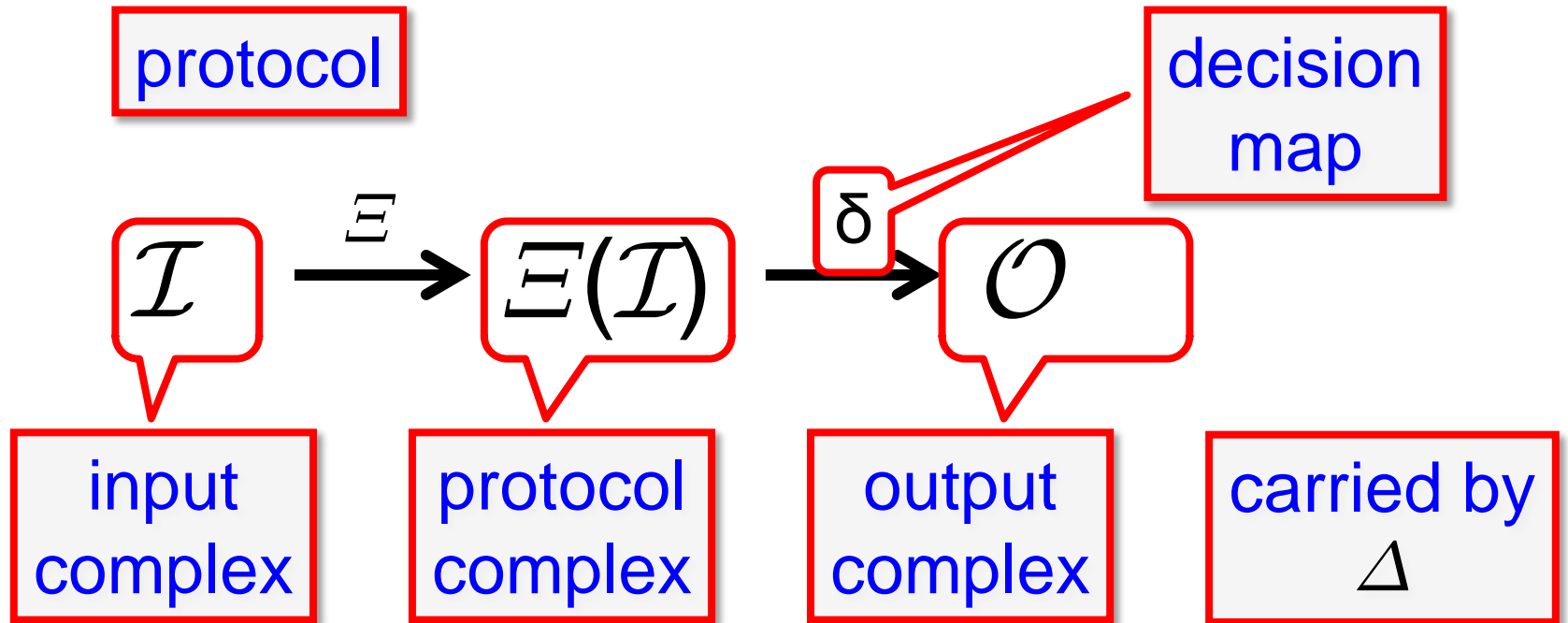
Solvability for colored tasks

Protocol \Rightarrow map

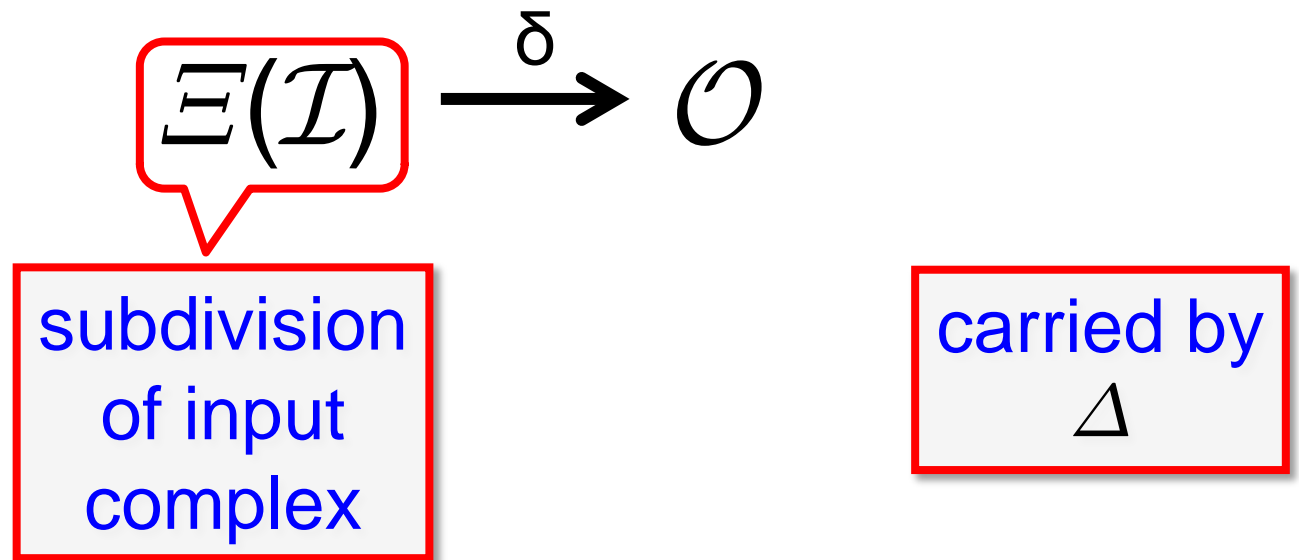
Map \Rightarrow protocol

A Sufficient Topological Conditions

Protocol \Rightarrow Map



Protocol \Rightarrow Map



Road Map

Inherently colored tasks

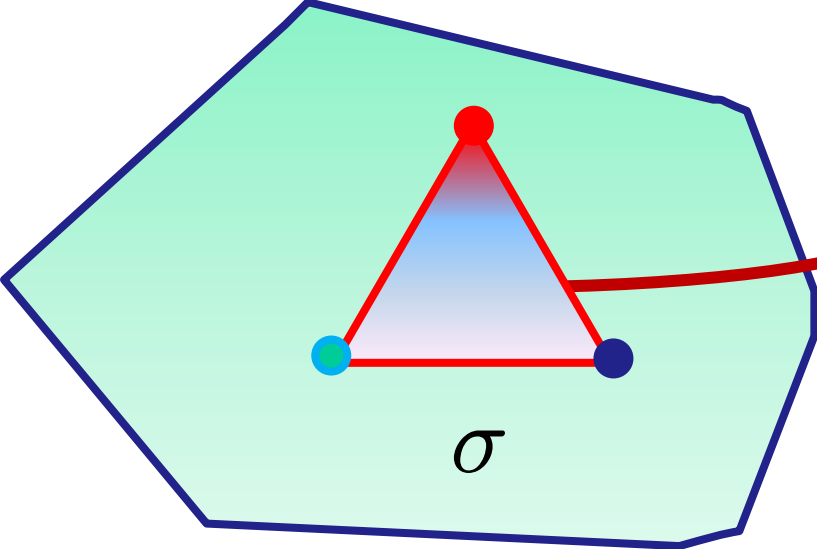
Solvability for colored tasks

Protocol \Rightarrow map

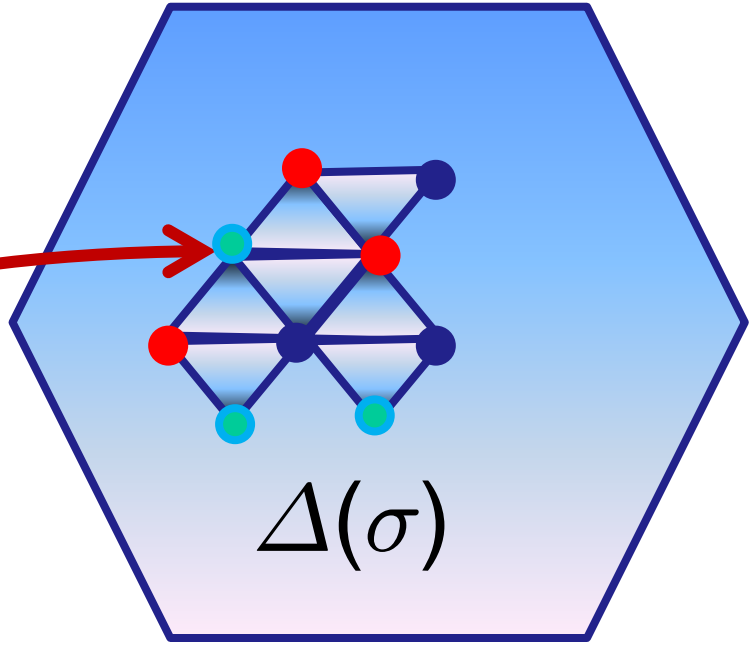
Map \Rightarrow protocol

A Sufficient Topological Conditions

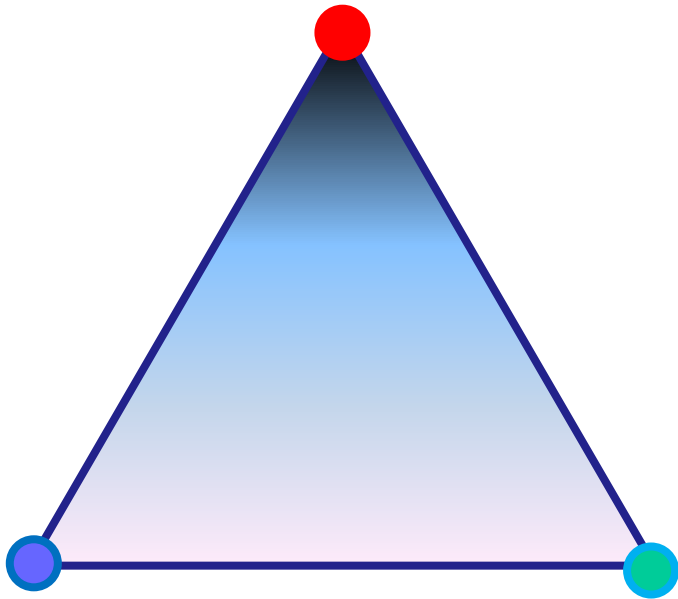
Task $(\mathcal{I}, \mathcal{O}, \Delta)$



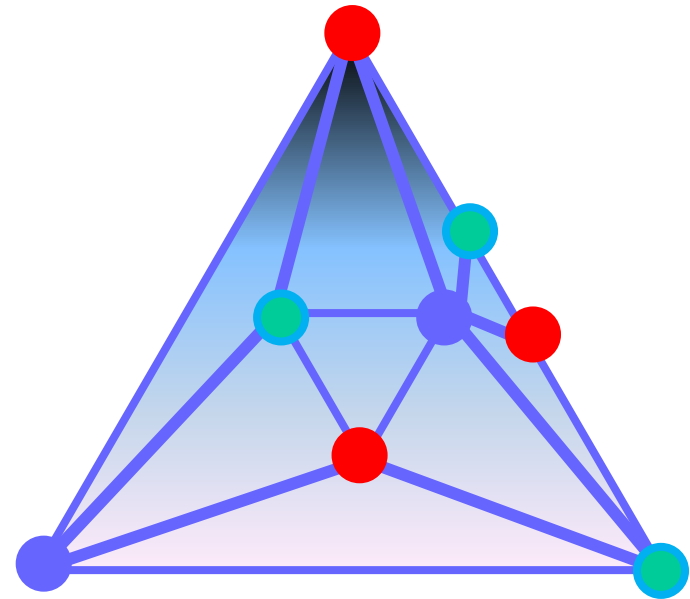
\mathcal{I}



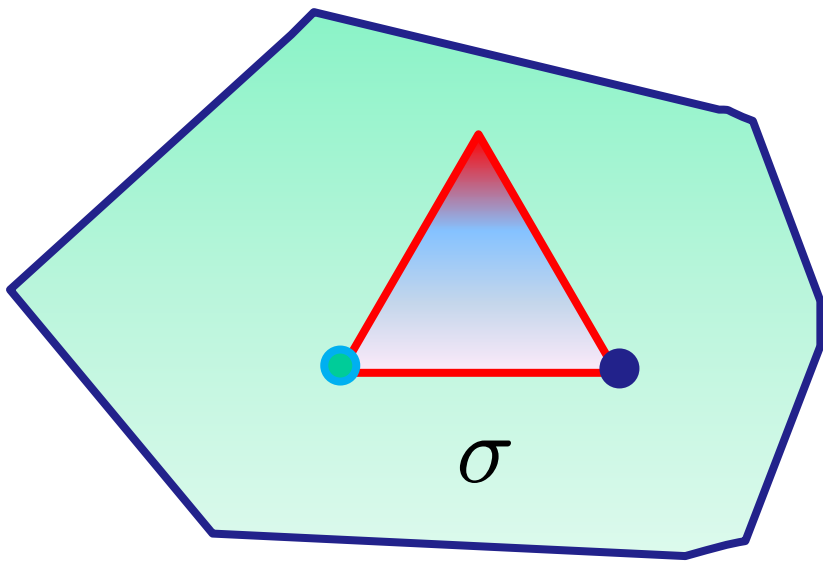
\mathcal{O}



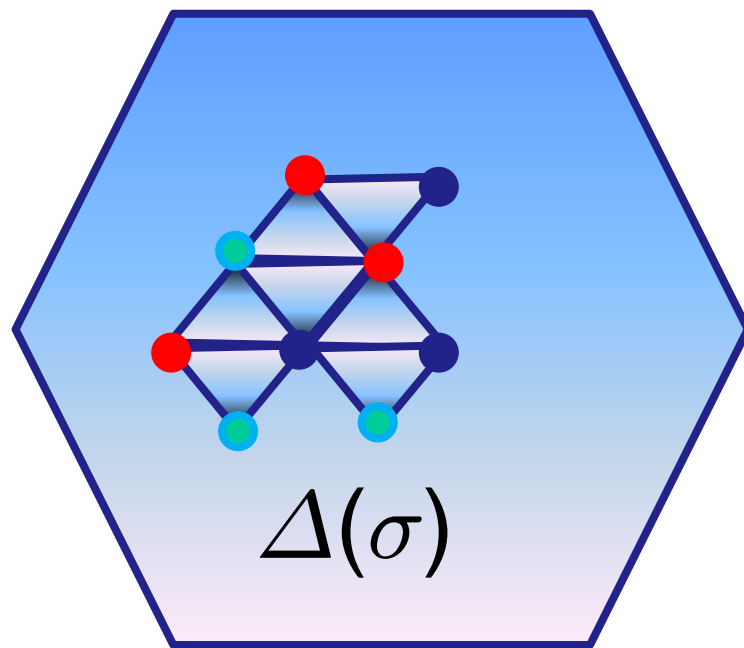
chromatic simplex σ



chromatic subdivision $\text{Div } \sigma$



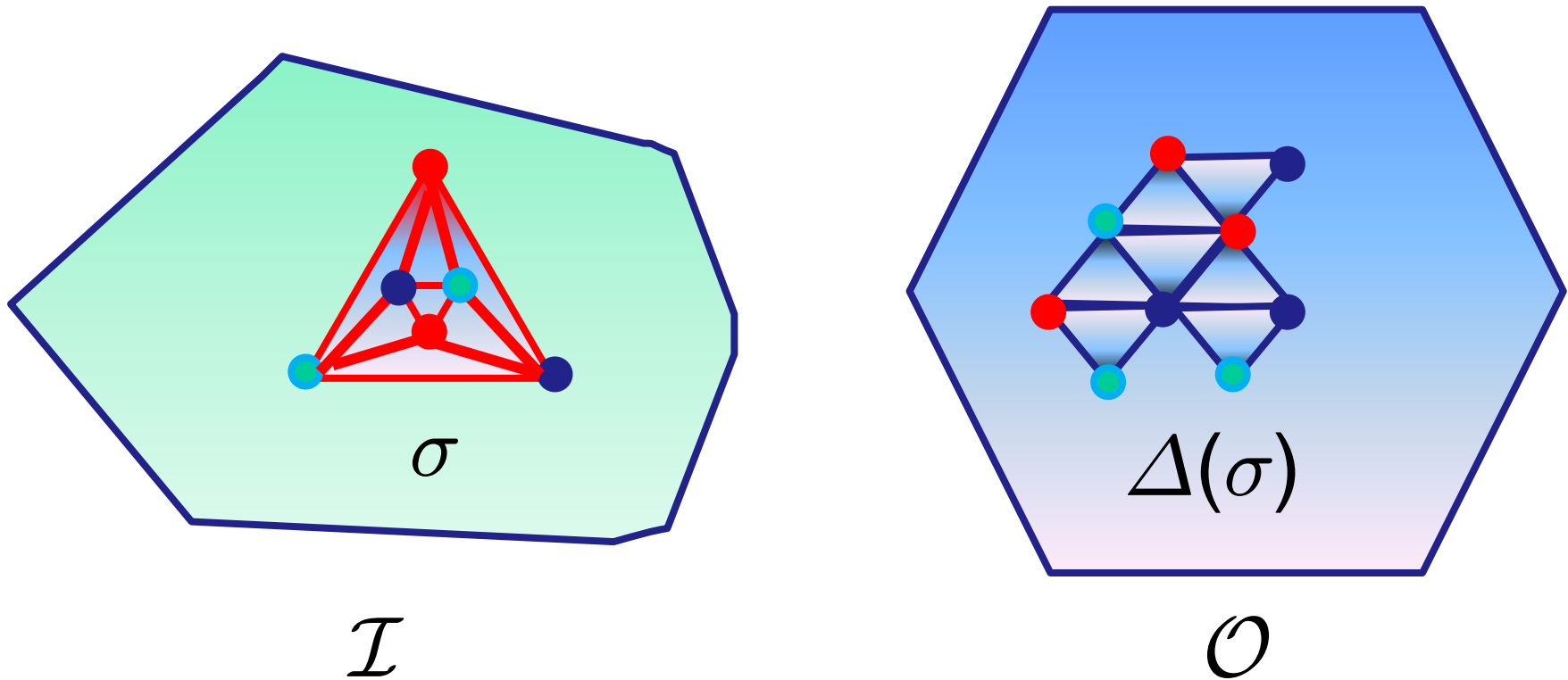
\mathcal{I}



\mathcal{O}

Theorem says ...

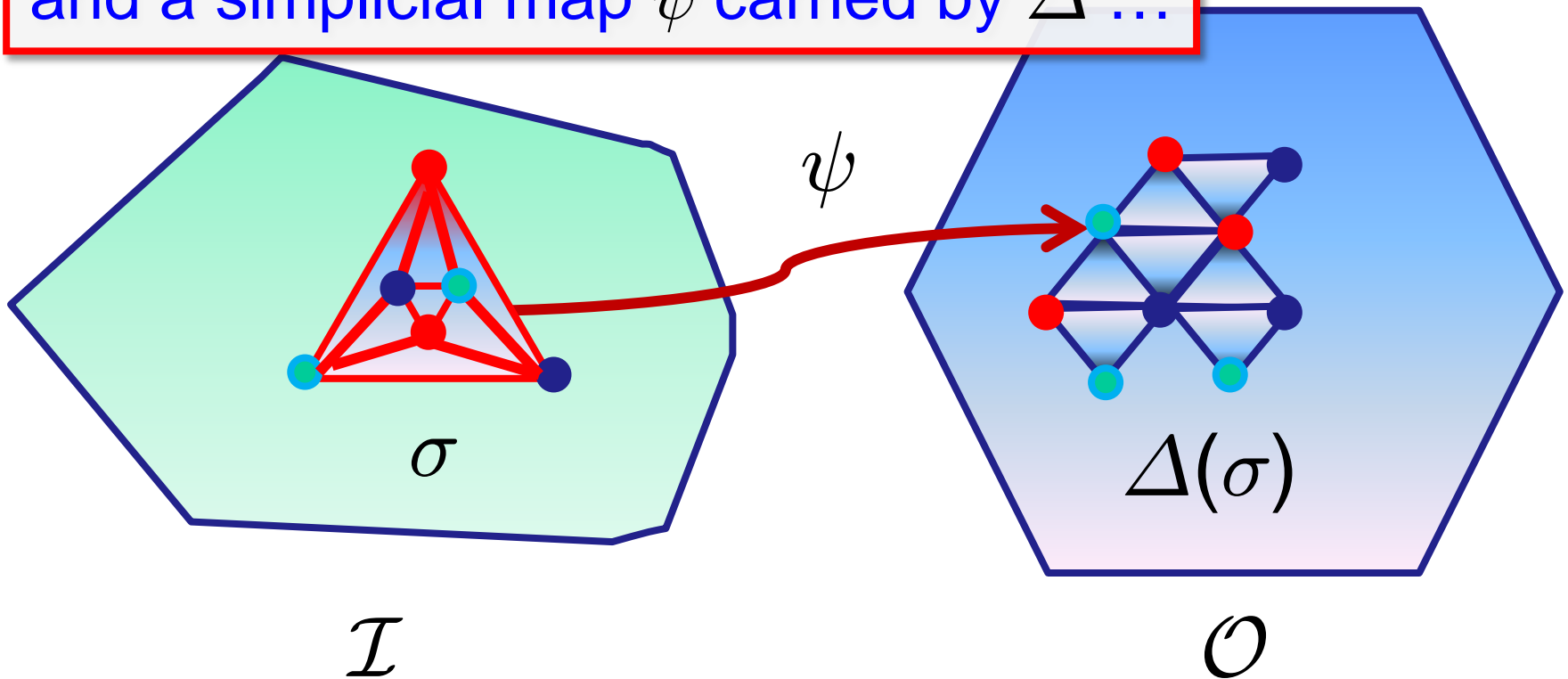
If there is a chromatic subdivision ...



Theorem says ...

If there is a chromatic subdivision ...

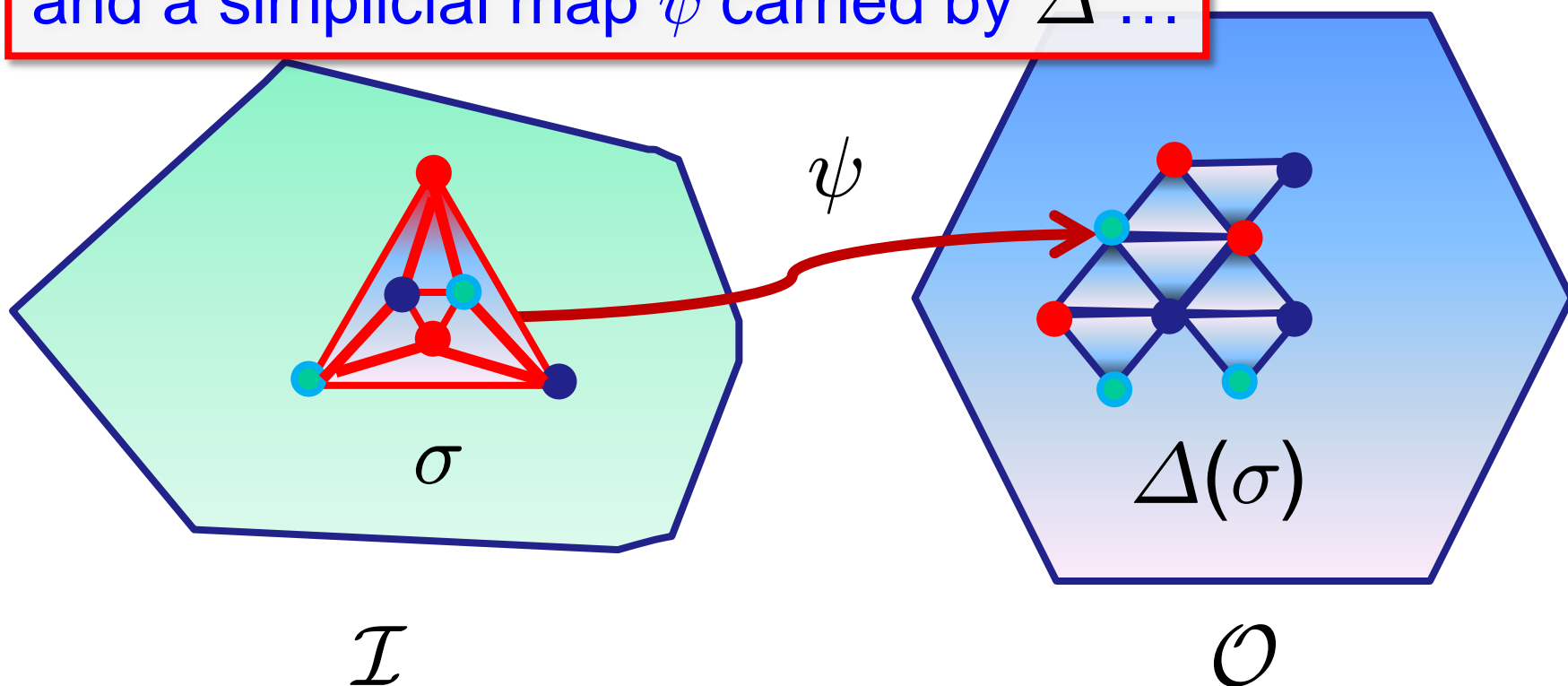
and a simplicial map ψ carried by Δ ...



Theorem says ...

If there is a chromatic subdivision ...

and a simplicial map ψ carried by Δ ...

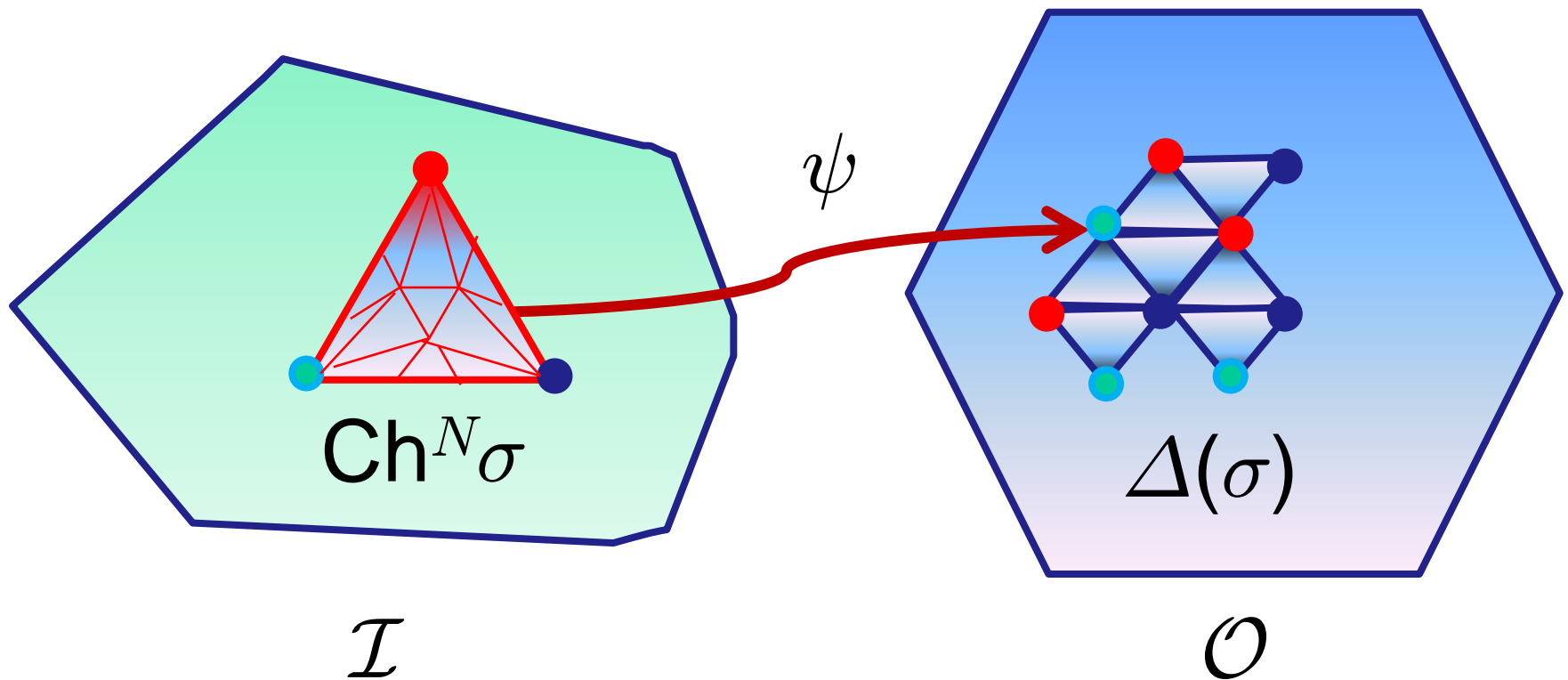


... then there is a wait-free IS protocol!

Let's start with something easier ...

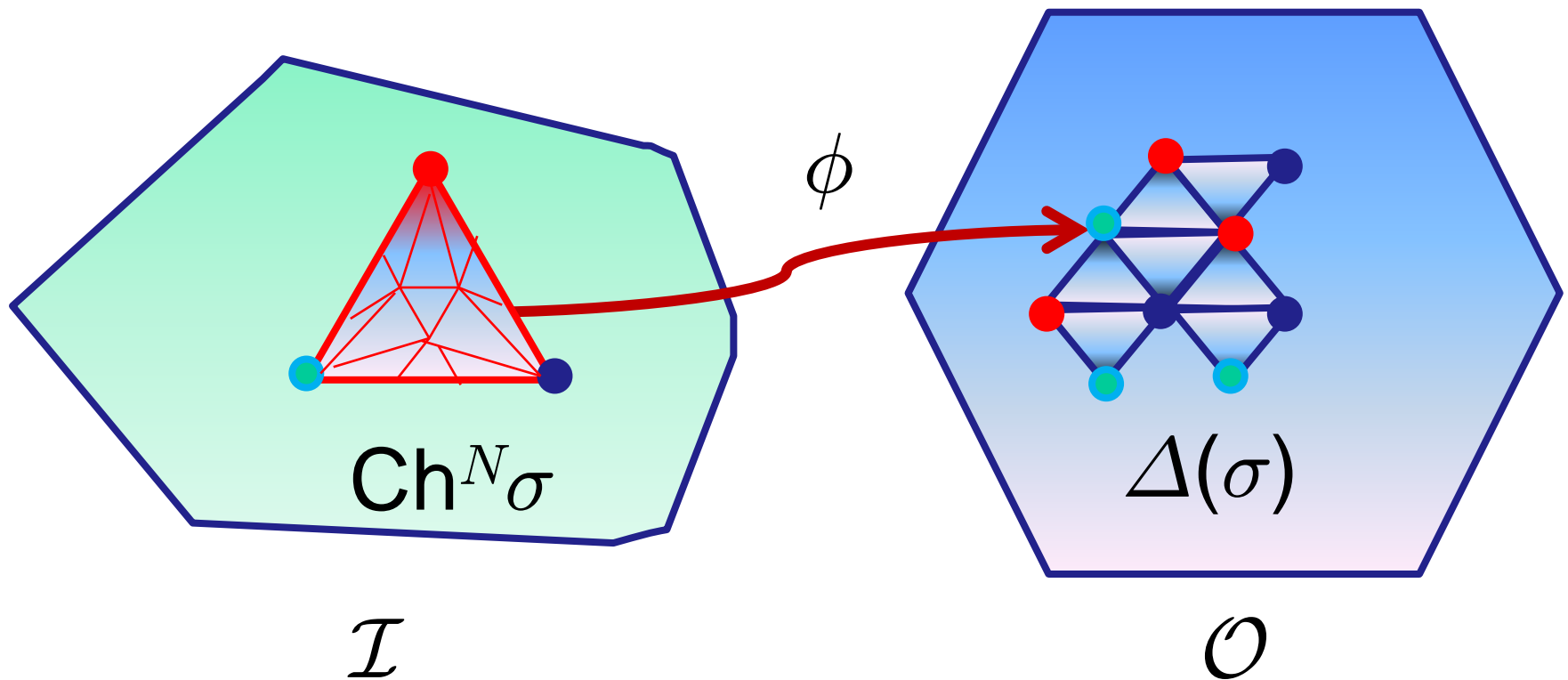
Let's start with a special case ...

If there is a simplicial map $\psi: \text{Ch}^N \sigma \rightarrow \Delta(\sigma) \dots$



Let's start with something easier ...

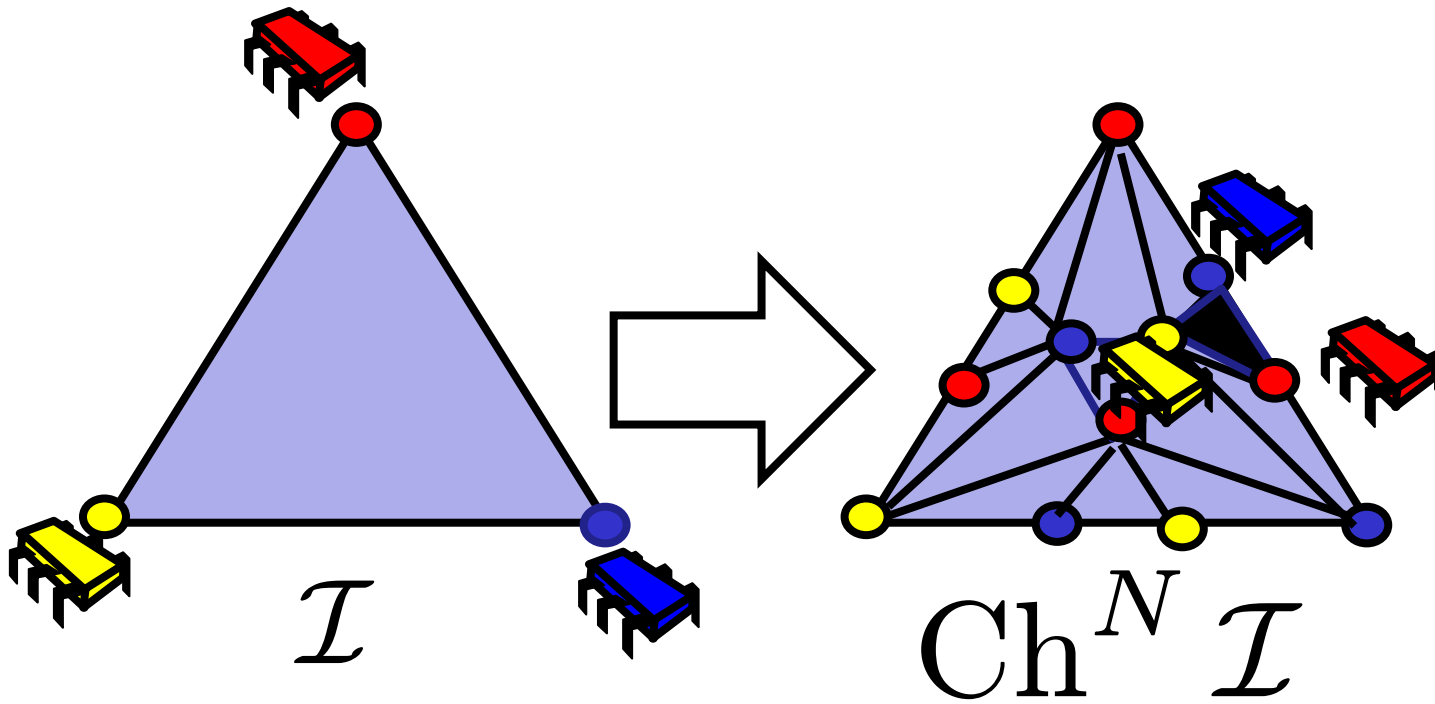
If there is a simplicial map $\phi: \text{Ch}^N \sigma \rightarrow \Delta(\sigma) \dots$



... then there is a wait-free IS protocol!

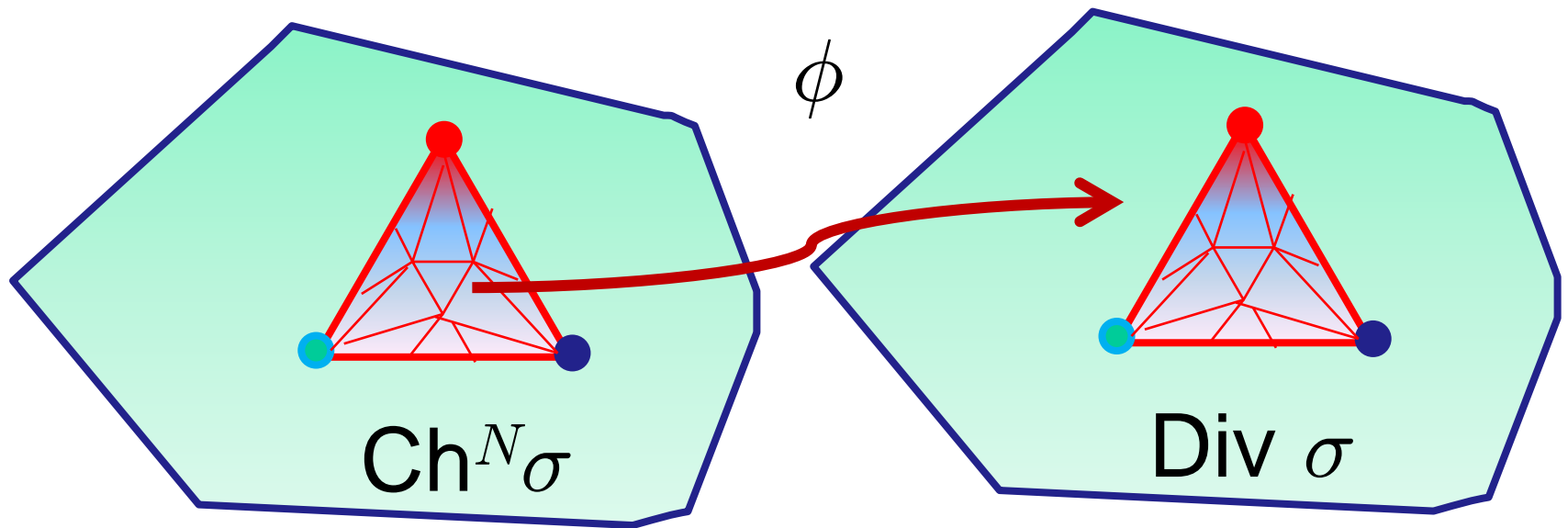
Protocol

Iterated immediate snapshot

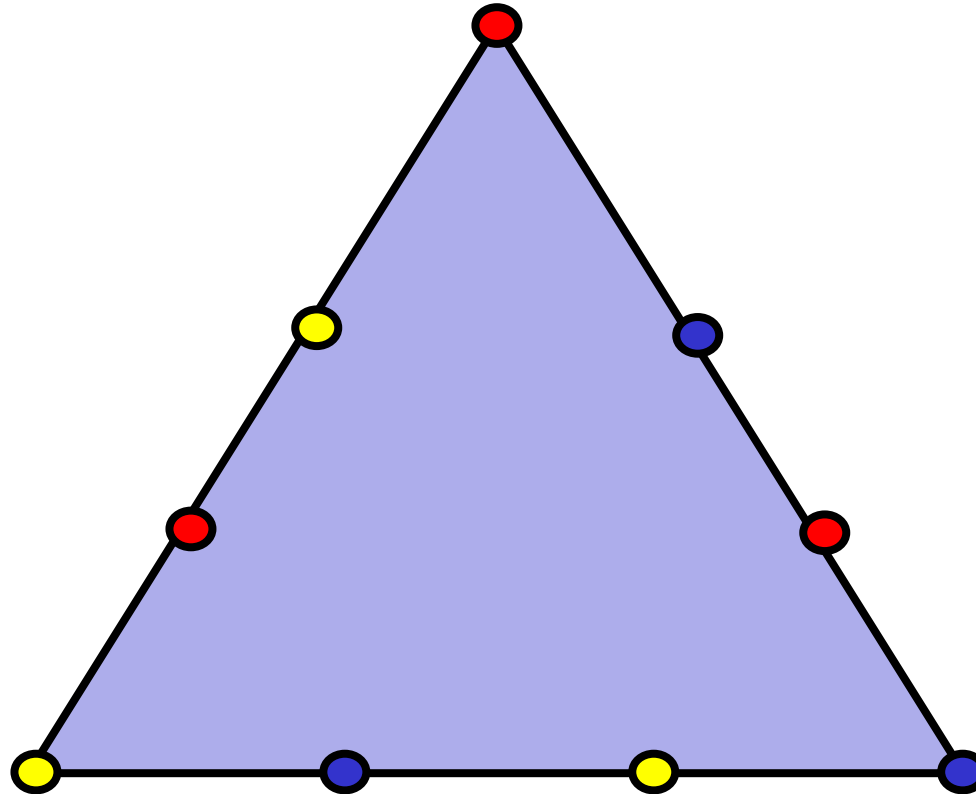


For any chromatic subdivision $\text{Div } \sigma \dots$

If there is a color and carrier-preserving simplicial map $\phi: \text{Ch}^N \sigma \rightarrow \text{Div } \sigma \dots$

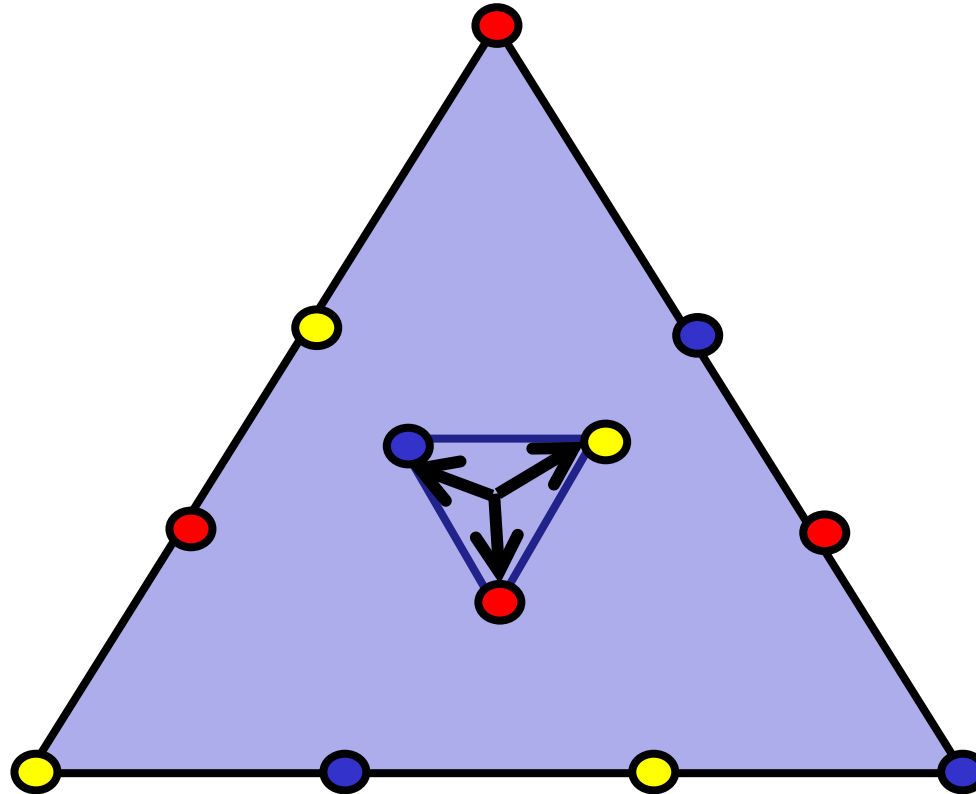


Geometric construction



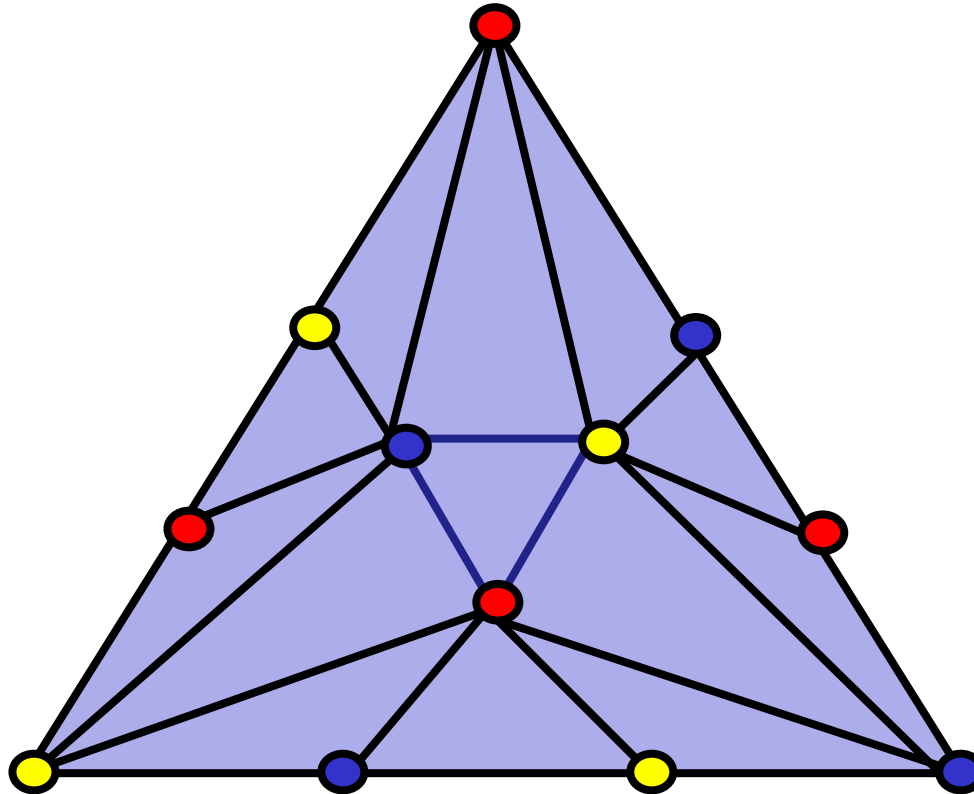
Inductively divide boundary

Geometric construction

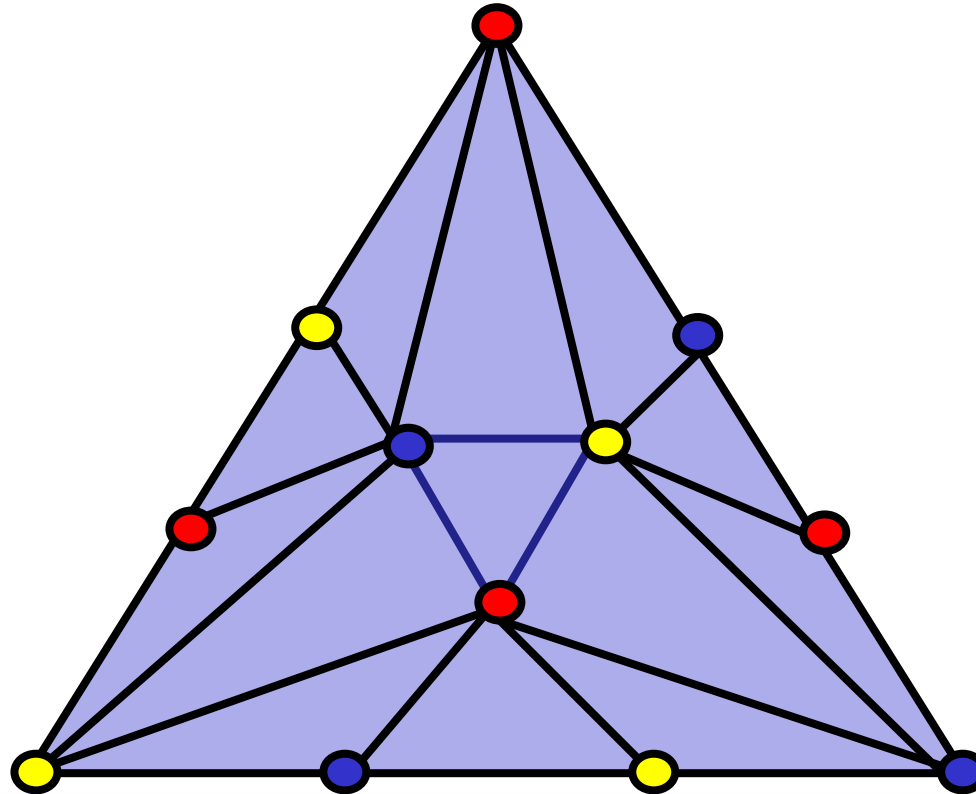


Displace vertices from barycenter

Geometric construction

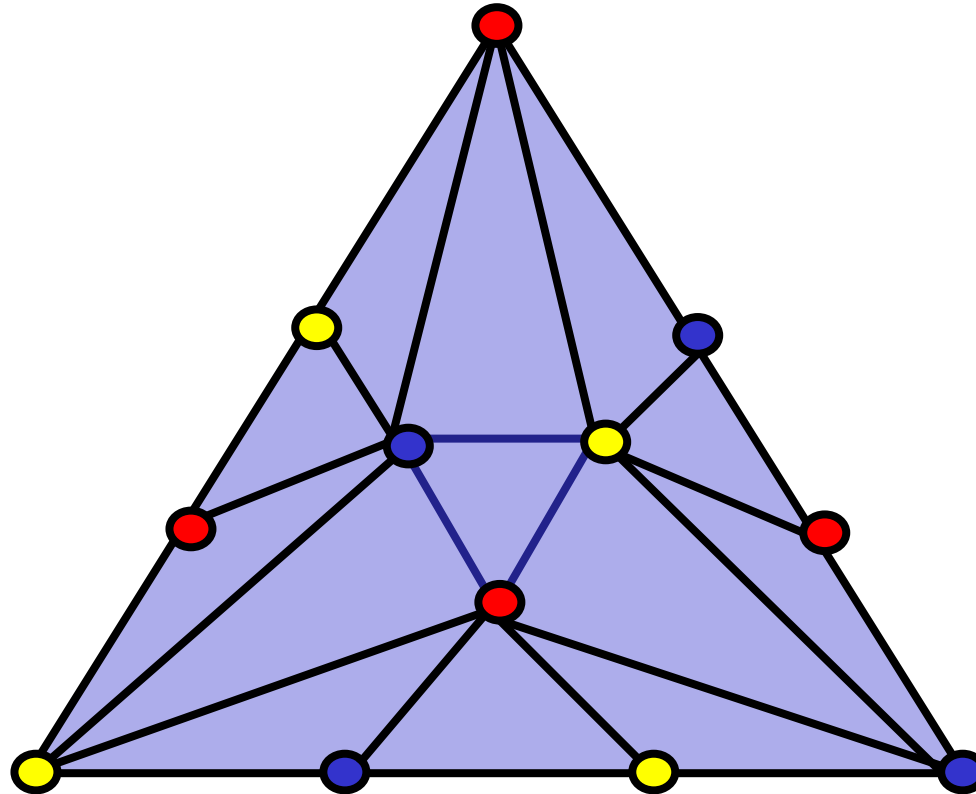


Geometric construction



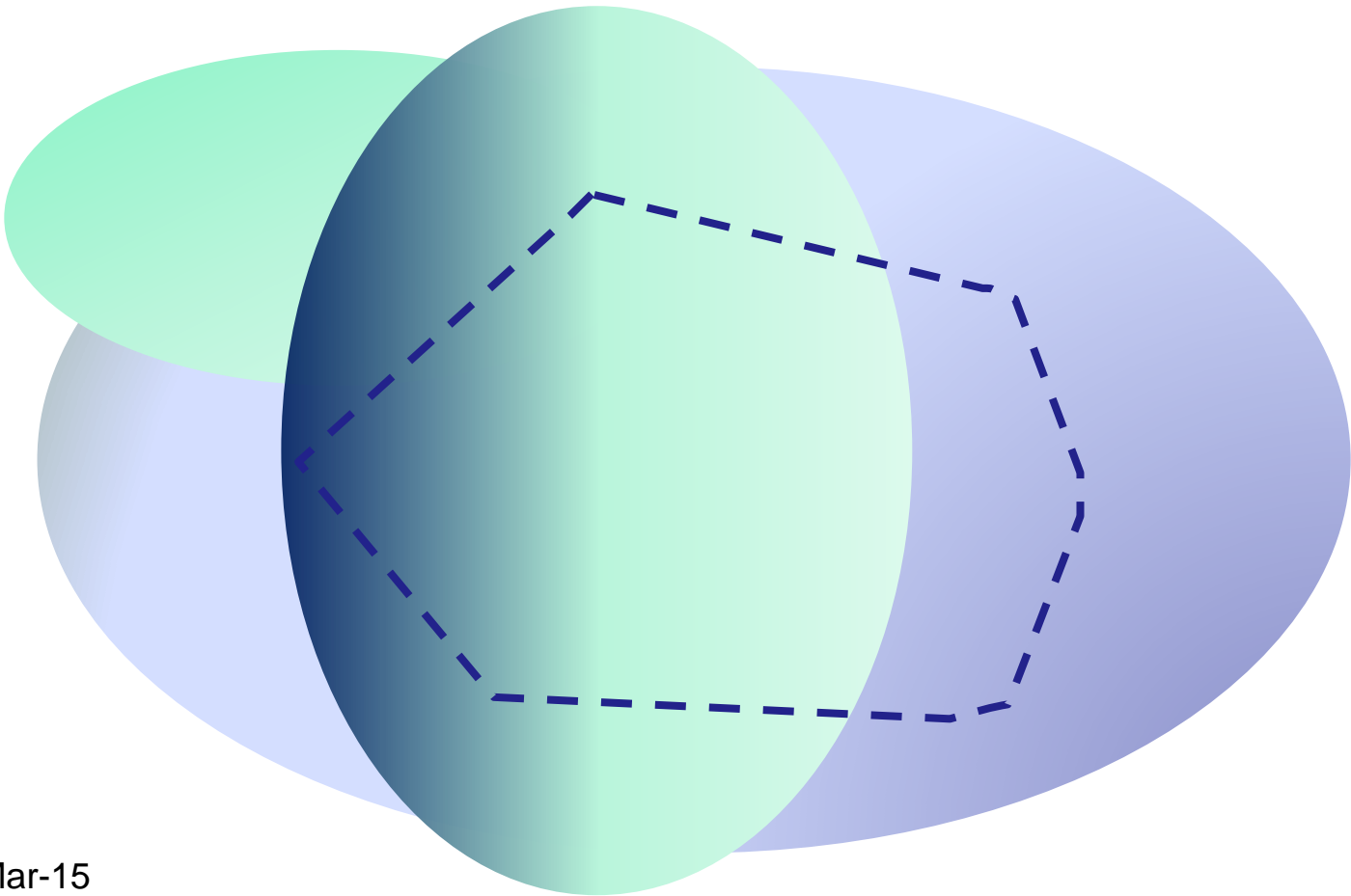
Mesh(Ch σ) is max diameter of a simplex

Subdivision shrinks mesh

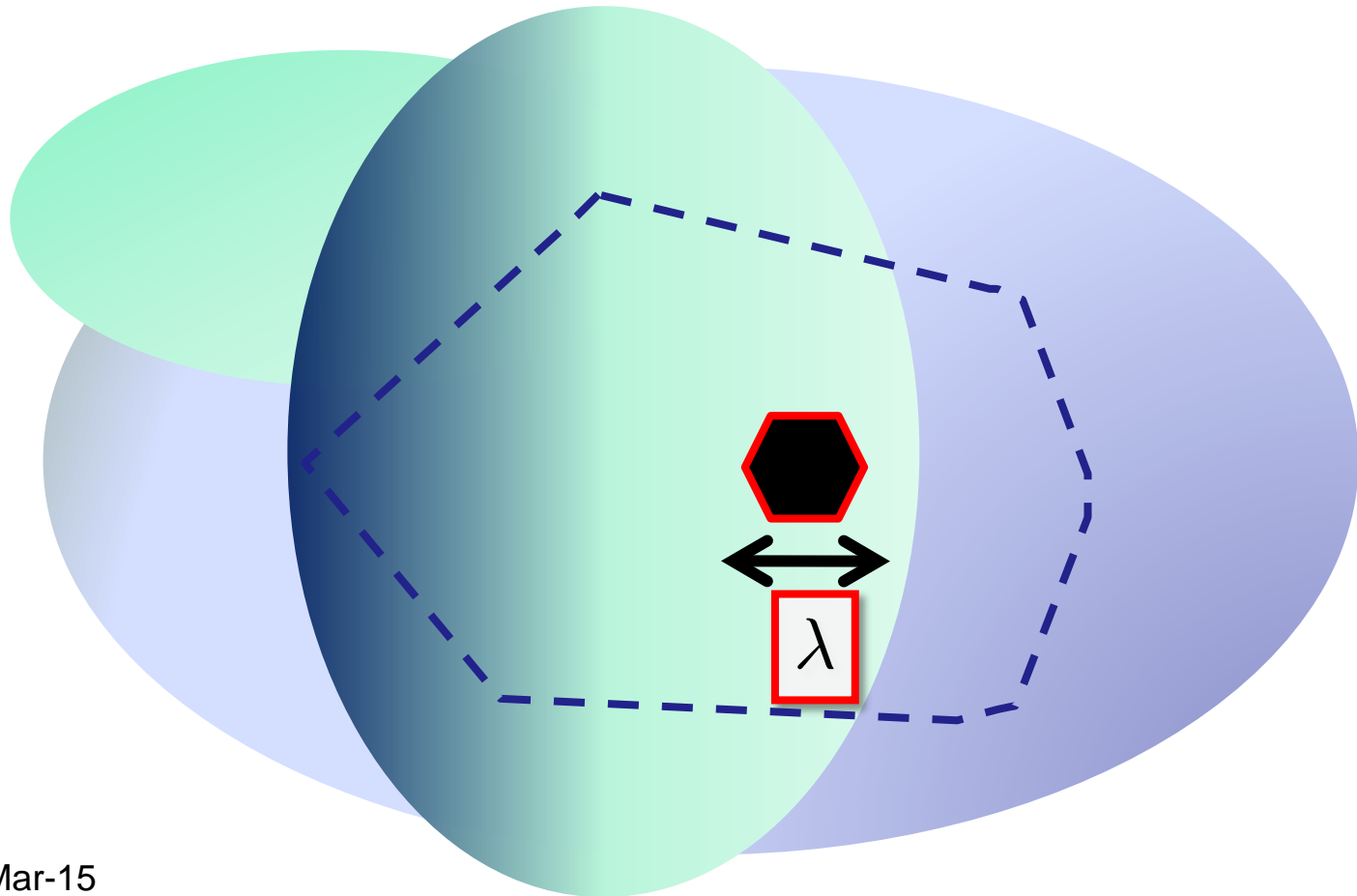


$\text{mesh}(\text{Ch } \sigma) \leq c \text{ mesh}(\sigma)$ for some $0 < c < 1$

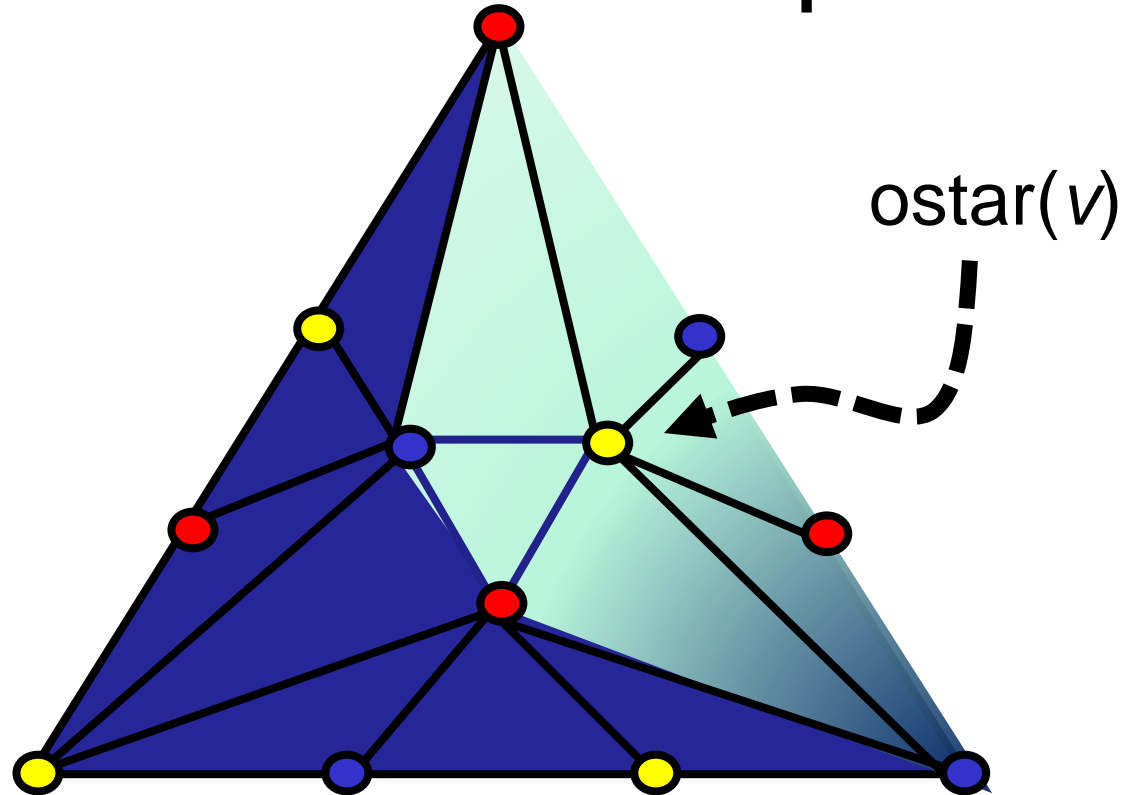
Open cover



Lesbesgue Number

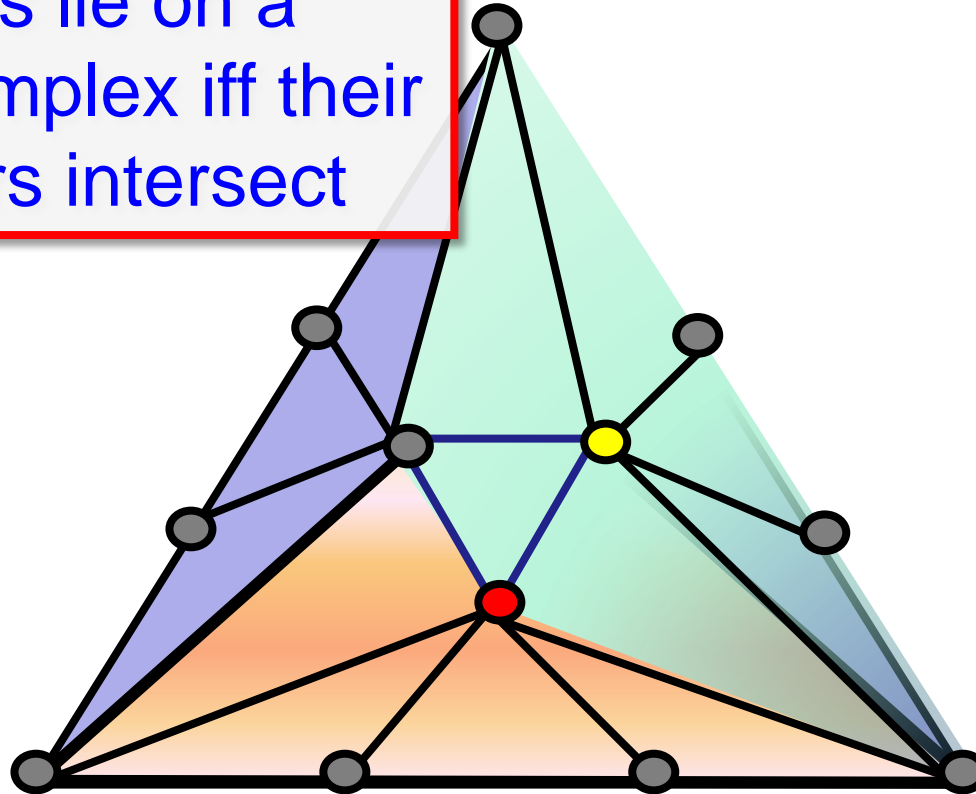


Open stars form an open cover for a complex

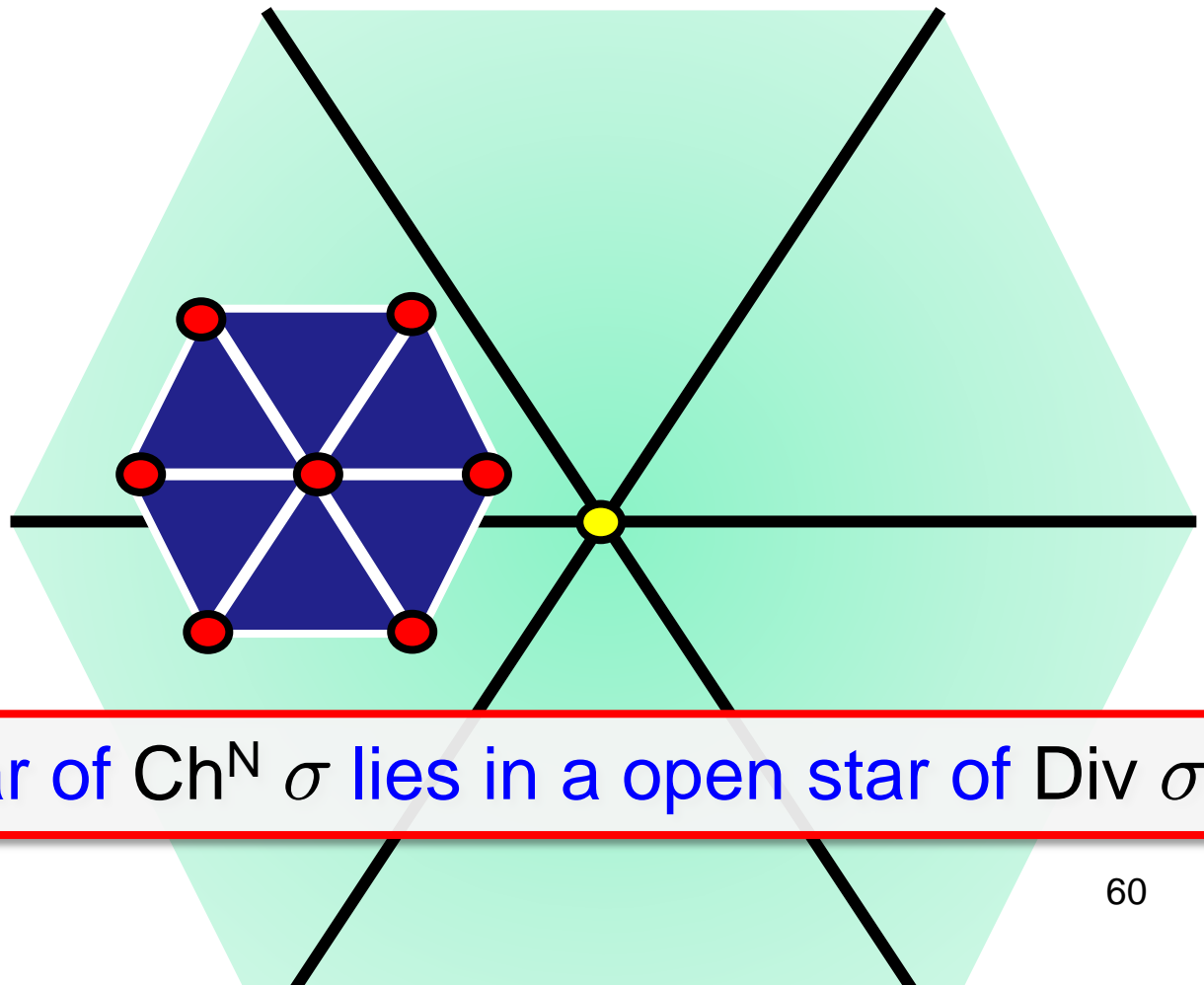


Intersection Lemma

Vertexes lie on a common simplex iff their open stars intersect



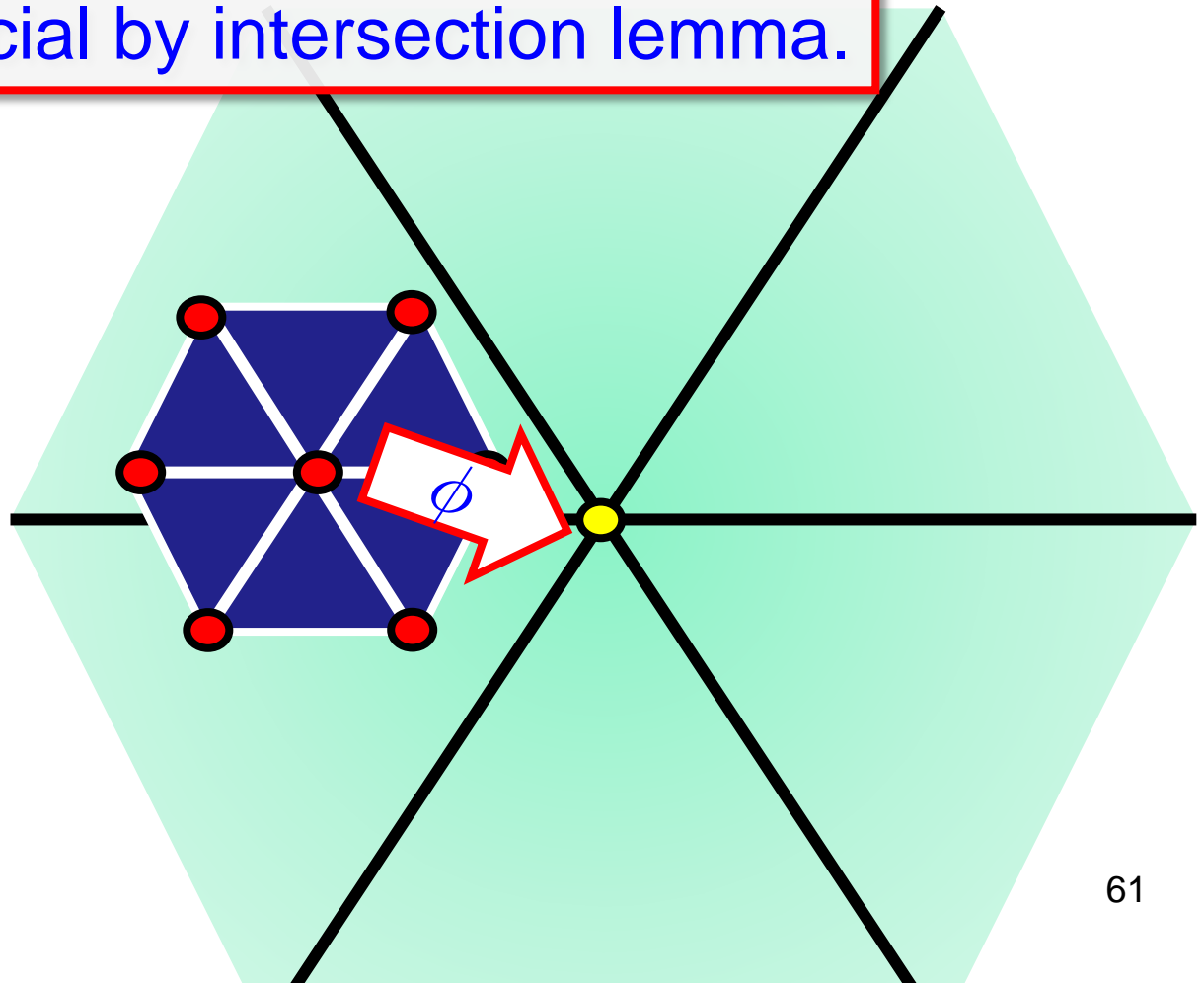
Pick N large enough that each (closed) star of $\text{Ch}^N \sigma$ has diameter less than $\lambda \dots$



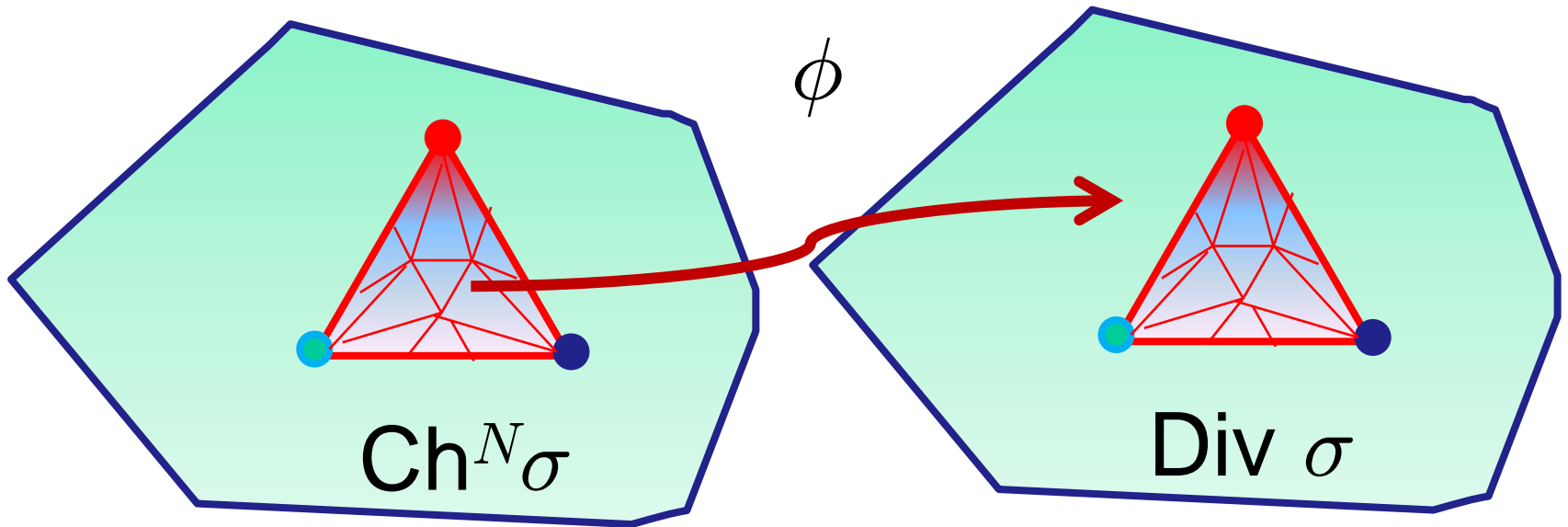
\dots each star of $\text{Ch}^N \sigma$ lies in a open star of $\text{Div } \sigma$

Defines a vertex map

Simplicial by intersection lemma.



We have just proved the
Simplicial Approximation
Theorem

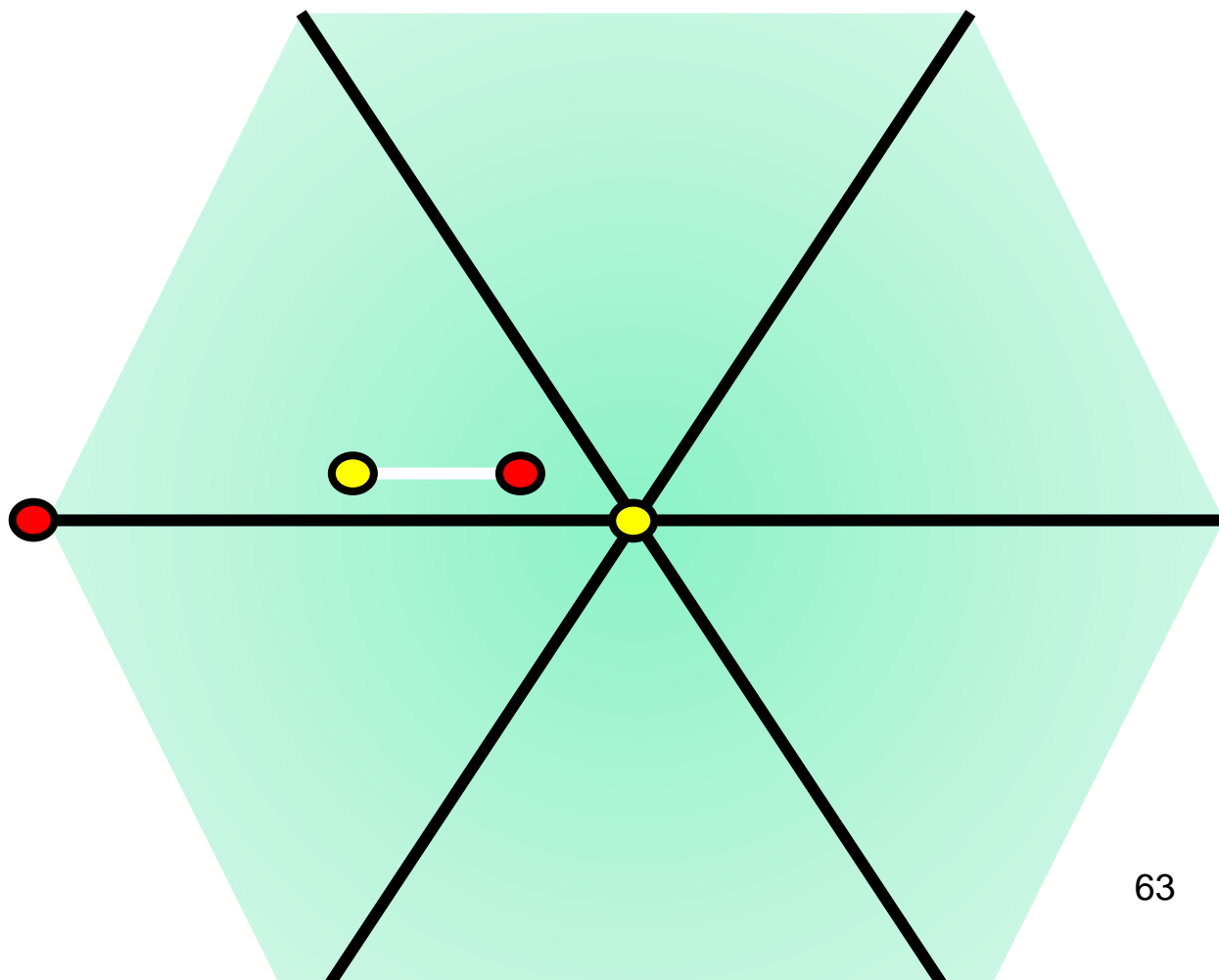


There is a carrier-preserving simplicial map

$$\phi: \text{Ch}^N \sigma \rightarrow \text{Div } \sigma$$

Not necessarily color-preserving!

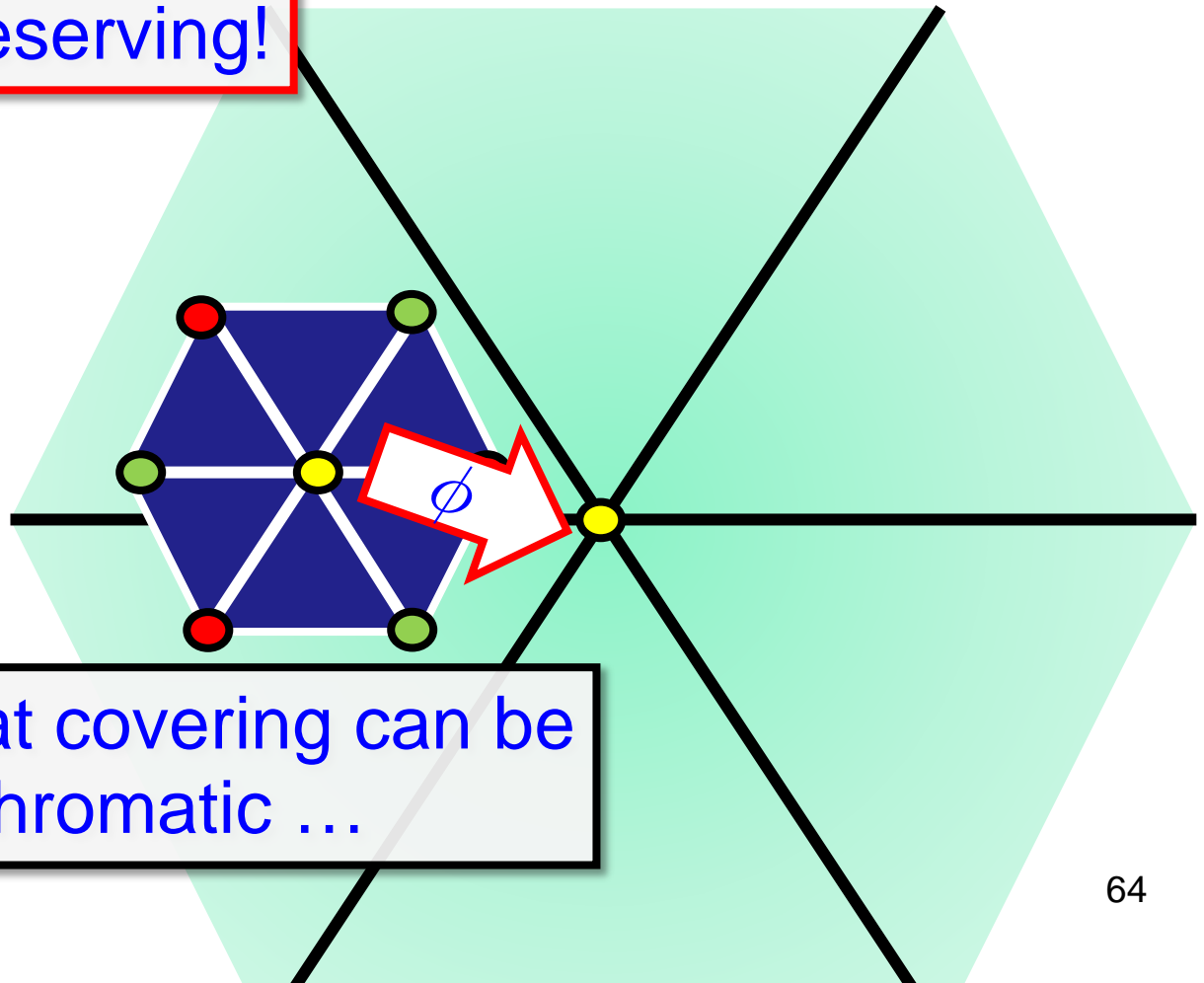
An open-star cover is *chromatic* if every simplex τ of $\text{Ch}^N \sigma$ is covered by open stars of of the same color.



If the open-star cover is chromatic

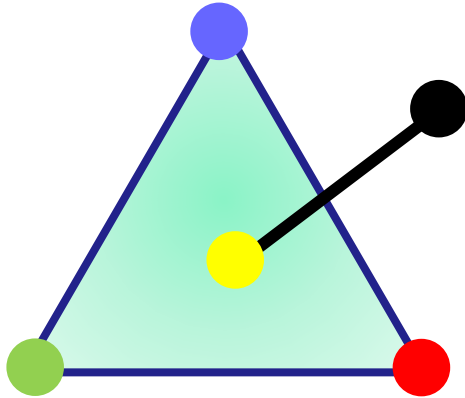
Then the simplicial map

Is color preserving!



Must show that covering can be made chromatic ...

Open Cover Fail



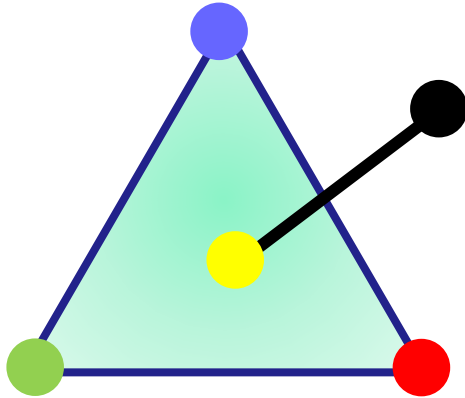
Two simplexes conflict ...

If colors disjoint, but ...

polyhedrons overlap.

cannot map to same color

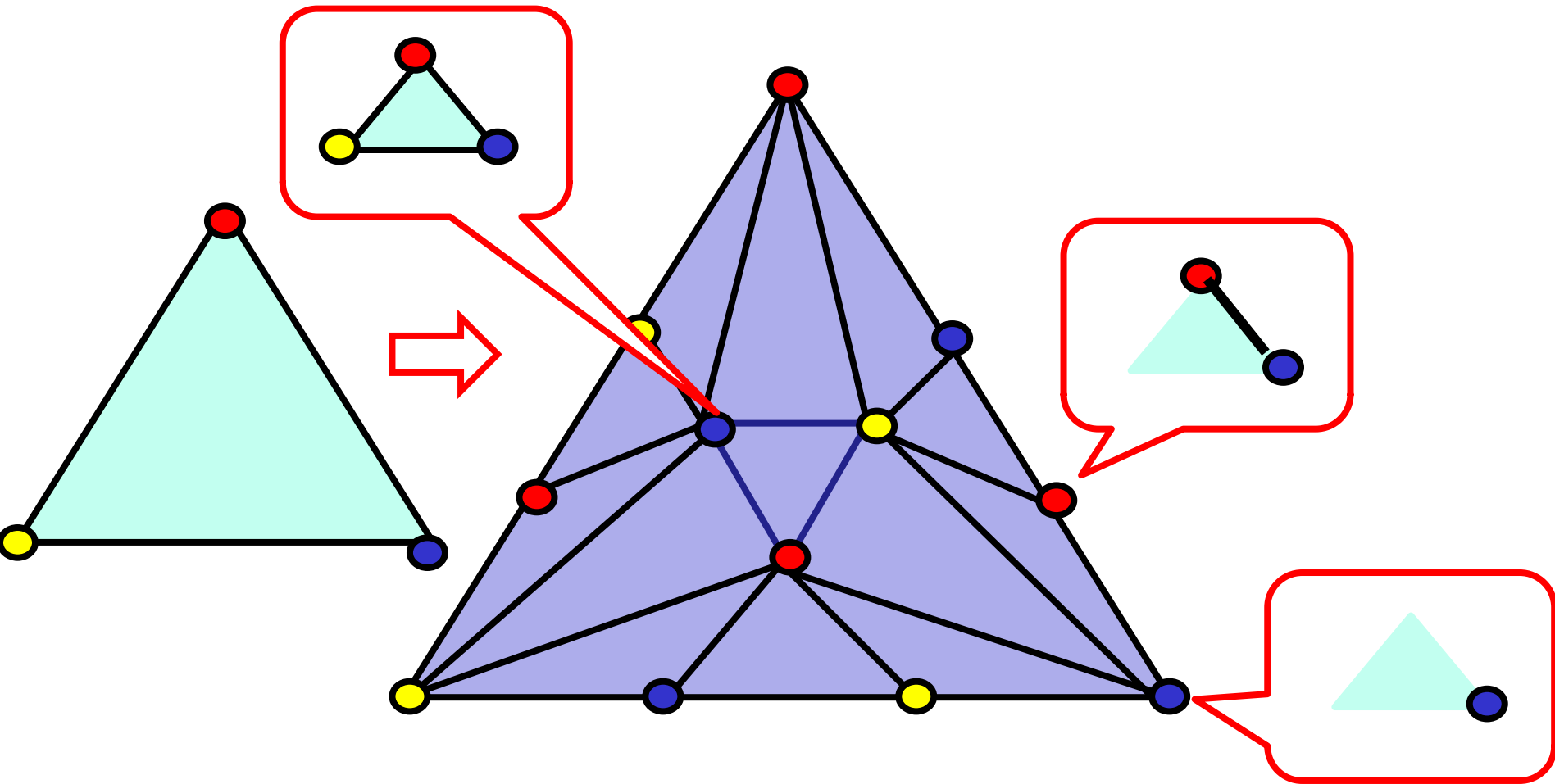
Open Cover Fail



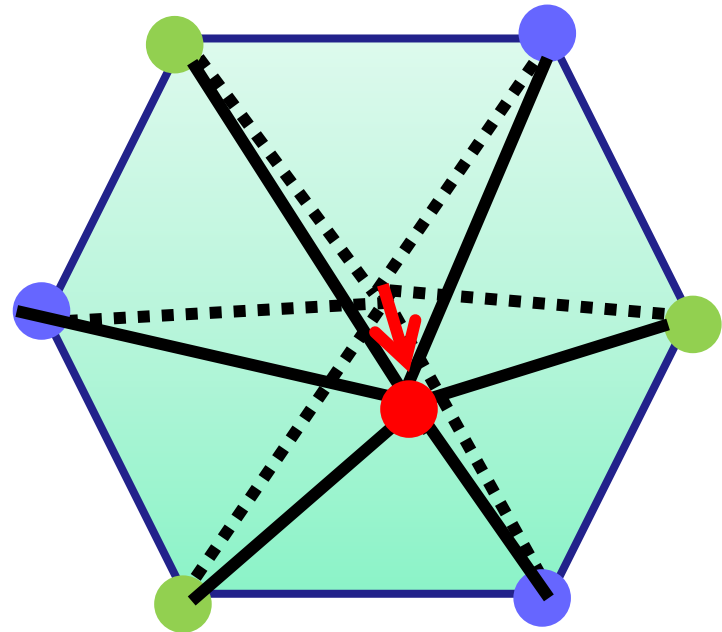
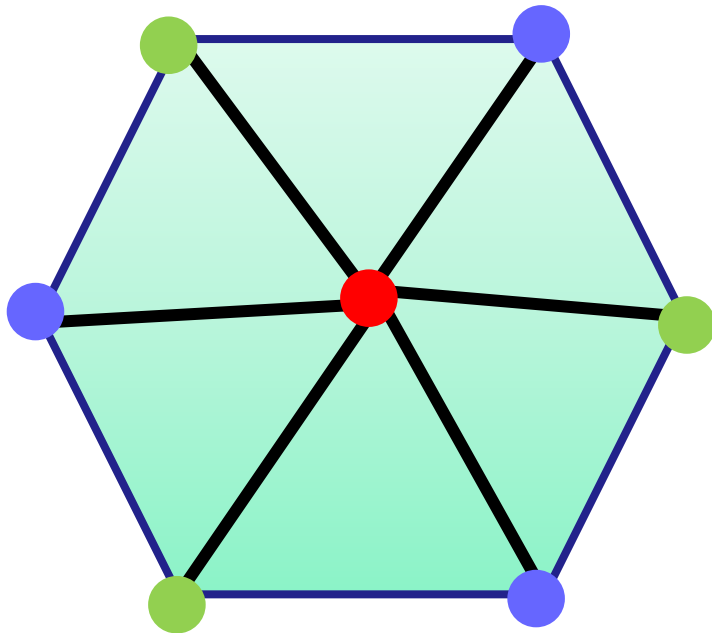
An open-star cover is chromatic iff there are no conflicting simplexes.

We will show how to eliminate conflicting simplexes

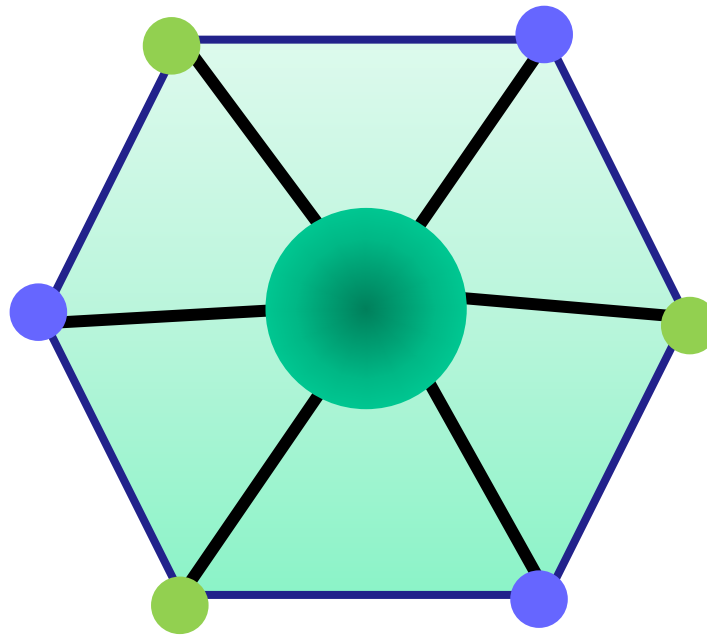
Carriers



Perturbation

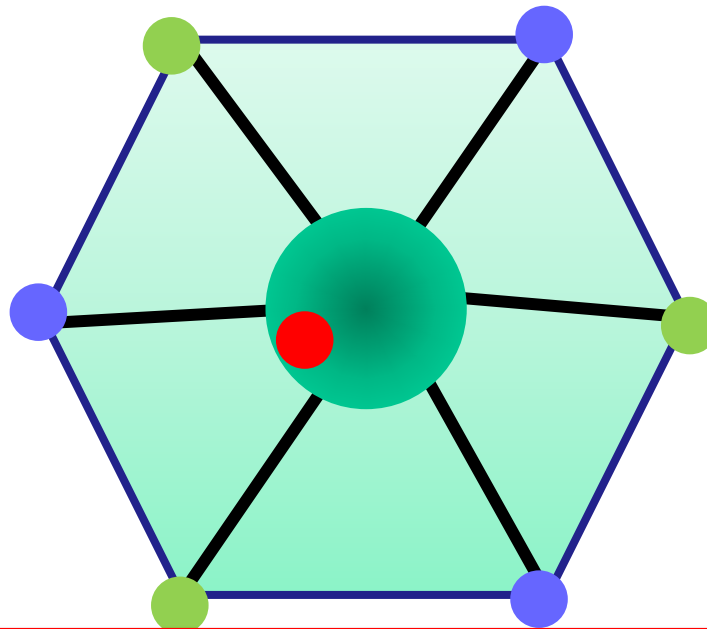


Room for perturbation



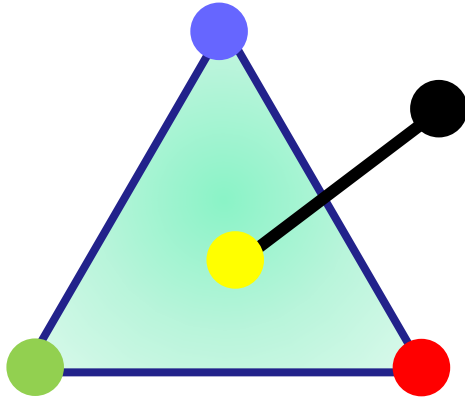
Star contains ϵ ball in carrier around vertex

Room for perturbation



Can perturb to any point within
 ϵ ball in carrier and still have
subdivision

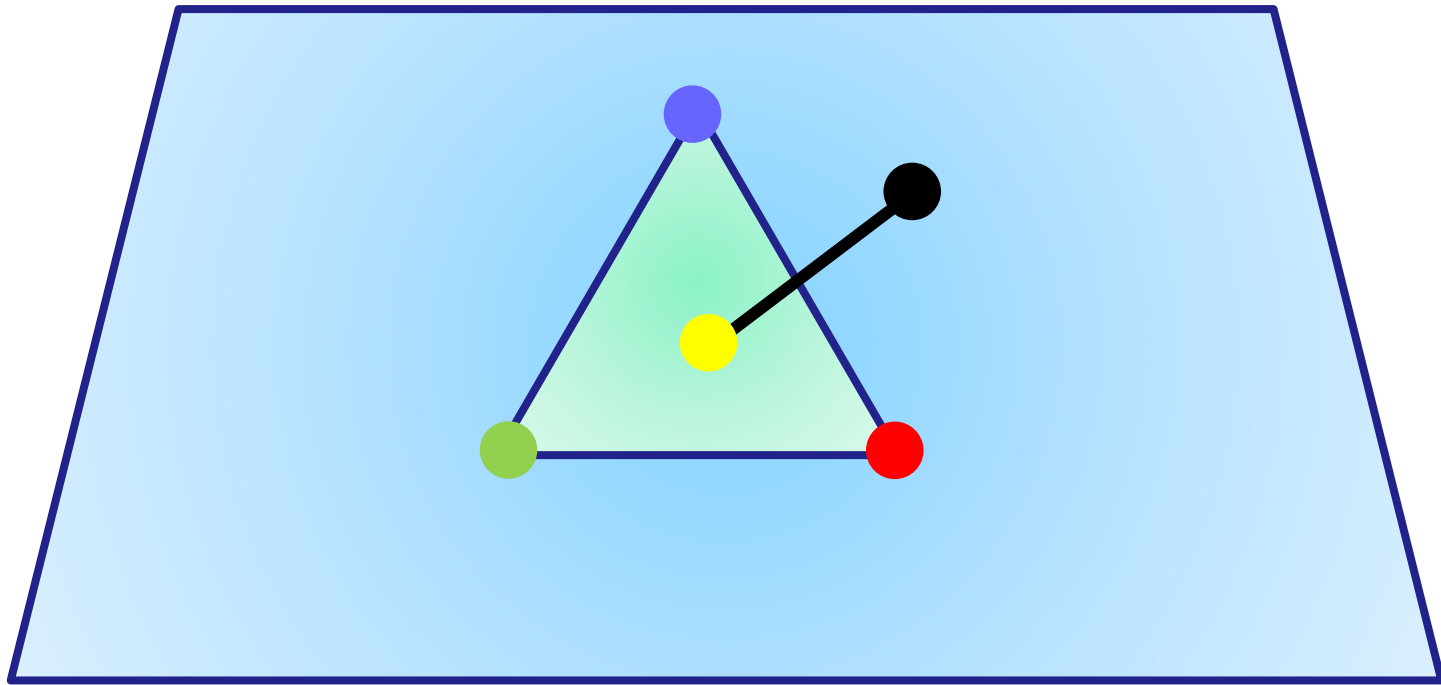
Open Cover Fail

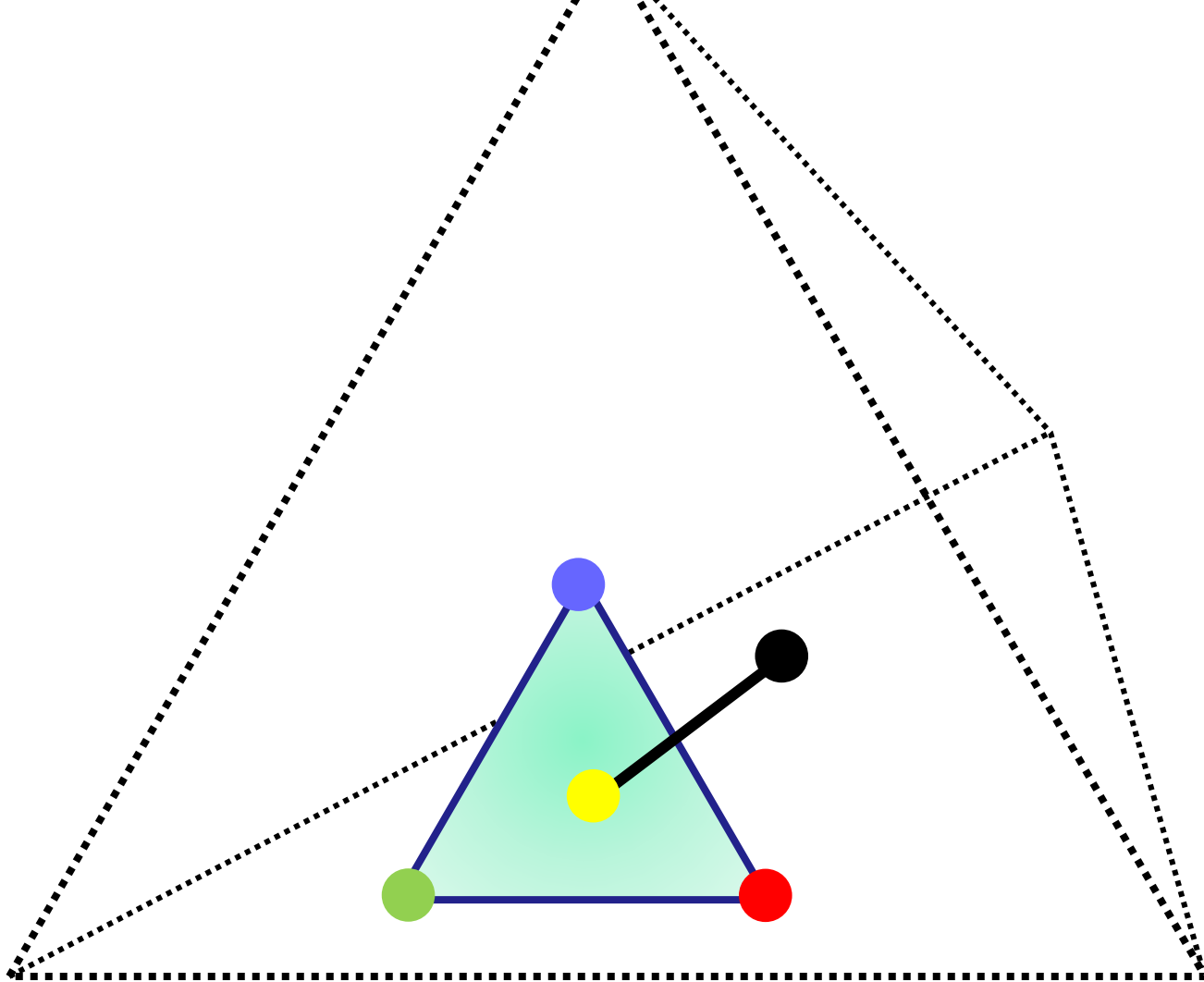


ρ has $q+1$ colors

τ has $p+1$ colors

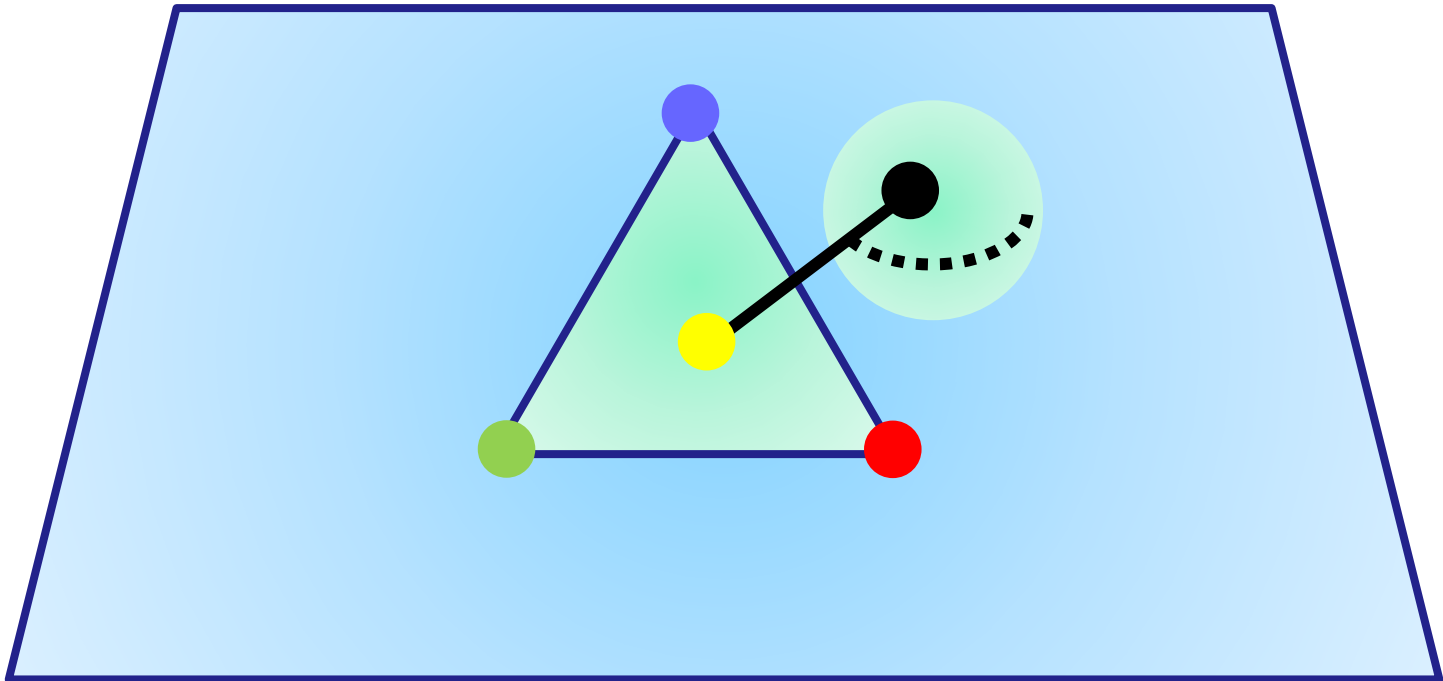
Simplexes lie in hyperplane
of dimension $p+q$
(because they overlap)



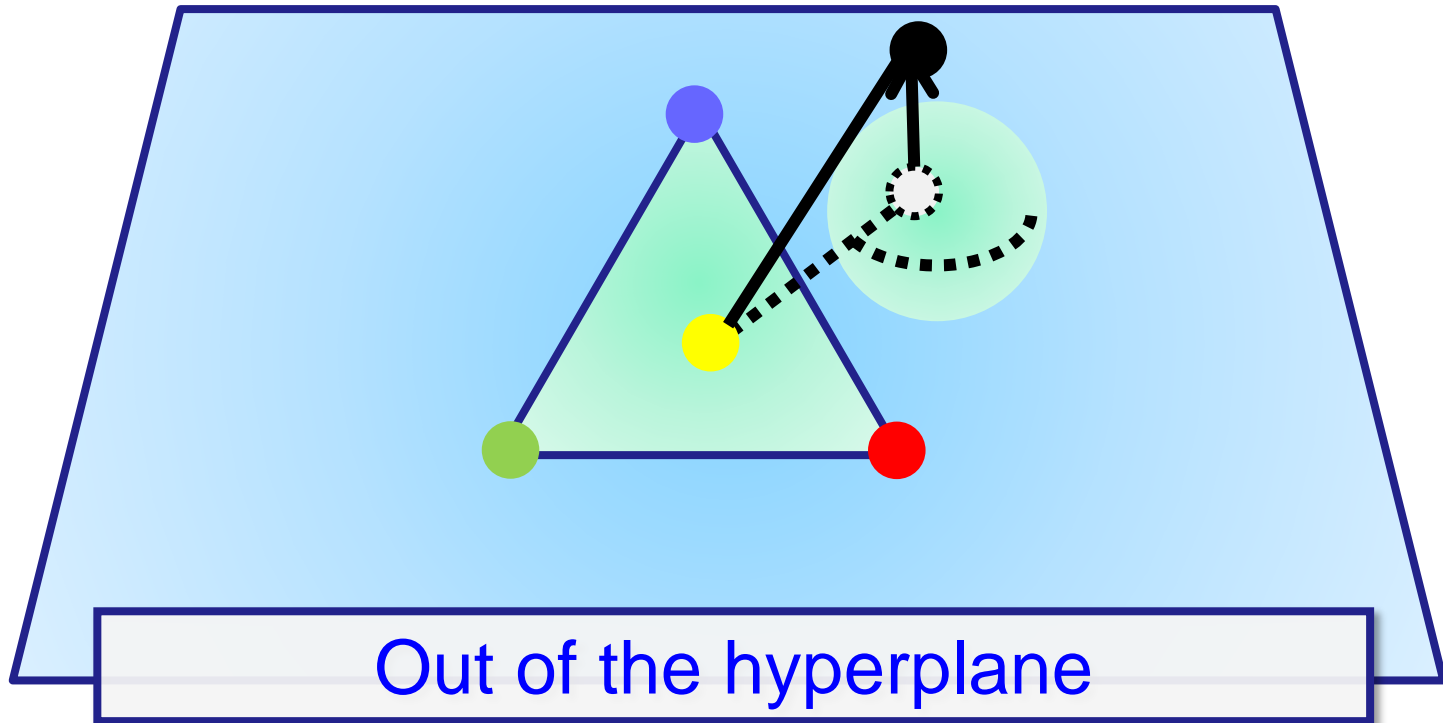


Some vertex has carrier of
dimension $p+q+1$
(because there are $p+q+2$ colors)

Can perturb vertex within $(p+q+1)$ -
dimension ϵ ball ...



Can perturb vertex within $(p+q+1)$ -
dimension ϵ ball ...



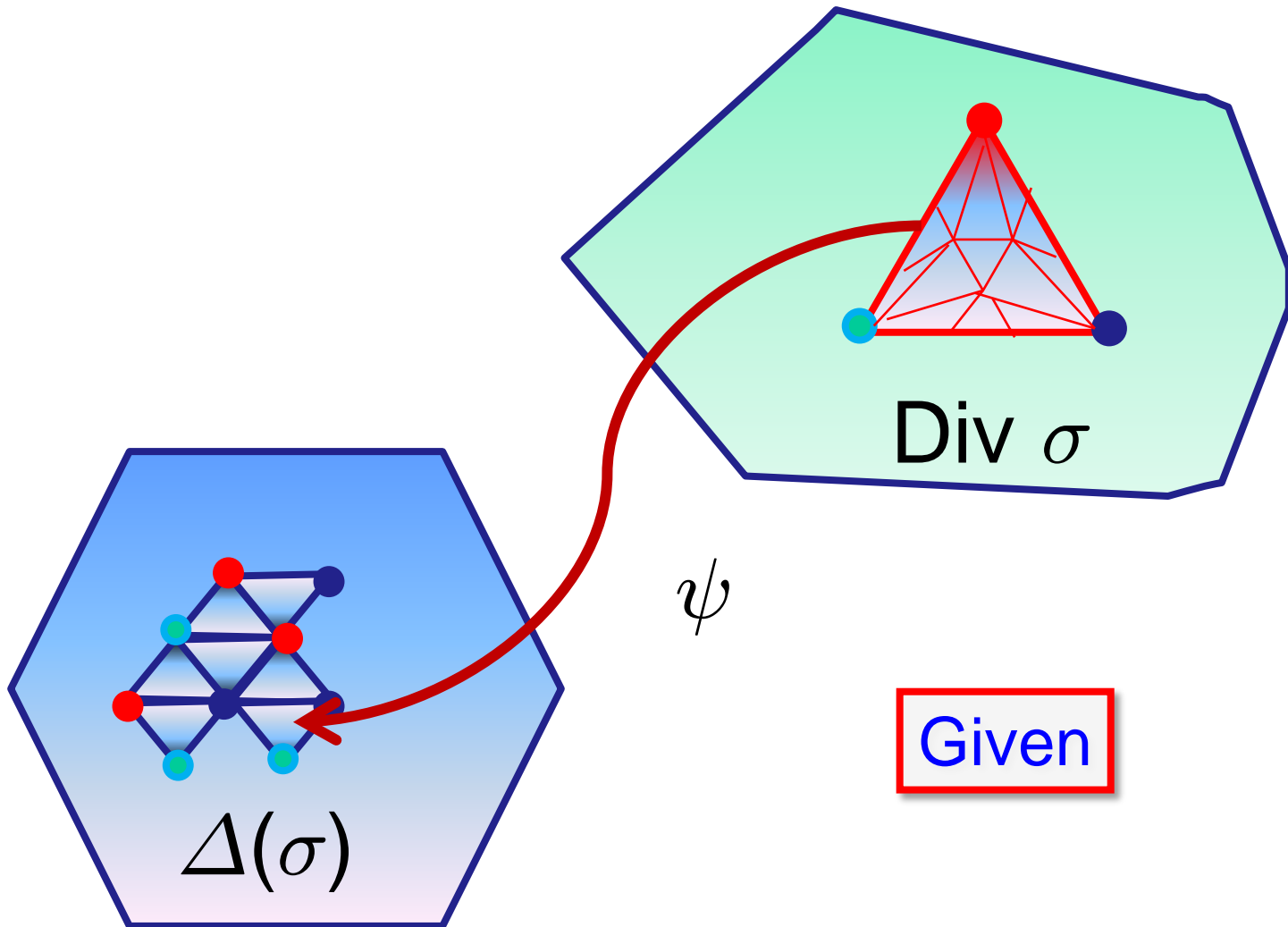
Repeat until star diameter $<$ Lebesgue number:

Construct $\text{Ch } \text{Ch}^{N-1}_* \sigma$

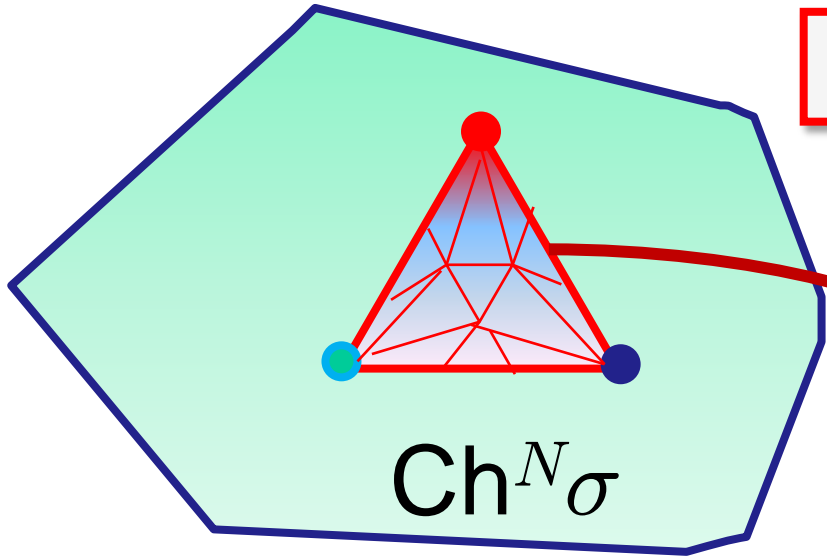
Perturb to $\text{Ch}^N_* \sigma$

So open-star cover is chromatic

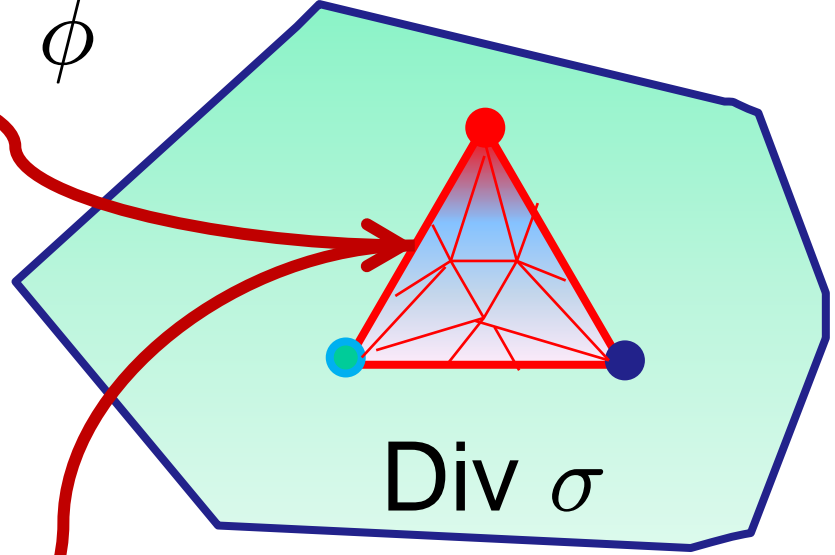
Construct color-preserving simplicial map



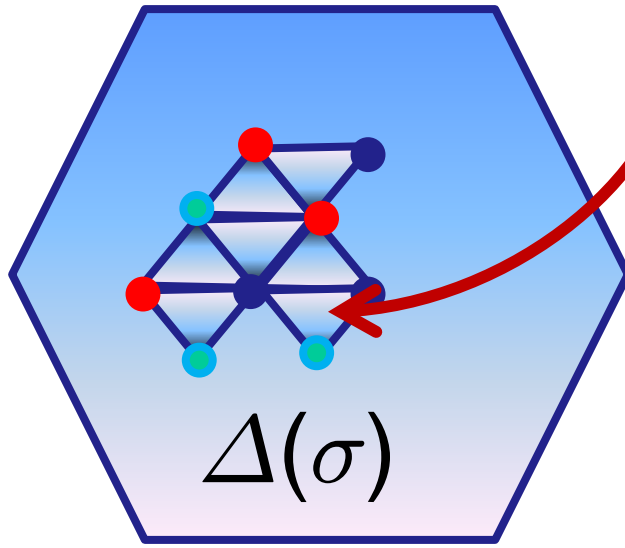
Constructed



ϕ

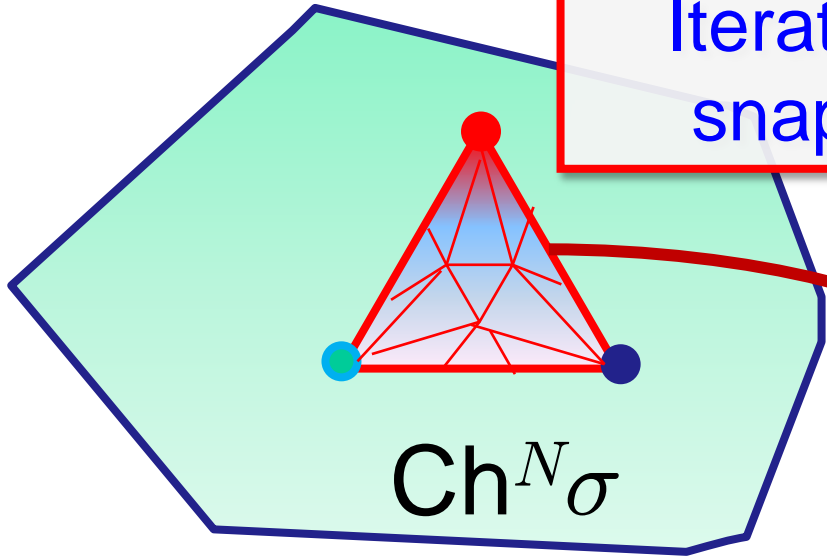


ψ

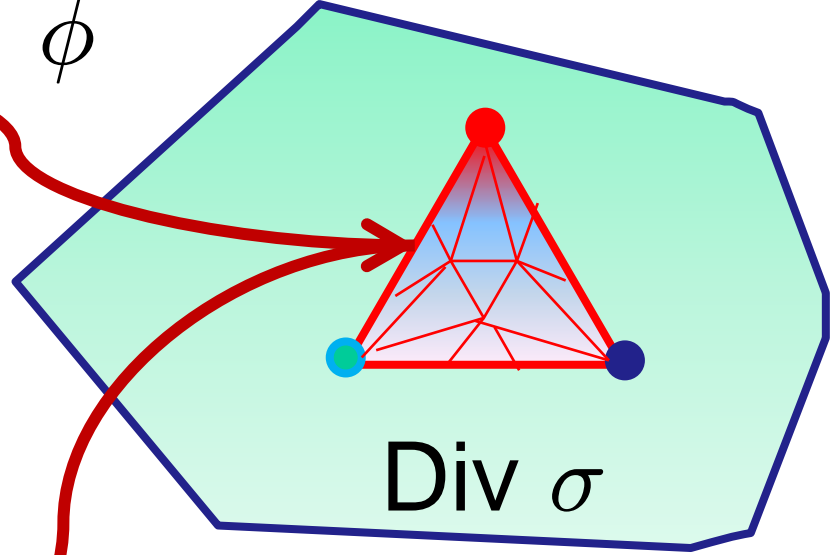


Given

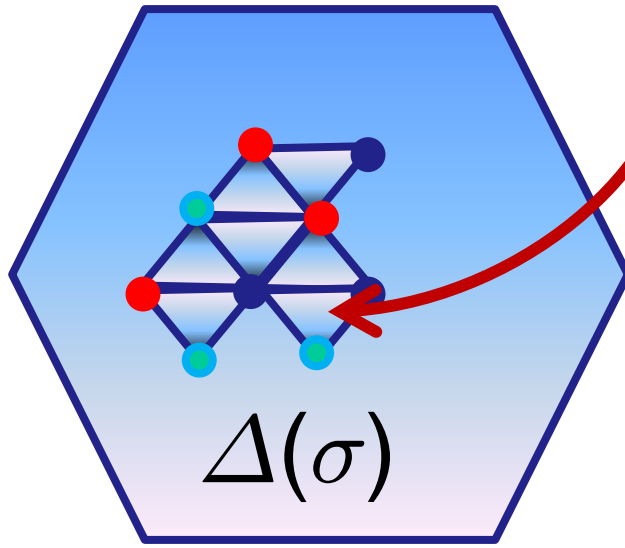
Iterated immediate
snapshot here ...



ϕ



ψ



Yields protocol here!

Road Map

Inherently colored tasks

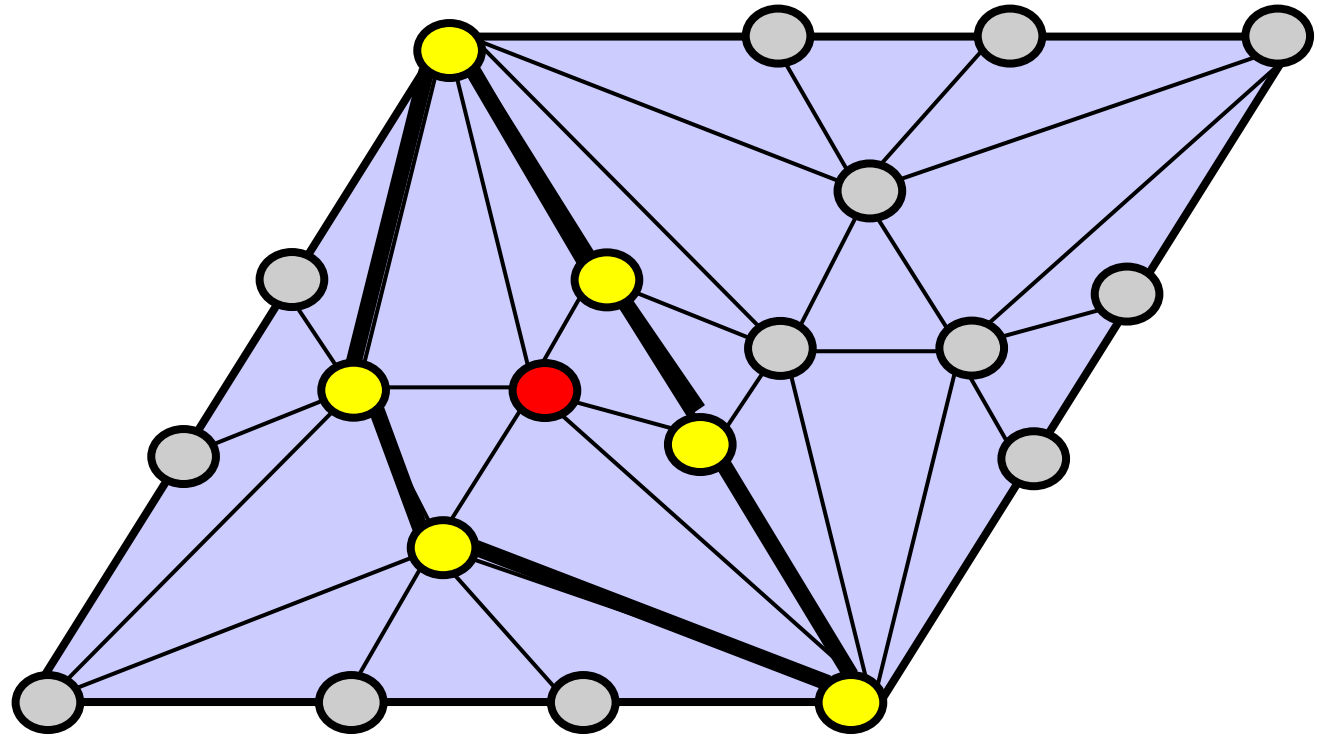
Solvability for colored tasks

Protocol \Rightarrow map

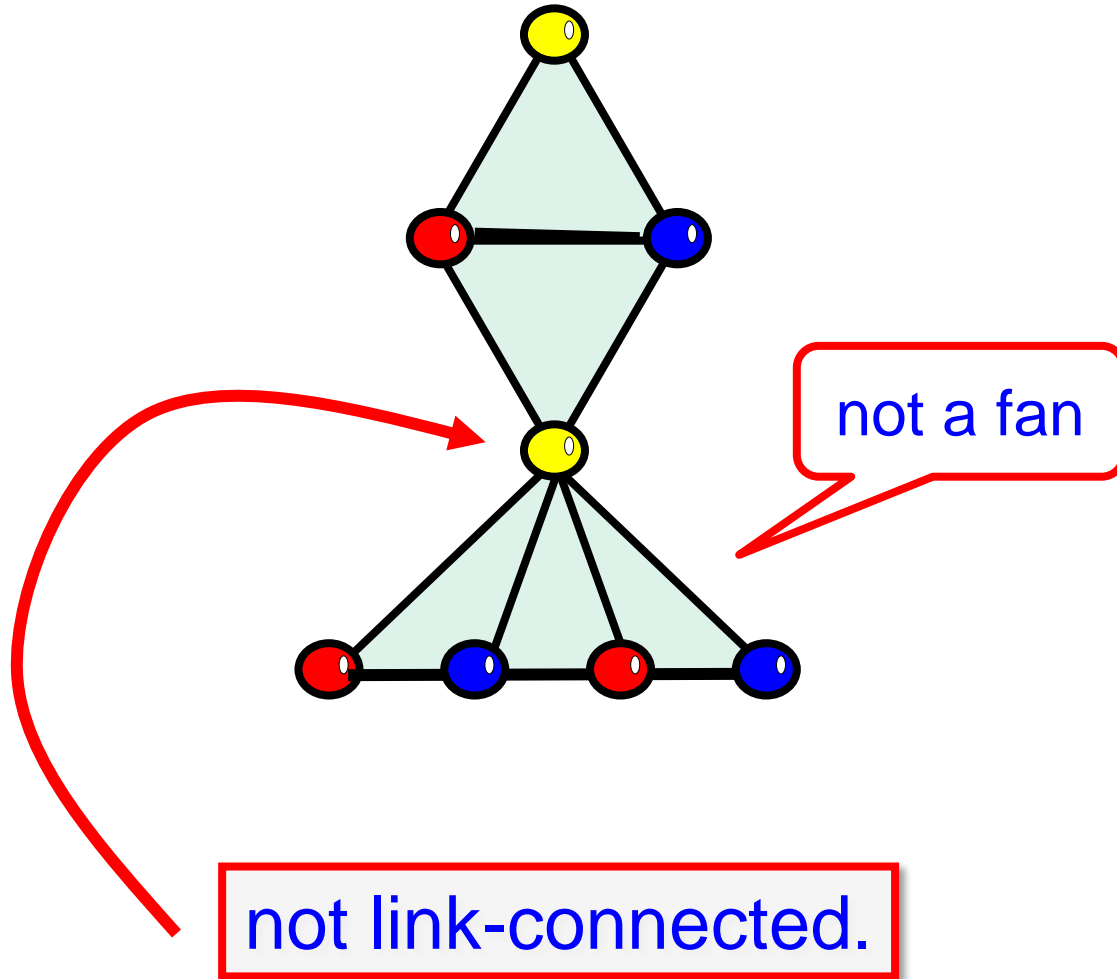
Map \Rightarrow protocol

A Sufficient Topological Condition

Link-Connected



\mathcal{O} is link-connected if for each $\tau \in \mathcal{O}$, $\text{link}(\tau, \mathcal{O})$ is $(n - 2 - \dim \tau)$ -connected.



Theorem

If, for all $\sigma \in \mathcal{I}$, $\Delta(\sigma)$ is

$((\dim \sigma)-1)$ -connected, and

\mathcal{O} is link-connected

then $(\mathcal{I}, \mathcal{O}, \Delta)$ has a wait-free IS protocol

Proof Strategy

If, for all $\sigma \in \mathcal{I}$, $\Delta(\sigma)$ is

$((\dim \sigma)-1)$ -connected, and

\mathcal{O} is link-connected,

there exists subdivision Div
& color-preserving simplicial map
 $\mu: \text{Div } \mathcal{I} \rightarrow \mathcal{O}$ carried by Δ .

Proof Strategy

If, for all $\sigma \in \mathcal{I}$, $\Delta(\sigma)$ is

$((\dim \sigma)-1)$ -colored, and

\mathcal{O} is link-connected

so protocol exists
by colored theorem

there exists subdivision Div
& color-preserving simplicial map
 $\mu: \text{Div } \mathcal{I} \rightarrow \mathcal{O}$ carried by Δ .

Lemma

rigid & color-preserving on boundary
means color-preserving everywhere

suppose we have a rigid simplicial map

$$\phi: \text{Div } \sigma \rightarrow \mathcal{O}$$

that is color-preserving on $\text{Div } \partial \sigma$

then ϕ is color-preserving on $\text{Div } \sigma$

Lemma

If \mathcal{O} is link-connected ...

can extend rigid simplicial map

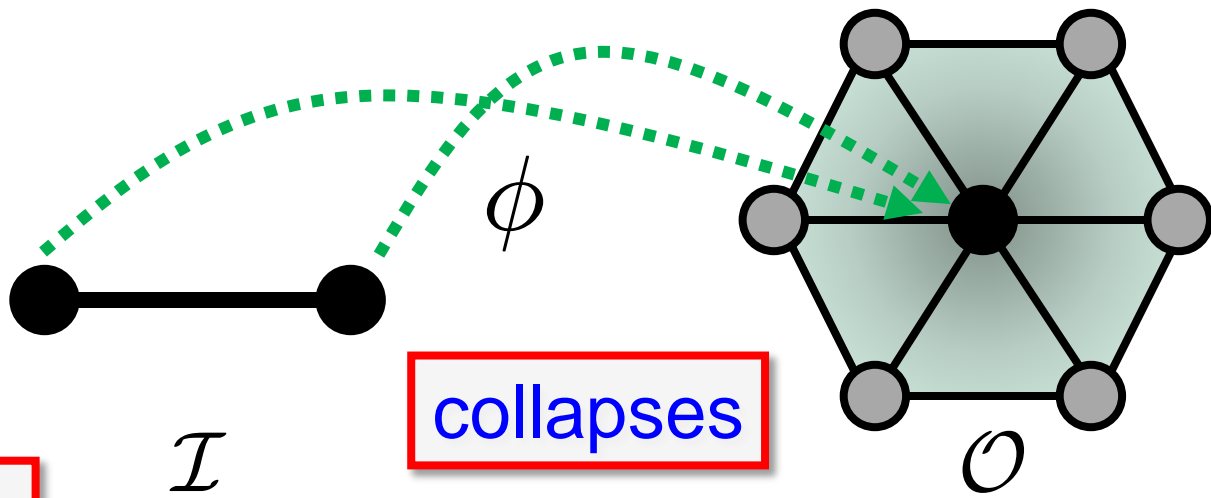
$$\phi_{n-1}: \text{skel}^{n-1} \mathcal{I} \rightarrow \mathcal{O}$$

to a rigid simplicial map

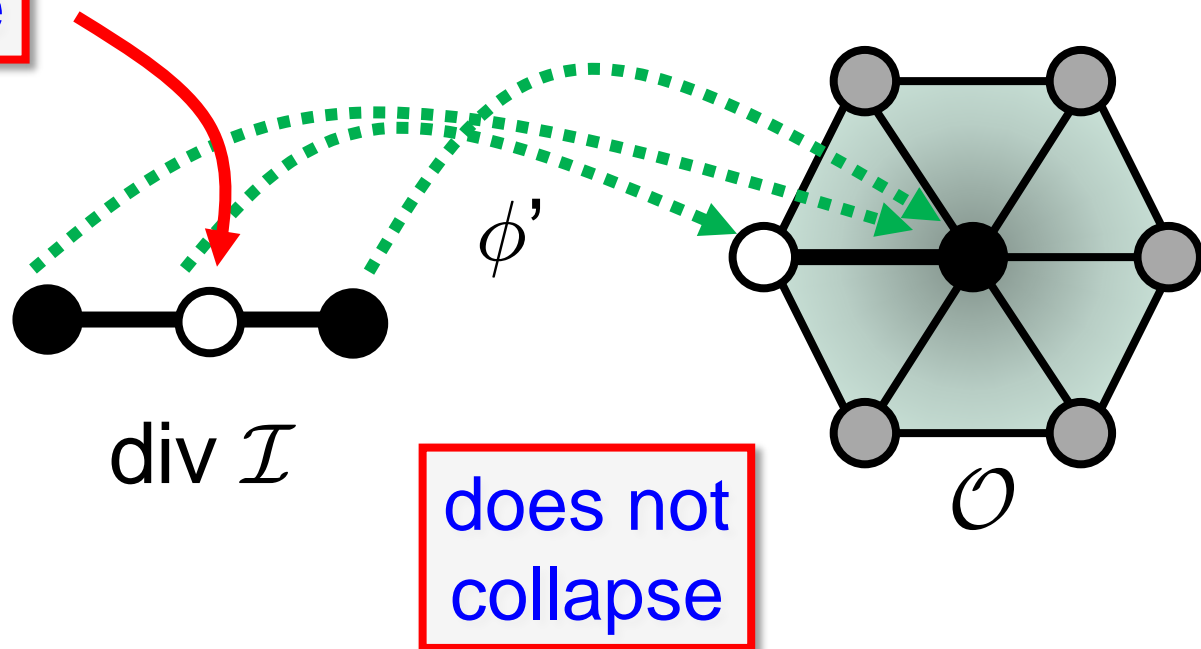
$$\phi_n: \text{Div } \mathcal{I} \rightarrow \mathcal{O}$$

where $\text{Div } \text{skel}^{n-1} \mathcal{I} = \text{skel}^{n-1} \mathcal{I}$

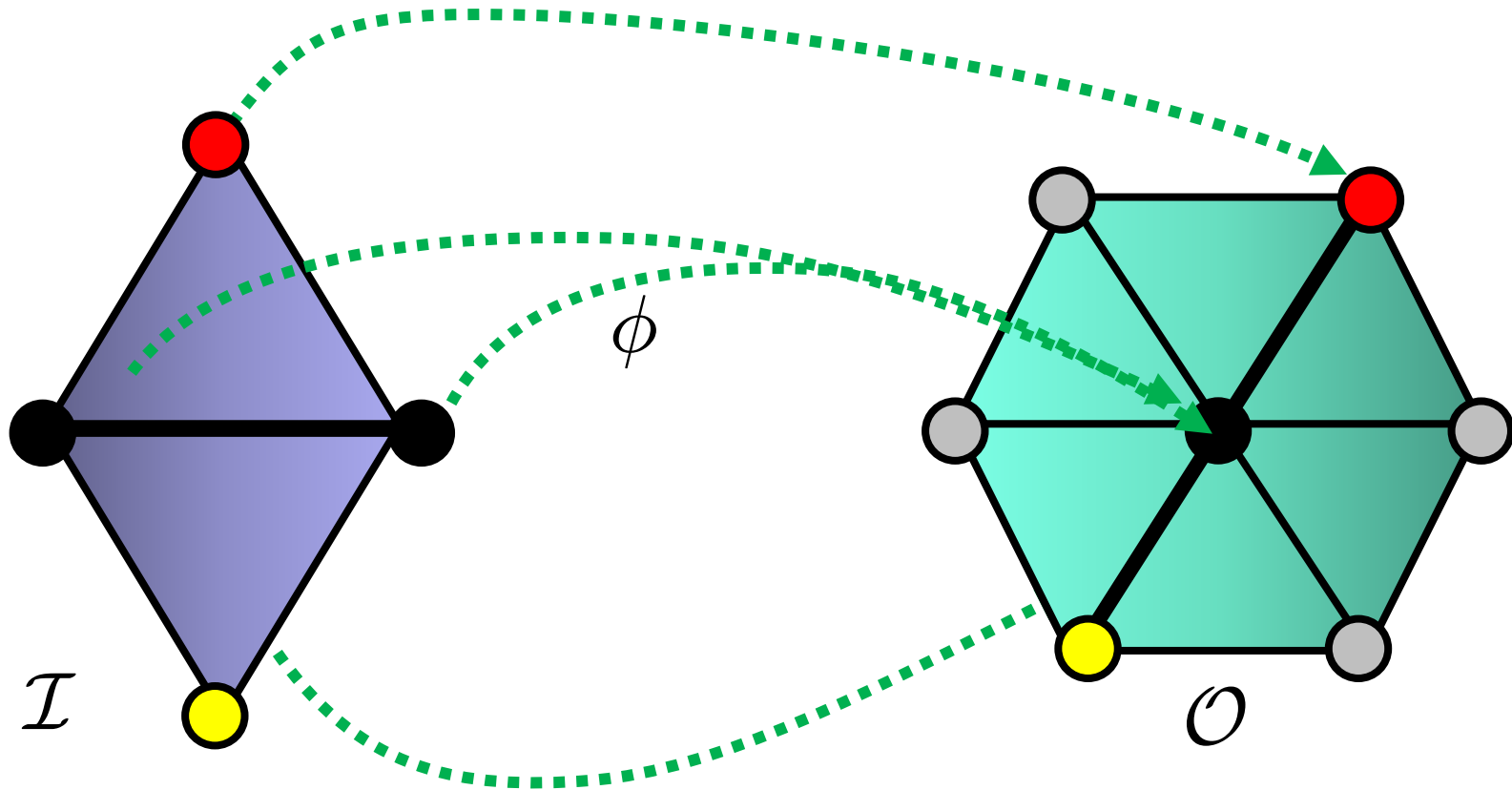
Induction Base: $n = 1$

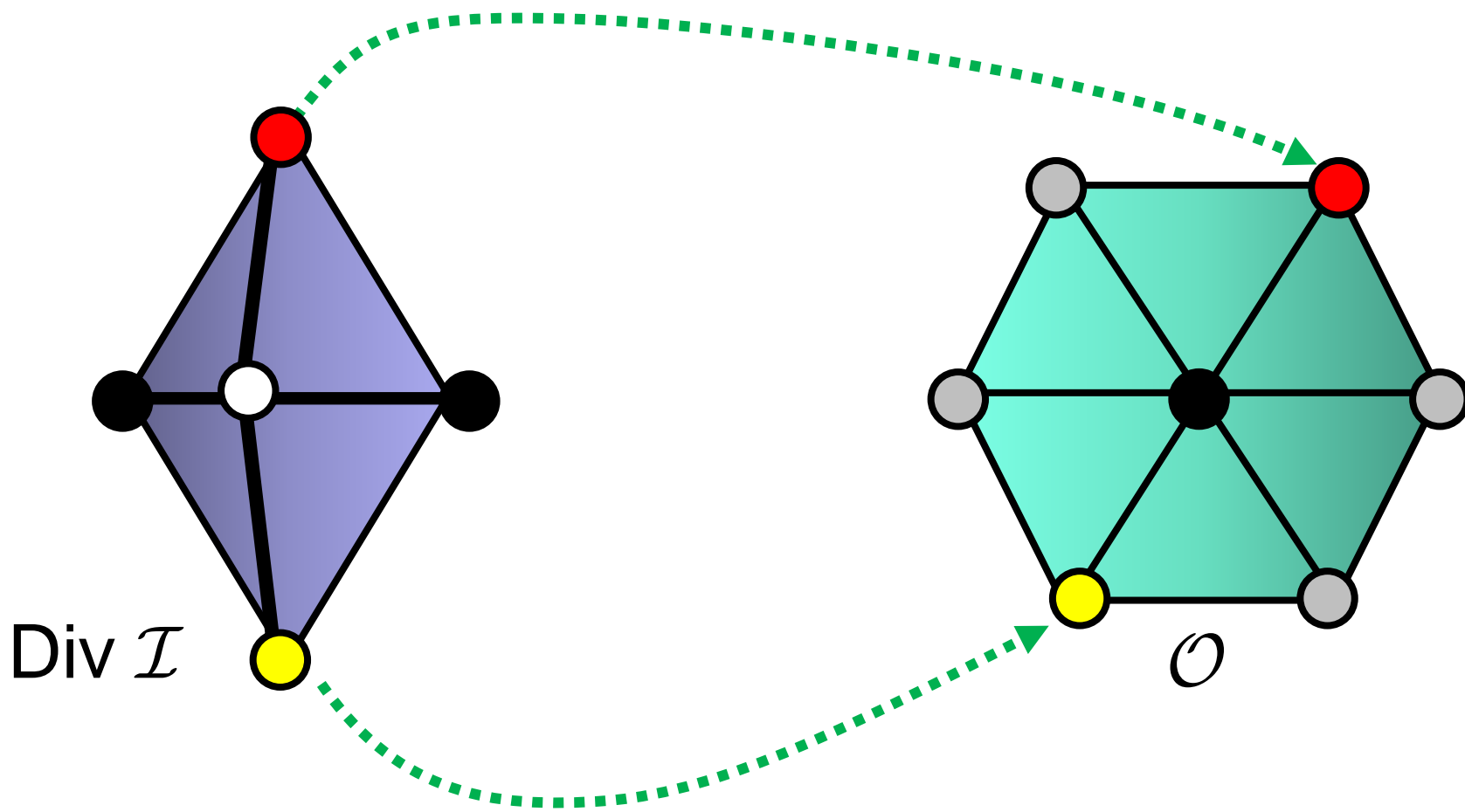


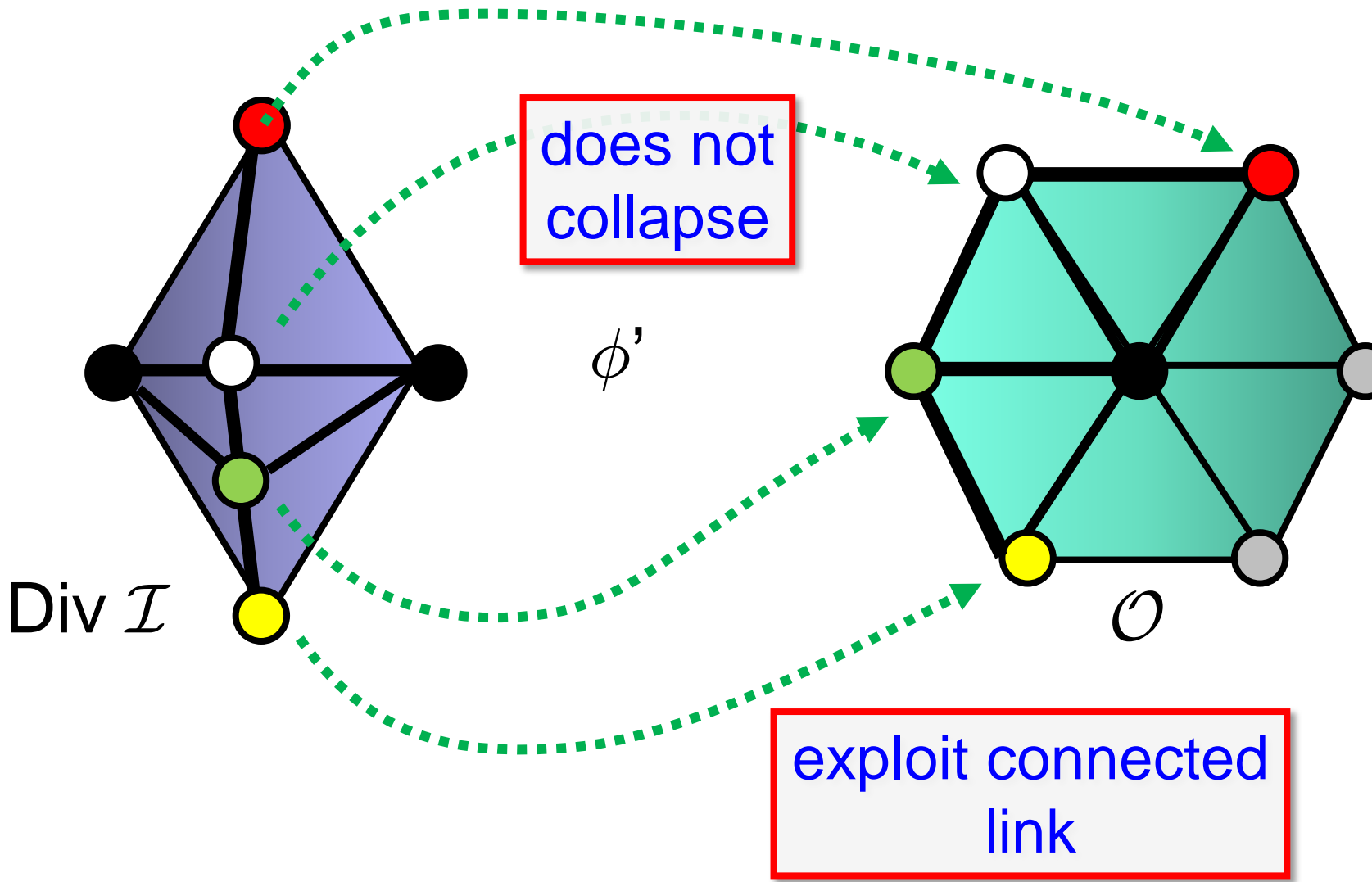
hinge



Induction Step: ϕ does not collapse $(n-1)$ -simplexes

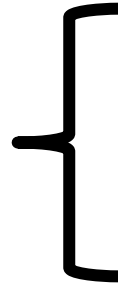






Summary

Inductively use ...



connectivity of $\Delta(\sigma)$

link-connectivity of \mathcal{O}

to construct a color-preserving simplicial map

$\phi: \text{Div } \mathcal{I} \rightarrow \mathcal{O}$ carried by Δ .

protocol follows from main theorem

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