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Building a Taxonomy of Attributes for Fine-Grained Scene Understanding

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Abstract

This paper presents the first effort to discover and exploit a diverse taxonomy of scene attributes. Starting with the fine-grained SUN database, we perform crowd-sourced human studies to find over 100 attributes that discriminate between scene categories. We construct an attribute-labeled dataset on top of the SUN database [7]. This "SUN Attribute database" spans more than 700 categories and 14,000 images and has potential for use in high-level scene understanding, attribute-based hierarchy construction, and fine-grained scene recognition.

1. Introduction

High-level scene understanding is a fundamental challenge in computer vision. Traditionally, computer vision algorithms have explained visual phenomena (objects, faces, actions, scenes, etc.) by giving each instance a categorical label. For scenes, this model has two significant problems: the space of scenes cannot be described by a well-defined taxonomy of non-overlapping categories, and simple category recognition does not provide any deep understanding or information about interesting inter-category and intracategory variations.

034 In the past two years there has been significant inter-035 est in attribute-based representations of visual phenomena 036 [3, 1].In the domain of scenes, an attribute-based algo-037 rithm might describe an image with 'tiled floor', 'crowded', 'shopping', and 'shiny' in contrast to a categorical label 038 039 such as 'store'. Attributes could be considered as an al-040 ternative to categorical descriptions of scenes, or they could 041 be used to reinforce fine-grained classification techniques.

Scenes are difficult to model because instances in the 042 043 same category have an incredible variety of layout, illumination, contents, occurrence, etc. Unlike with objects, 044 people, or faces it is difficult to identify discriminative at-045 tributes, and it is more difficult to reliably isolate the same 046 047 attributes in many instances of a scene. For example, eves 048 are a salient feature of a face, but what are the salient features of a mall? Can those mall features be identified for all 049 malls? 050

It is also true that many scenes don't have a clear membership in any category, and many scenes seem to qualify
for membership in several categories simultaneously. Ide-

ally the boundary between attribute states is clearer. Even if a given scene does have a few ambiguous attributes, those that are not will still facilitate scene understanding. For this reason, one might expect attribute-based representations to fail more gracefully than strict categorical taxonomies.

2. Building a Taxonomy of Scene Attributes from Human Descriptions

The results of [5, 4] indicate that global scene attributes as well as local attributes are probably necessary for creating a discriminative set of scene attributes. For this initial endeavor into identifying scene attributes we limit ourselves to *global, binary* attributes. Still, the space of such attributes is effectively infinite. The vast majority of attributes (e.g., "Was these photo taken on a Tuesday", "Does this scene contain air?") are neither interesting nor discriminative among scene types. To determine relevant scene attributes, we conducted experiments with human users of Amazon's Mechanical Turk (AMT) service.

We will discover attributes by having humans describe and compare scenes. To ensure a maximally diverse set of probe scenes, we use the most prototypical image of each scene category in the SUN database as found by Ehinger et al. [2]. These 707 prototype images were the basis for our human experiments. In our first experiments we asked participants to list attributes for various individual prototypical scenes. From the thousands of responses, we were able to determine the most common categories of attributes. Below is a list of the attribute categories we identified in this experiment, along with a brief description of each.

- **Materials**: the material components, surface properties, or lighting found in a scene.
- Functions or affordances: activities that typically occur in a scene or that a scene may make possible, e.g. playing baseball in on a baseball field or thinking in a library.
- **Spatial envelope attributes**: these address global characteristics of a scene, for example the symmetry of a scene or a scene's degree of enclosure.
- **Objects**: the items commonly found in a particular scene.

Within these broad categories we want to focus on *discriminative* attributes - those that differentiate scene categories. Inspired by the "splitting task" of [5], we show participants two sets of scenes and ask them to list attributes that are present in one set but not the other. The images

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108 that make up these sets are prototypes from distinct, ran-109 dom categories. In the simplest case, with only one scene in 110 each set, we found that participants would focus on trivial, 111 happenstance objects or attributes. Such attributes would 112 not be broadly useful for describing other scenes. At the 113 other extreme, with many category prototypes in each set, 114 it is rare that any attribute would be shared by one set and 115 absent from the other. We found that having two scenes in 116 each set produced a diverse but broadly applicable set of 117 scene attributes. Figure 1 shows an example interface. 118



Figure 1. Mechanical Turk Human Intelligence Task - workers are asked to compare the images on the left to those on the right. Workers must attribute tags for left or right images into the text boxes at the bottom of the page.

The attribute gathering task was repeated more than 6000 times. From the thousands of raw discriminative attributes reported by participants, we collapse nearly synonymous attributes (e.g. dirt and soil) and then create our final taxonomy from the most frequently reported attributes. Some common emotional attributes (e.g. happy) were not used in order to focus our initial experiments on attributes that have a strong visual presence in scenes. The final list of attributes can be seen on the supplemental poster.

2.1. Labeling the Dataset

152 Now that we have a taxonomy of attributes we wish to create a large database of attribute-labeled scenes. In or-153 der to study the interplay of attribute and category-based 154 155 representations, we build the "SUN Attribute database" on 156 top of the fine-grained SUN categorical database. Building an attribute dataset on top of an existing fine-grained image 157 dataset was successfully demonstrated by Russakovsky and 158 Fei-Fei in [6] for the object domain. 159

We use Mechanical Turk to annotate 20 images from717 scene categories. Participants are shown 20 scenes and

asked to mark all the scenes that contained a specified attribute. The images are randomized to encourage the participants to examine each scene individually. Figure 2 shows an example interface.

Select Images Where This Activity Could Happen

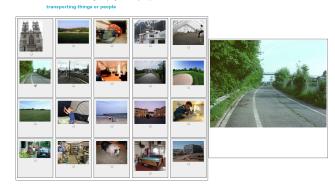


Figure 2. Attribute Labeling Interface for MTurk - workers are instructed to click on any of the 20 thumbnail-sized images that contain the given attribute (displayed in blue at the top of the page). Workers are able to mouse over a thumbnail and see the full-sized image in the review window on the right.

3. Future Work

The human experiments described in this paper are the first forays into a deep and interesting new domain. It remains to be seen how well attributes can be recognized and how useful such attributes will be for fine-grained categorization. One unexplored question is whether a principled hierarchy of the scene categories could be constructed by clustering based on attributes. Would the resulting categories resemble the lexicographical taxonomy used in the SUN database? It would also be interesting to see if attribute-based representations of scenes help explain human behaviors in studies of scene perception.

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